



# Point cloud processing for geometric and semantic interpretation



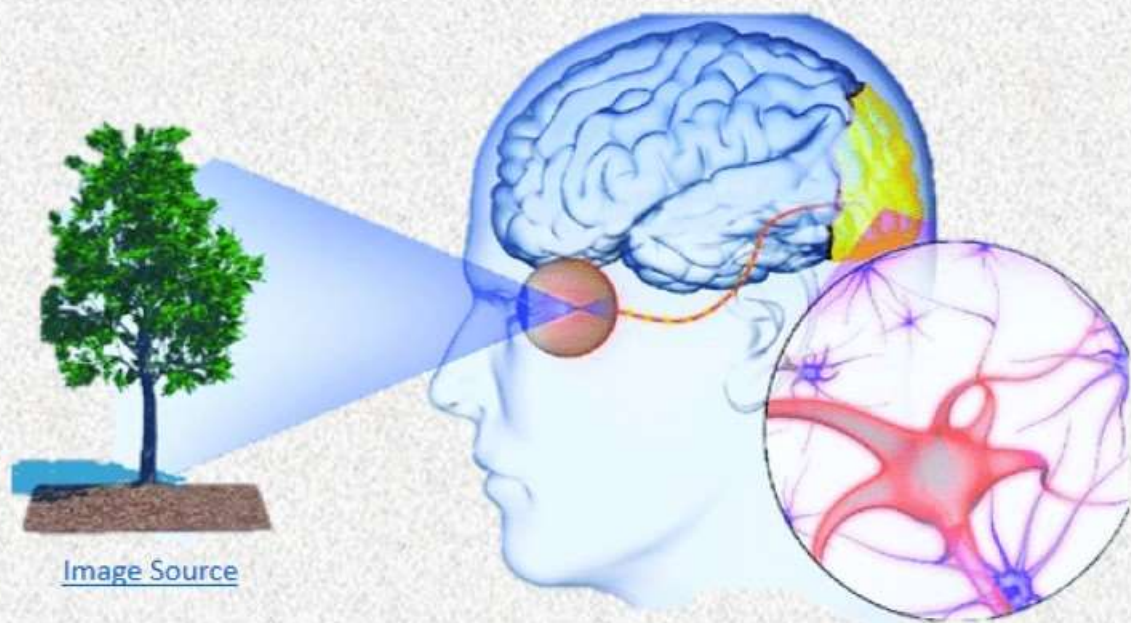
Florent Poux

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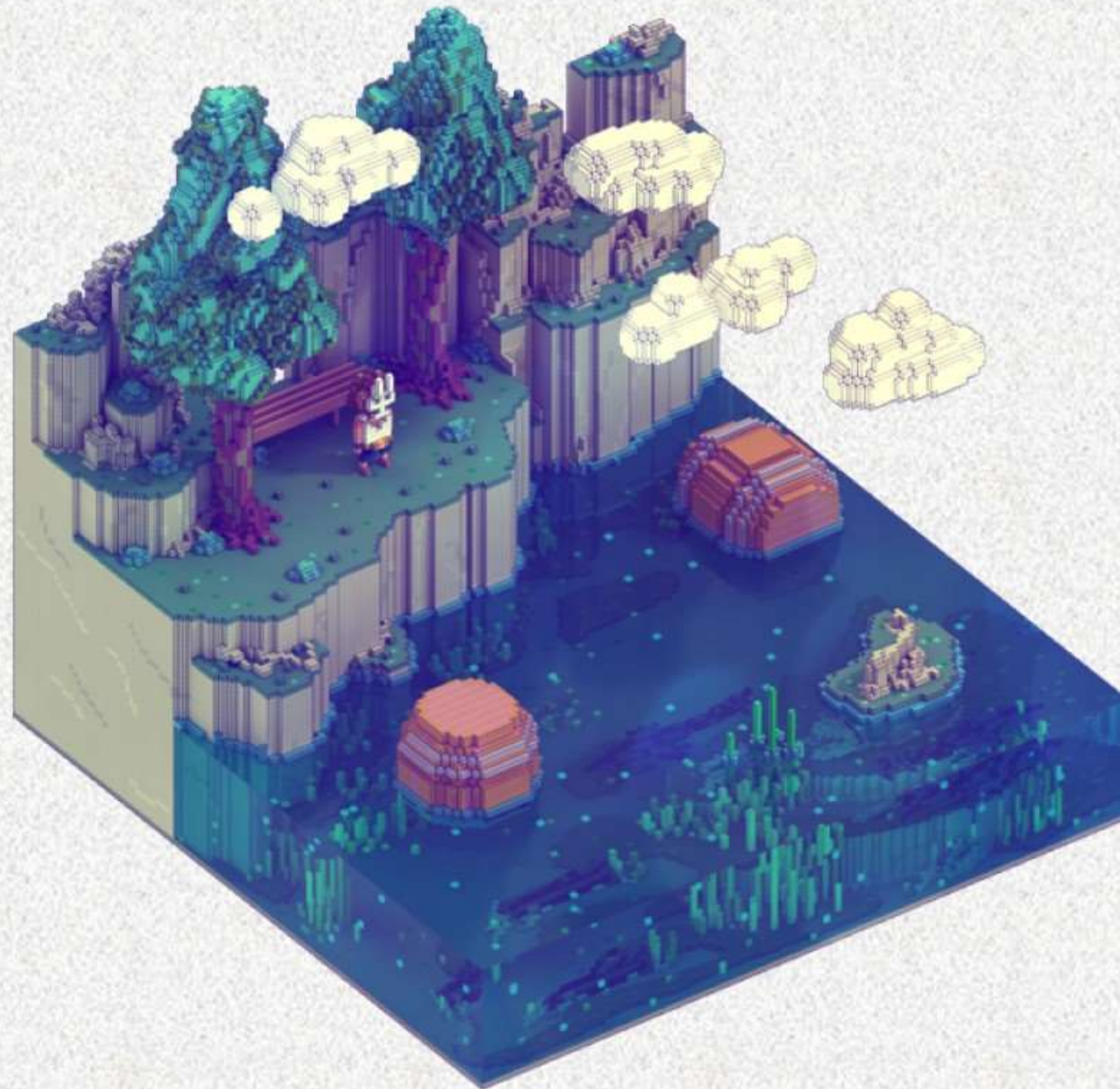
*Arts. L335-2 to L335-4*

## Visual perception



“ when we open **our eyes** on a **familiar scene**, we form an immediate **impression of recognizable objects**, organized coherently in a **spatial framework** “ (Treisman, 1980)





## Human Perception?



“ when we open **our eyes** on a **familiar scene**, we form an immediate **impression of recognizable objects**, organized coherently in a **spatial framework** ” (Treisman, 1980)

**A sensor** captures a **scene**, and the computer will make sense out of the gathered data through available **knowledge** and output a **semantic representation**.

**1. Can we mimic our perception system powers? (geometry, semantics & interpretation)**

1. The high-level workflow
2. Point cloud processing automation
3. The Smart Point Cloud
4. Interpretation for decision-making

**2. Can we play on multi-layered perception and representation?**

1. Reality Capture methods for geometric consistency
2. 3D Geometric representation
3. Semantic representation
4. Level of Detail and Semantics
5. The viewpoint case

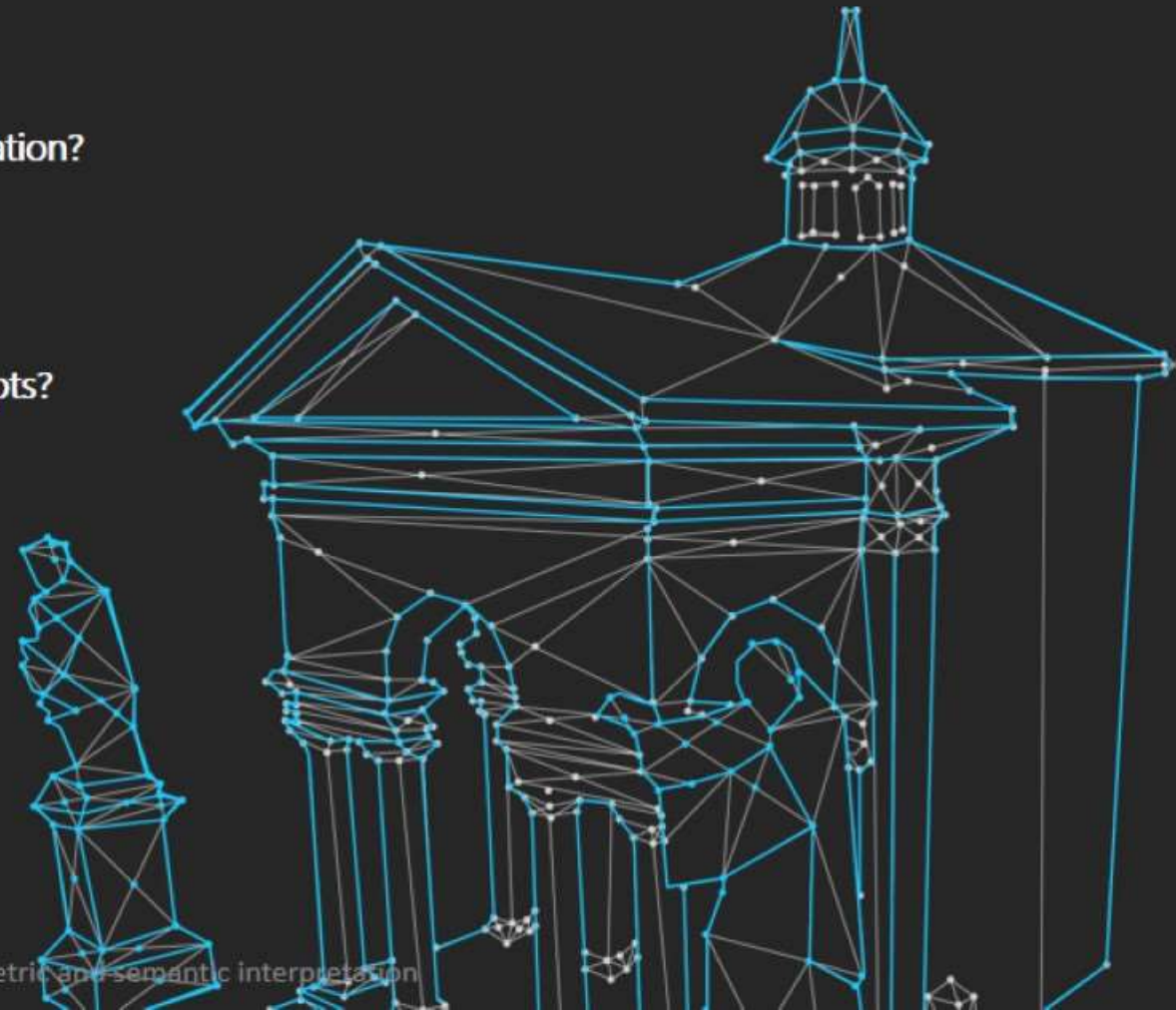
**3. Can we address widely different applications and concepts?**

1. Method adaptation to the needs
2. ANI vs AGI vs ASI
3. Detection, Classification and Segmentation
4. Semantic augmentation methods
5. 3D Geometric representation
6. Semantic augmentation

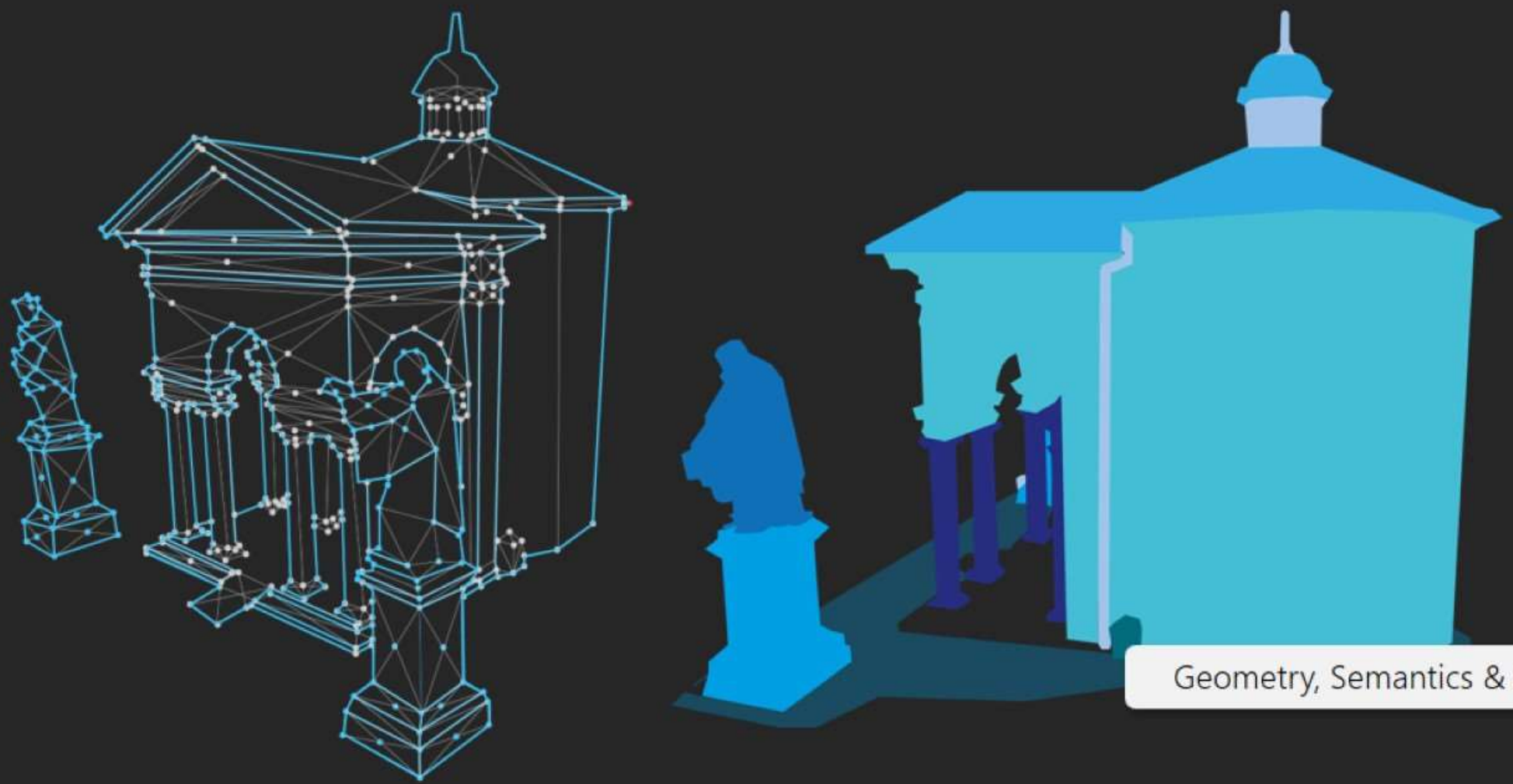
**4. A word on generalization?**

**5. Identified Perspectives**

**6. Conclusion**



# 1. A parallel to our perceptual system for Decision-Making?



Geometry, Semantics & Interpretation

# Workflow



Real world

Digitization

Low-level digital model

Transformation (additional info from domain or app.)

High-level digital model

Usage Interpretation



# Automation



Acquisition

Pre-processing

Registration

Segmentation

Classification

Structuration

Application



Image source VR Modeler: From image sequences to 3D models

Acquisition

Pre-processing

Registration

Segmentation

Classification

Structuration

Application

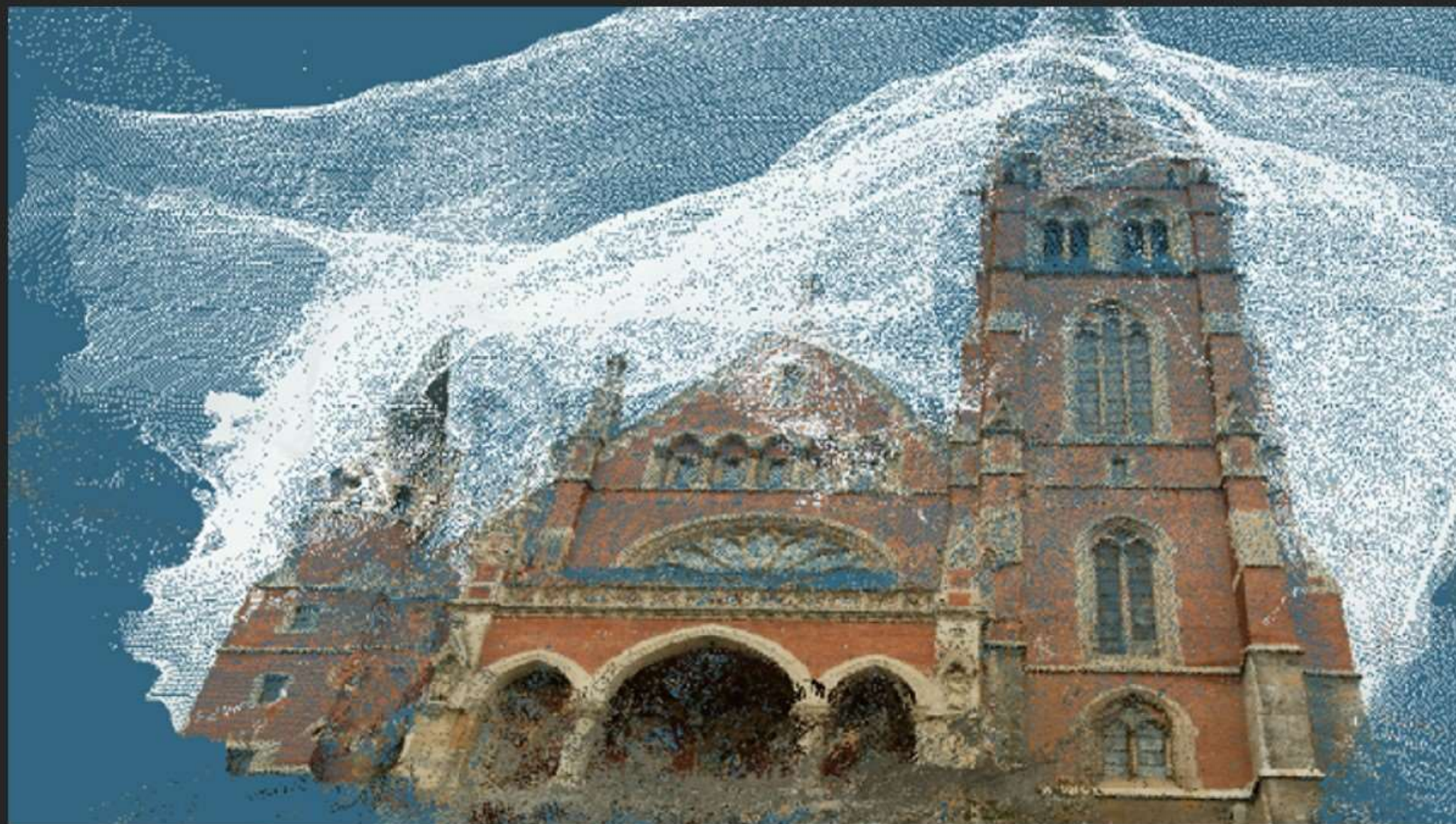


Image sourceVR Modeler: From image sequences to 3D models

- Acquisition
- Pre-processing
- Registration
- Segmentation
- Classification
- Structuration
- Application

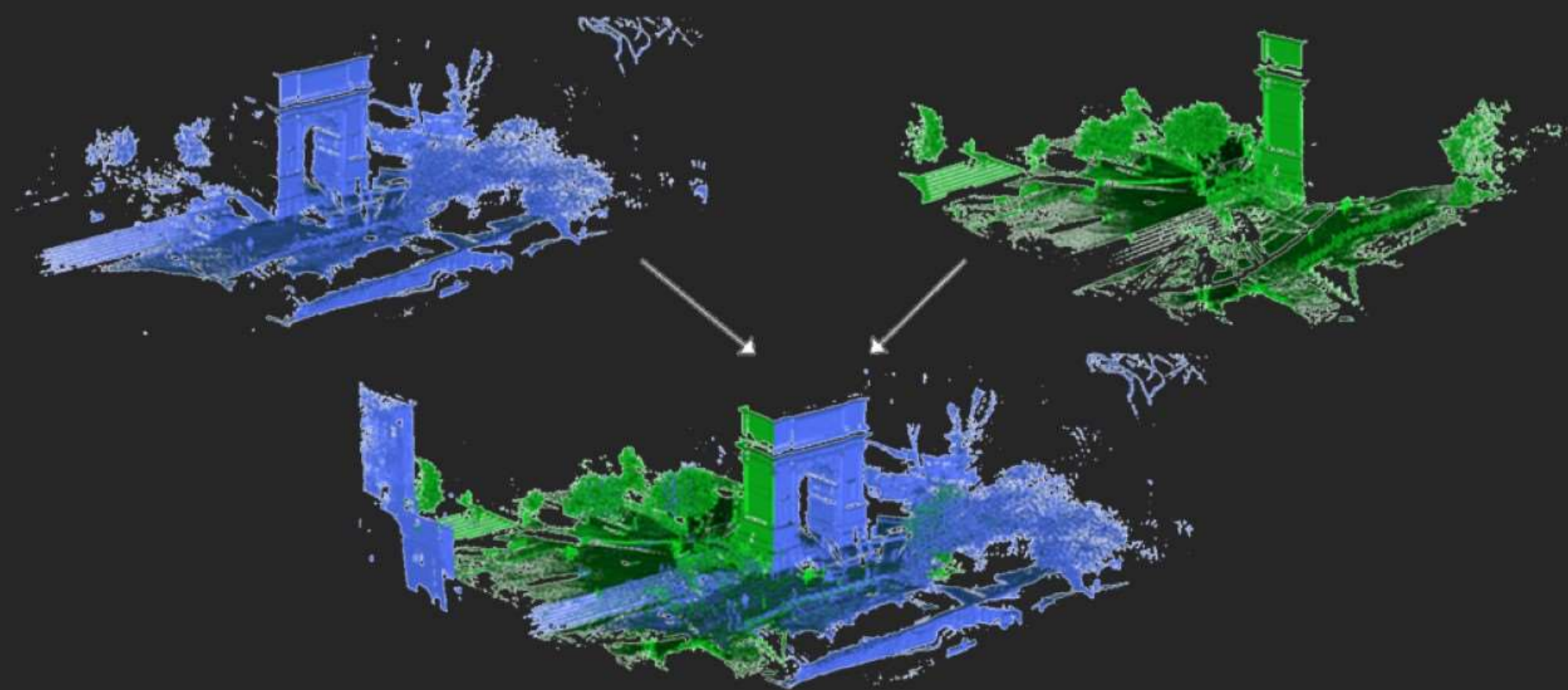


Image source: ETH Zürich

Acquisition

Pre-processing

Registration

Segmentation

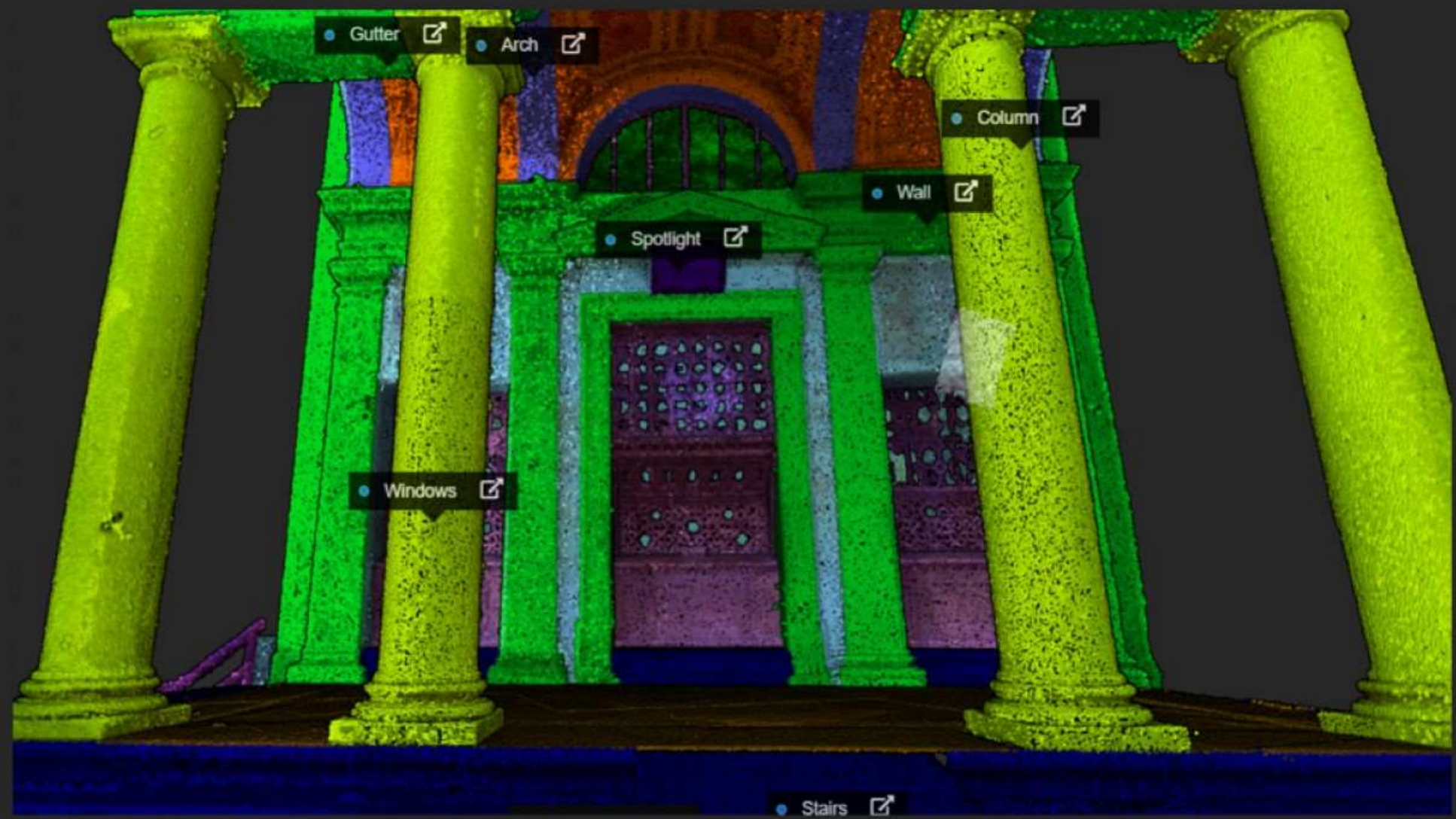
Classification

Structuration

Application



- Acquisition
- Pre-processing
- Registration
- Segmentation
- Classification**
- Structuration
- Application



Acquisition

Pre-processing

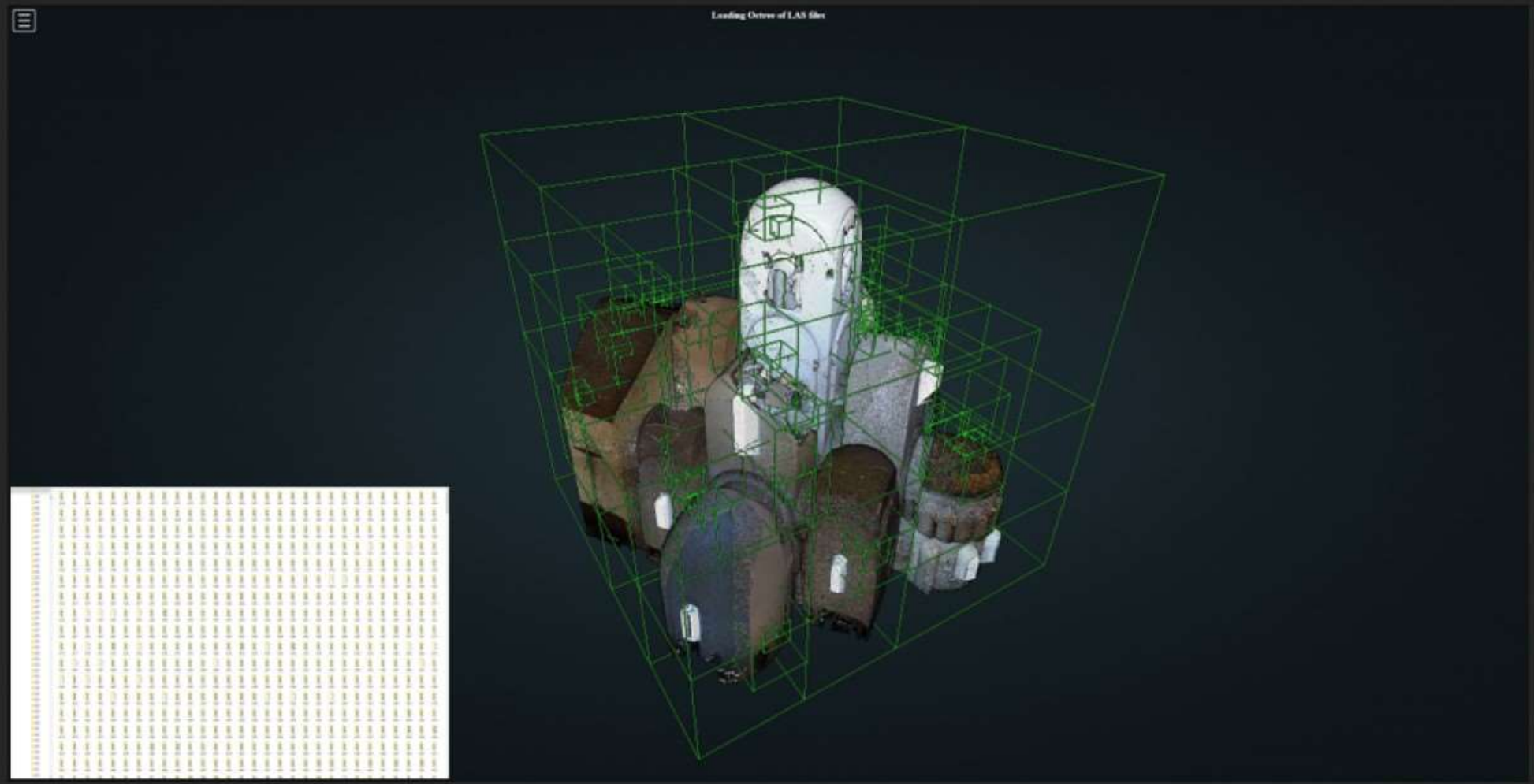
Registration

Segmentation

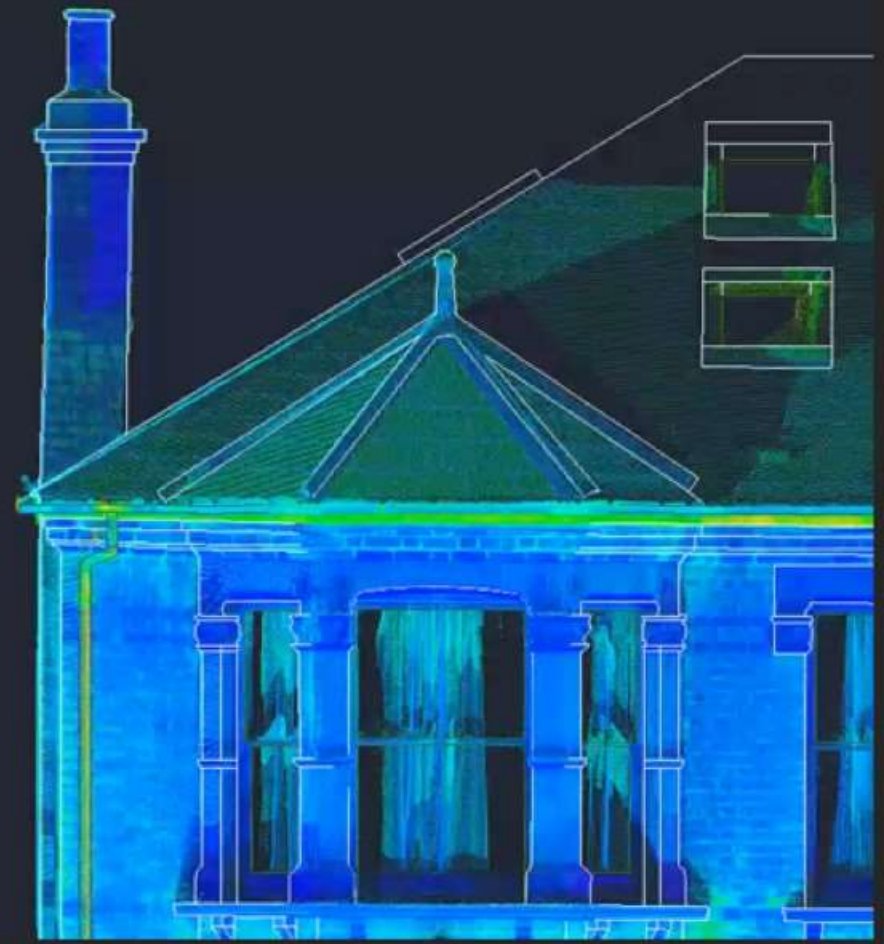
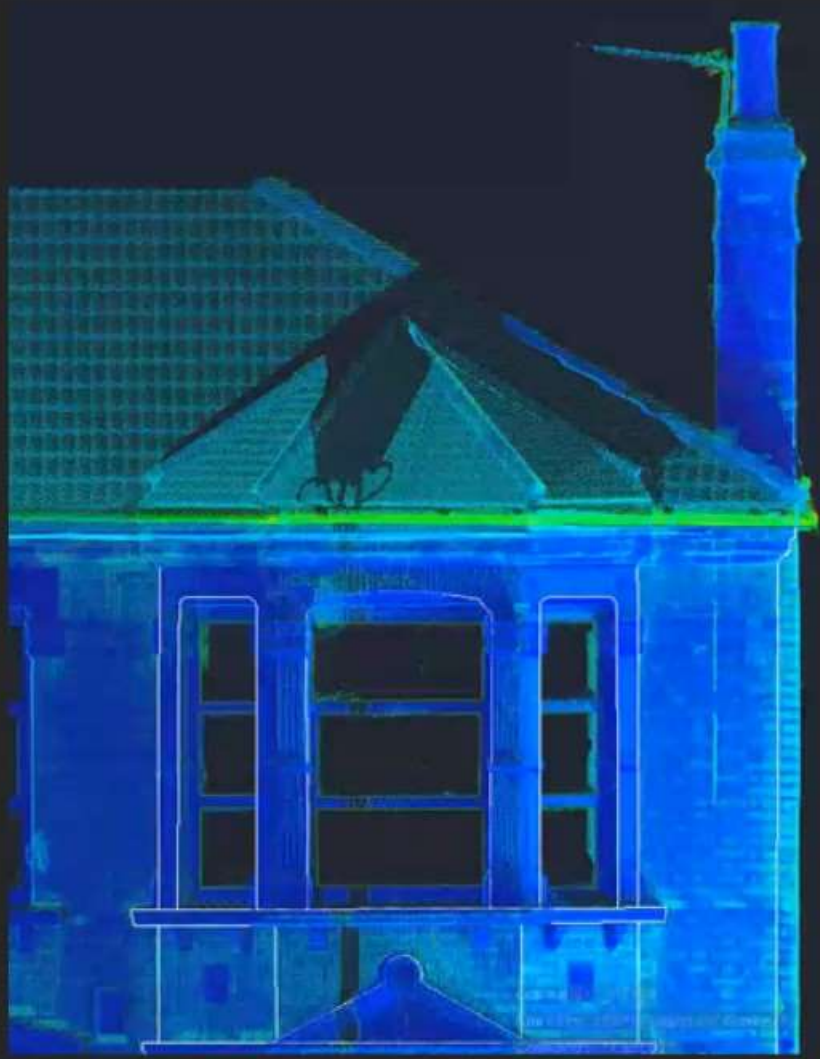
Classification

Structuration

Application

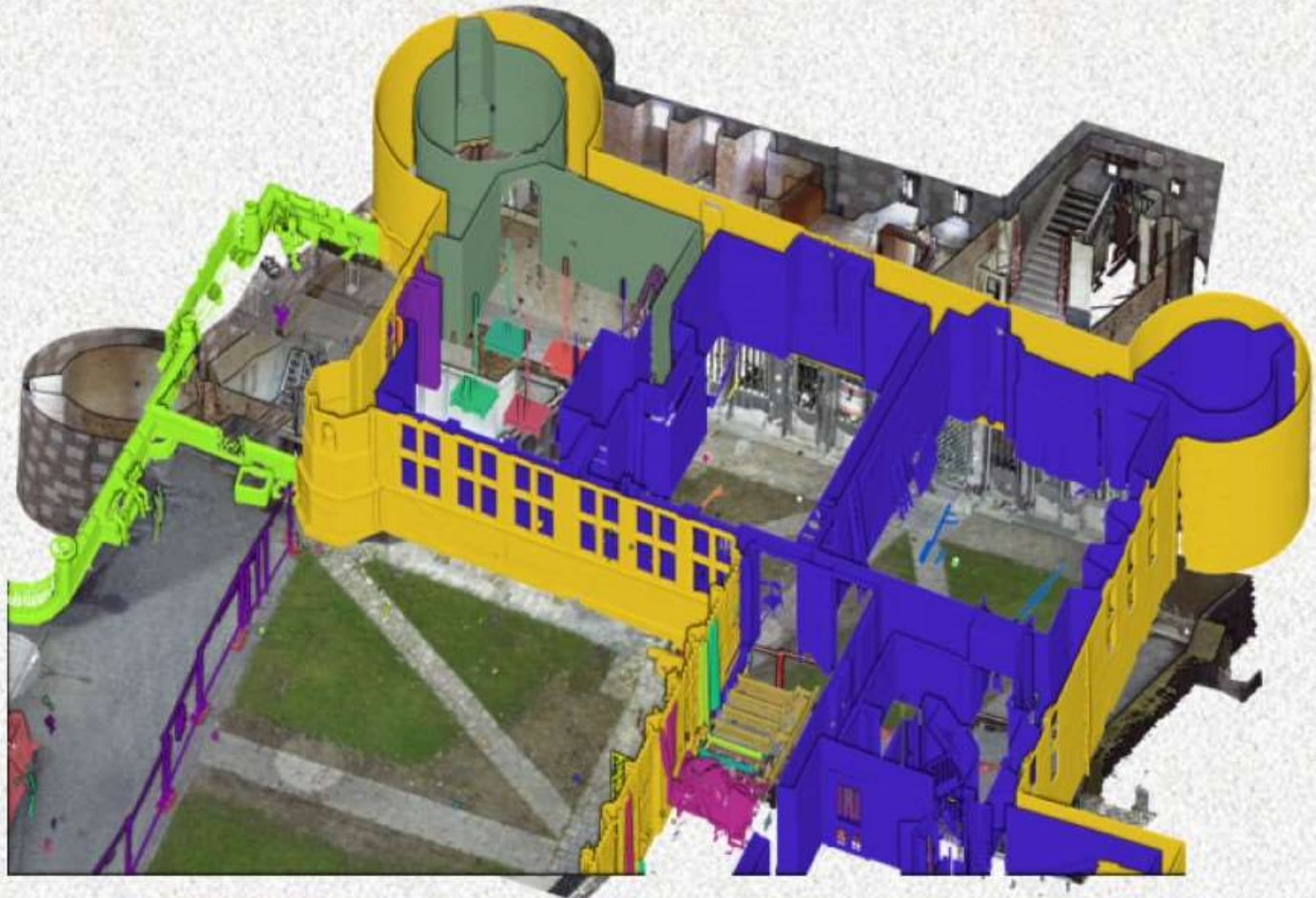


- Acquisition
- Pre-processing
- Registration
- Segmentation
- Classification
- Structuration
- Application





# The Smart Point Cloud



CLASSICAL  
← THE SPC →



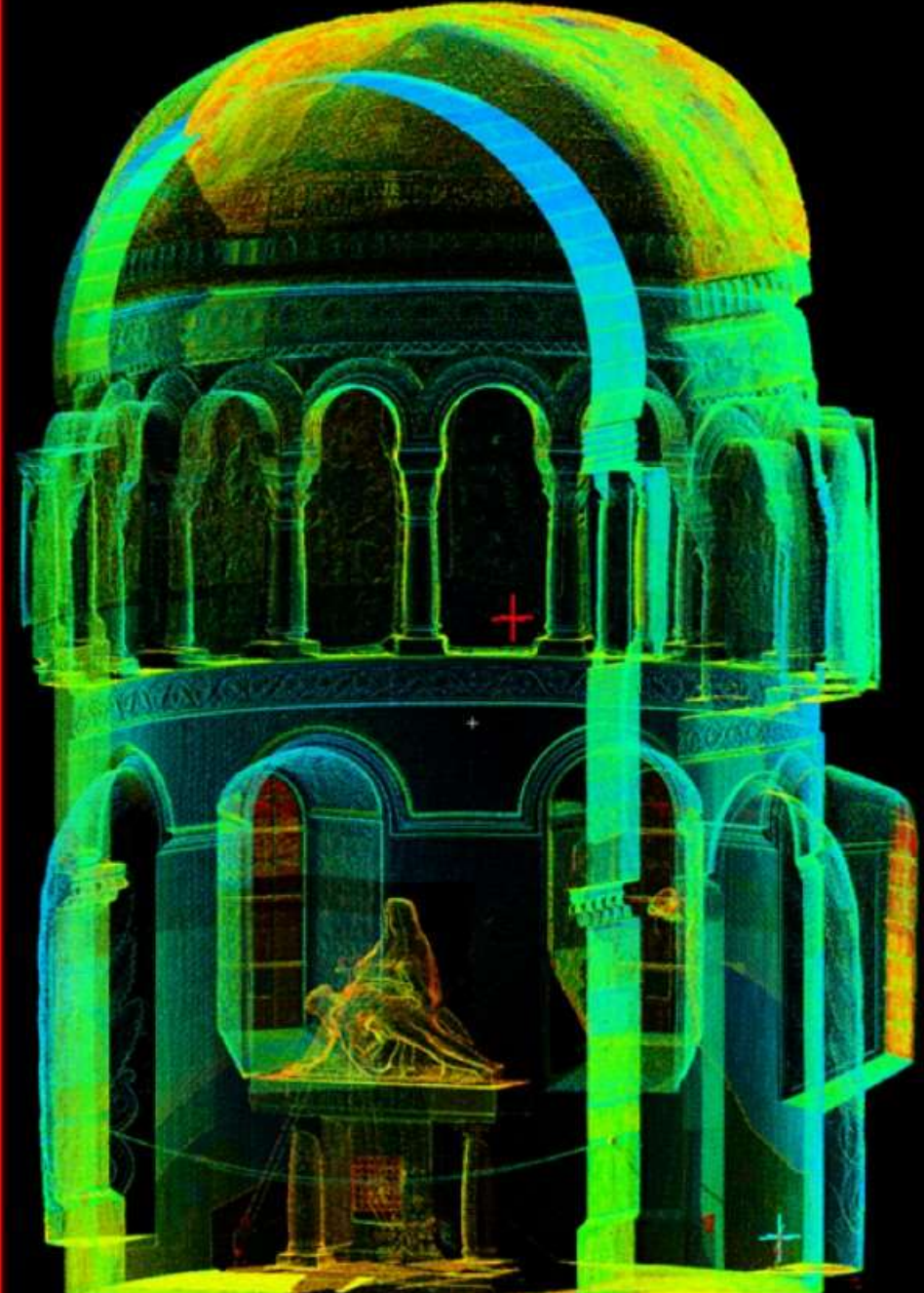
KNOWLEDGE

DELIMITATION  
EXTRACTION  
SIMULATION, ...

SMART POINT CLOUD: DEFINITION AND REMAINING CHALLENGES, Poux et al., 2016



The 3D Laser Scan

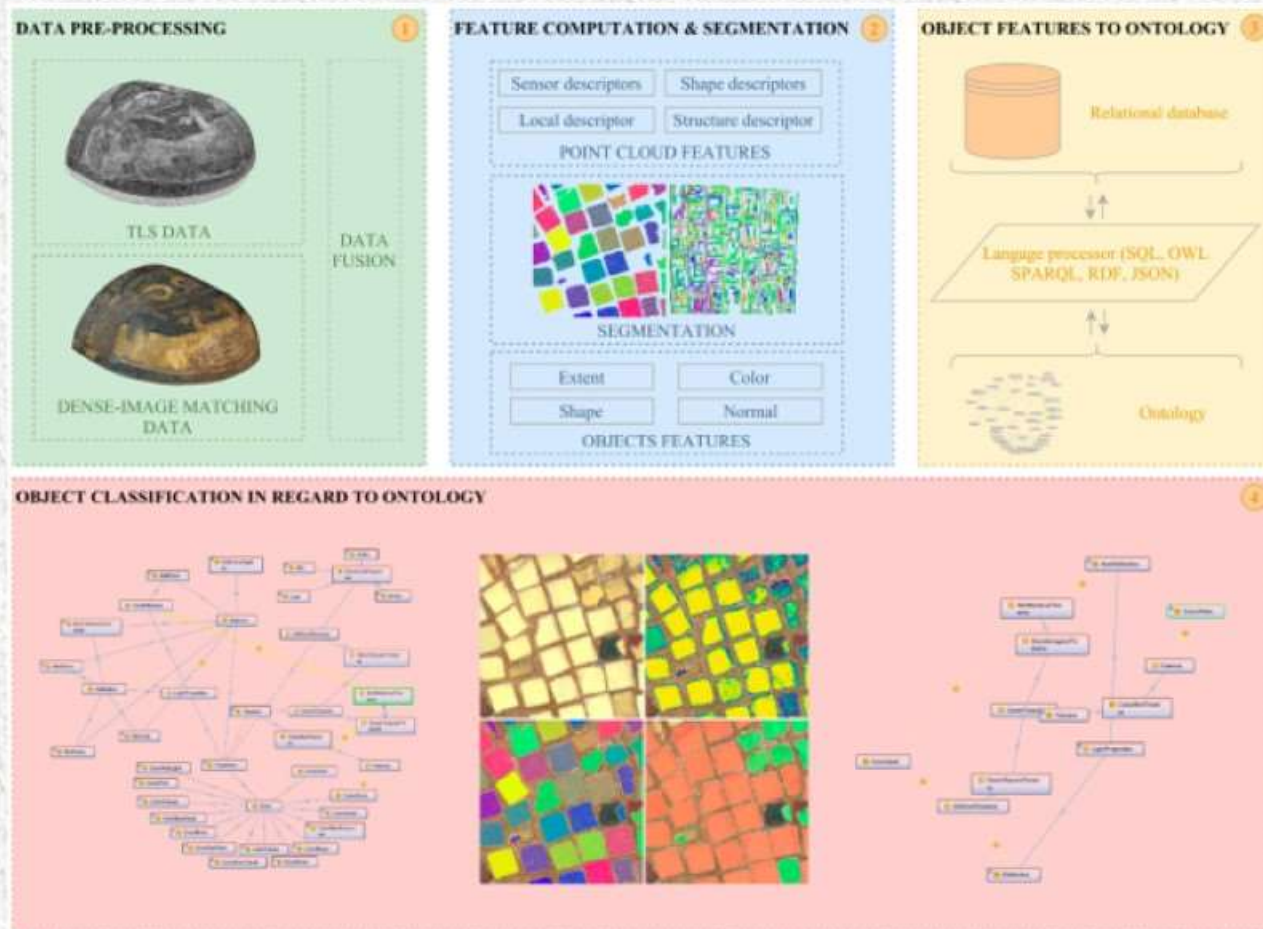


# The Image acquisition

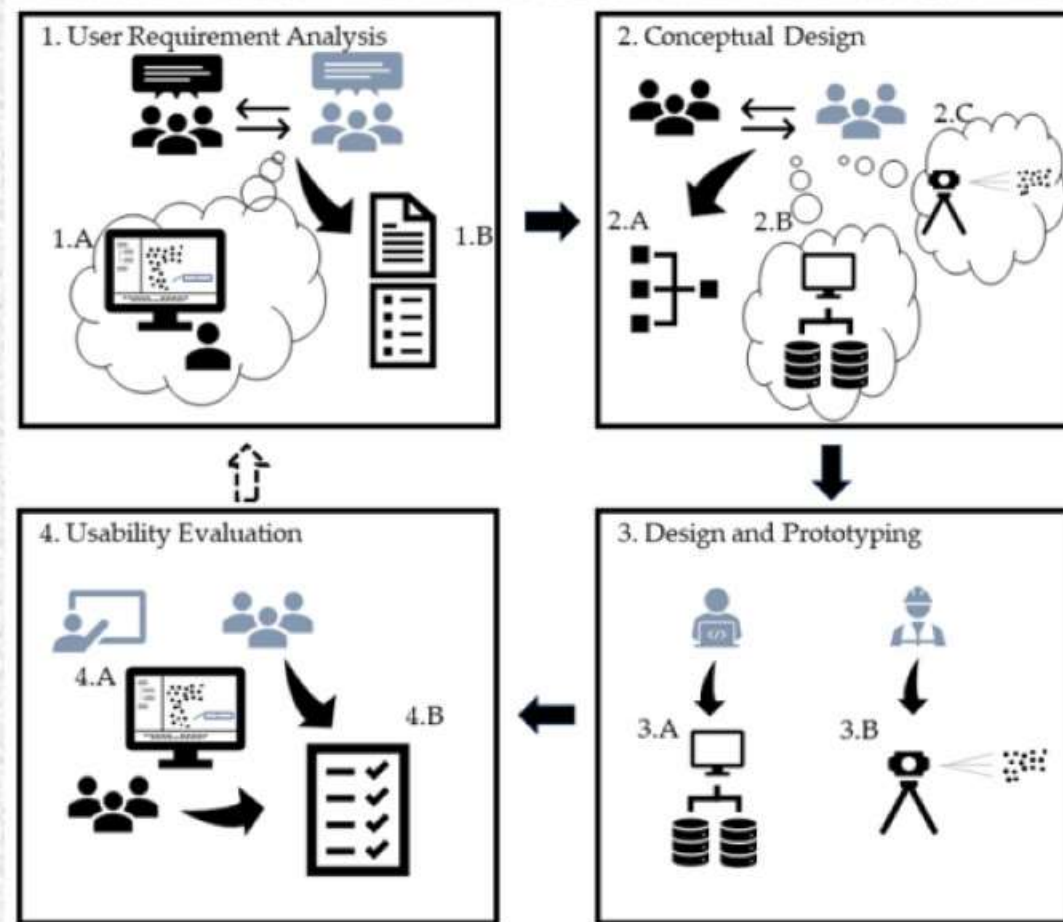


F. Poux - Point cloud processing for geometric and semantic interpretation

## A specialized workflow



[3D Point Clouds in Archaeology: Advances in Acquisition, Processing and Knowledge Integration Applied to Quasi-Planar Objects](#), Poux et al., 2017



[A Built Heritage Information System Based on Point Cloud Data: HIS-PC](#), Poux et al., 2020

INITIAL

GOLD

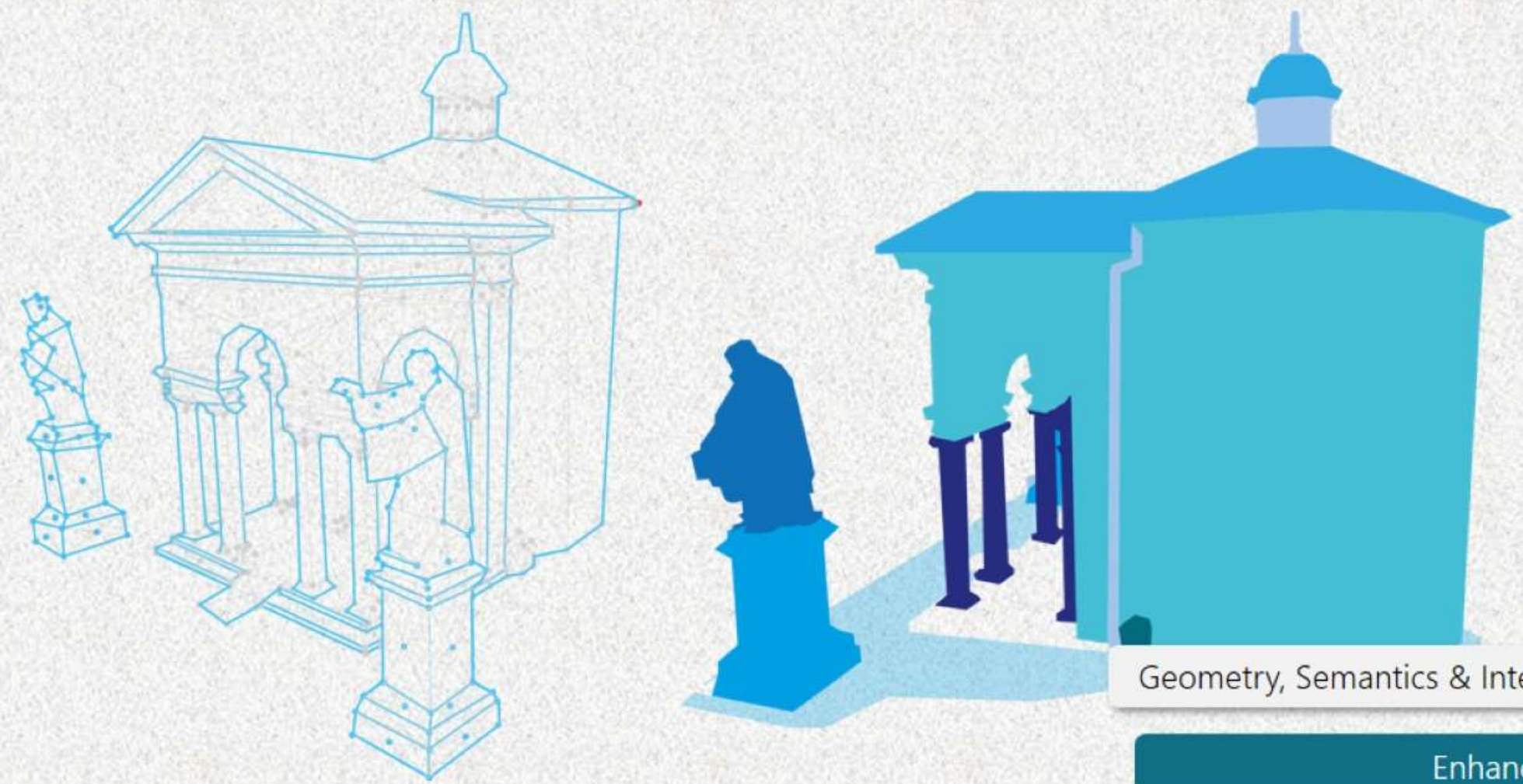
FAIENCE

SILVER

## The Decision-making tool



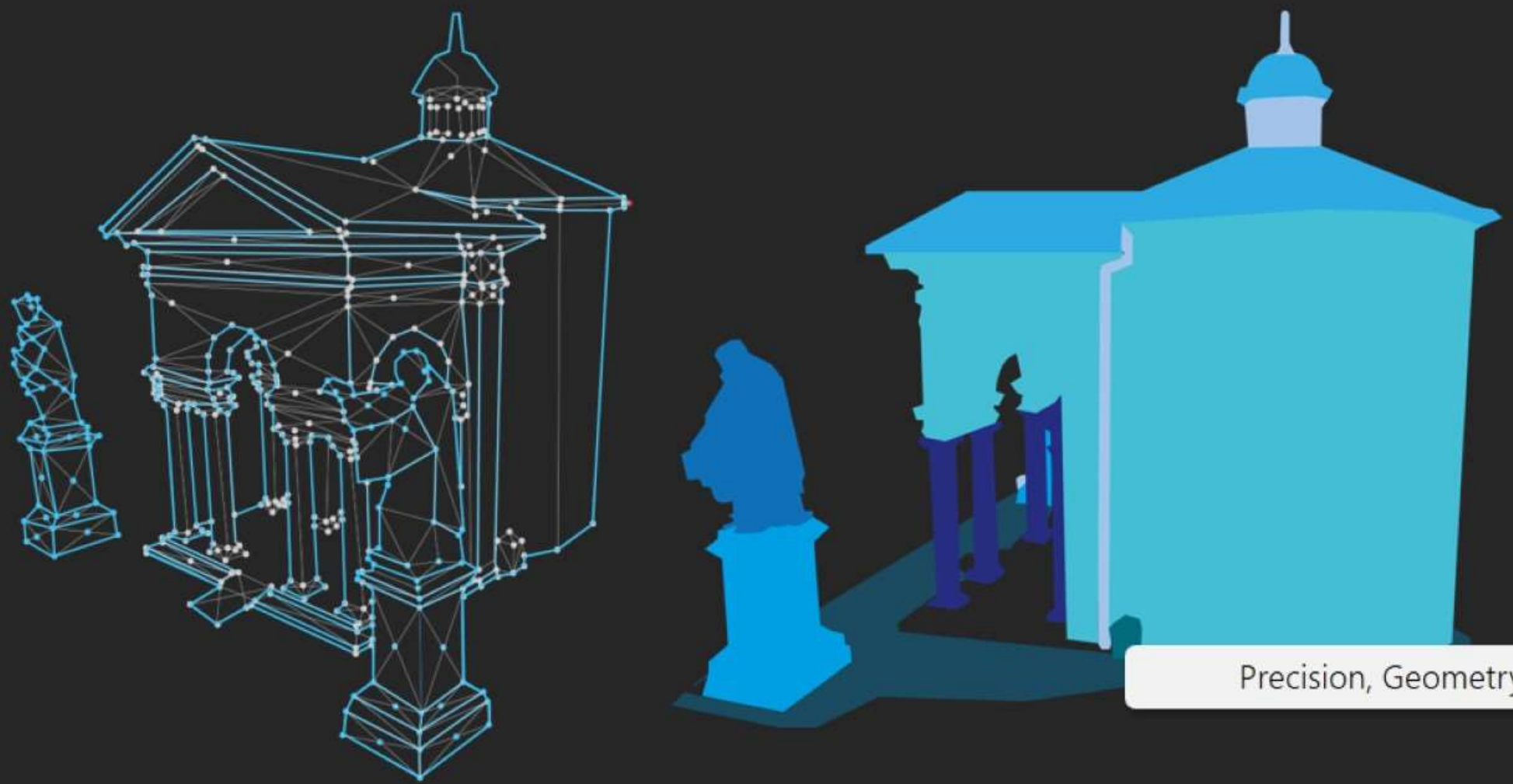
# 1. A parallel to our perceptual system for Decision-Making?



Geometry, Semantics & Interpretation ✓

Enhanced Sensing +

## 2. Multiple levels of representation and perception?



Precision, Geometry & Semantics

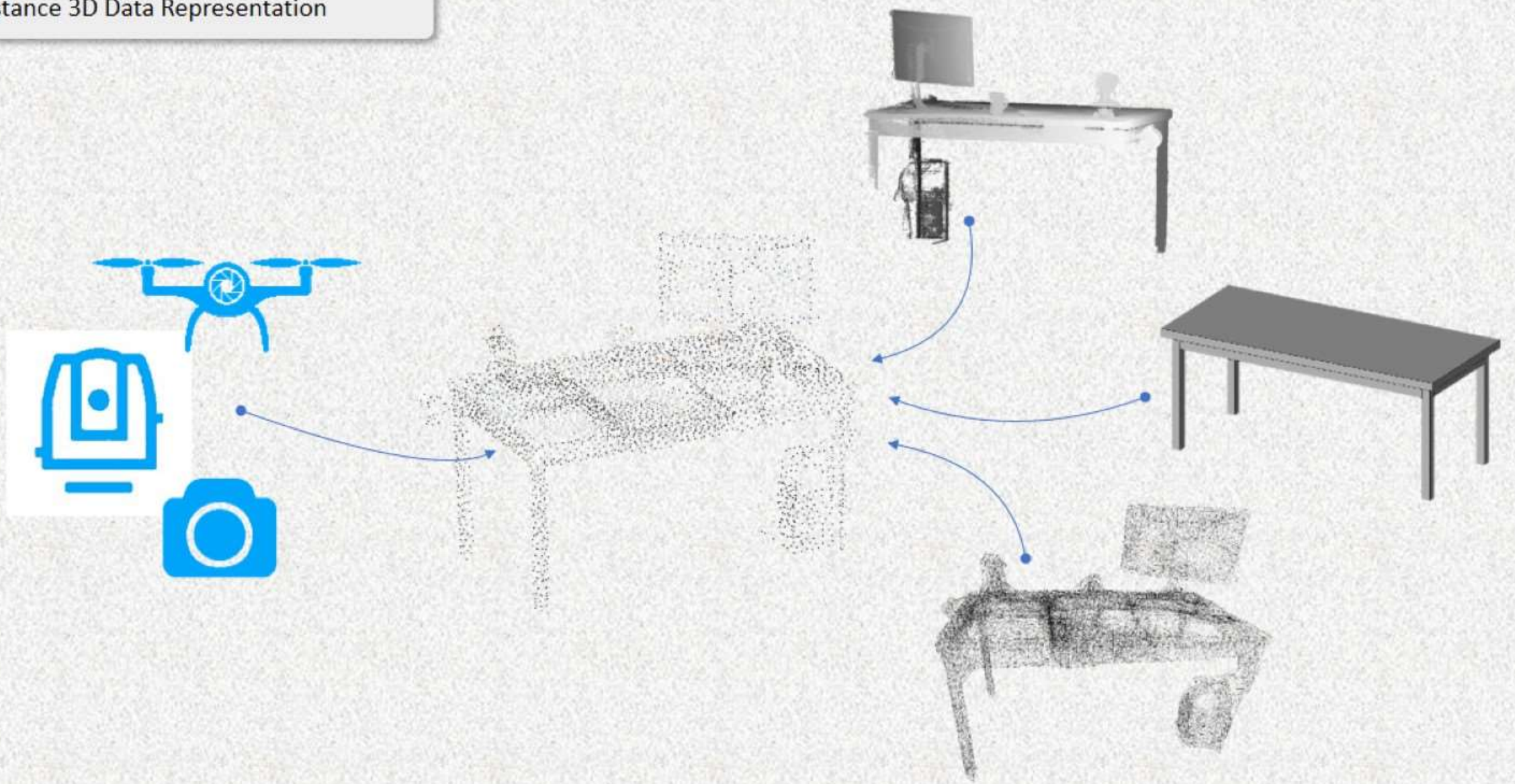




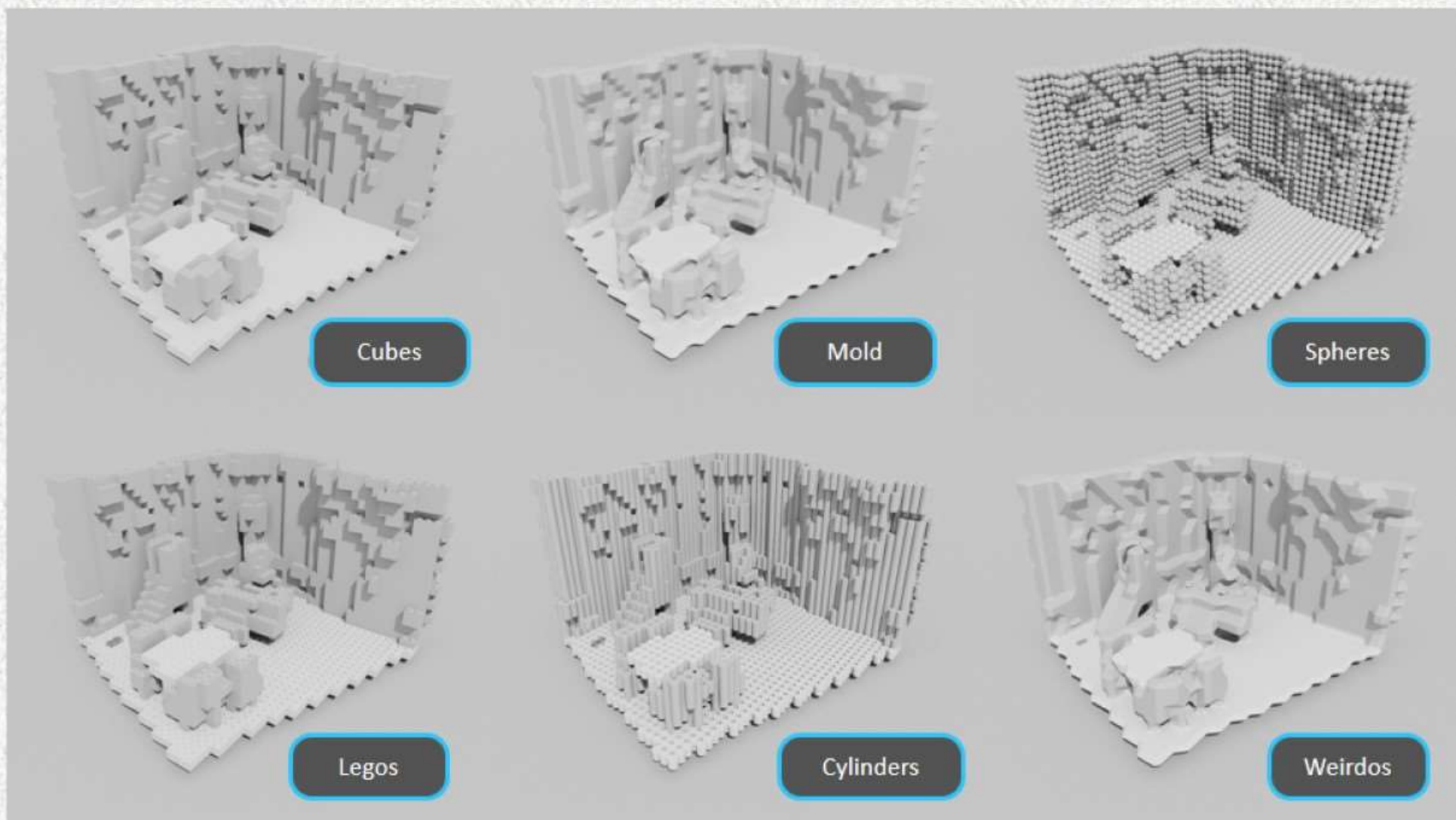
Point Clouds



# Instance 3D Data Representation



## Scene Data Representation

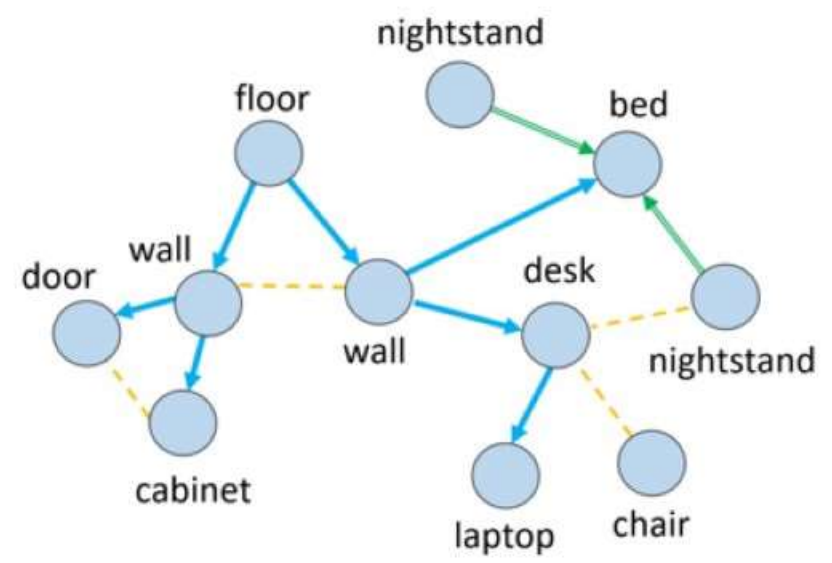




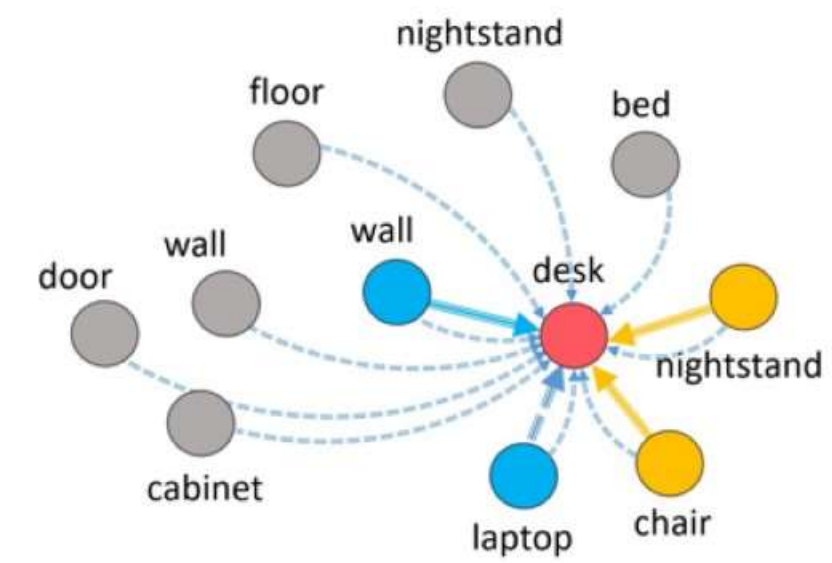
# Scene Semantic Representation



3D indoor scene example (bedroom)



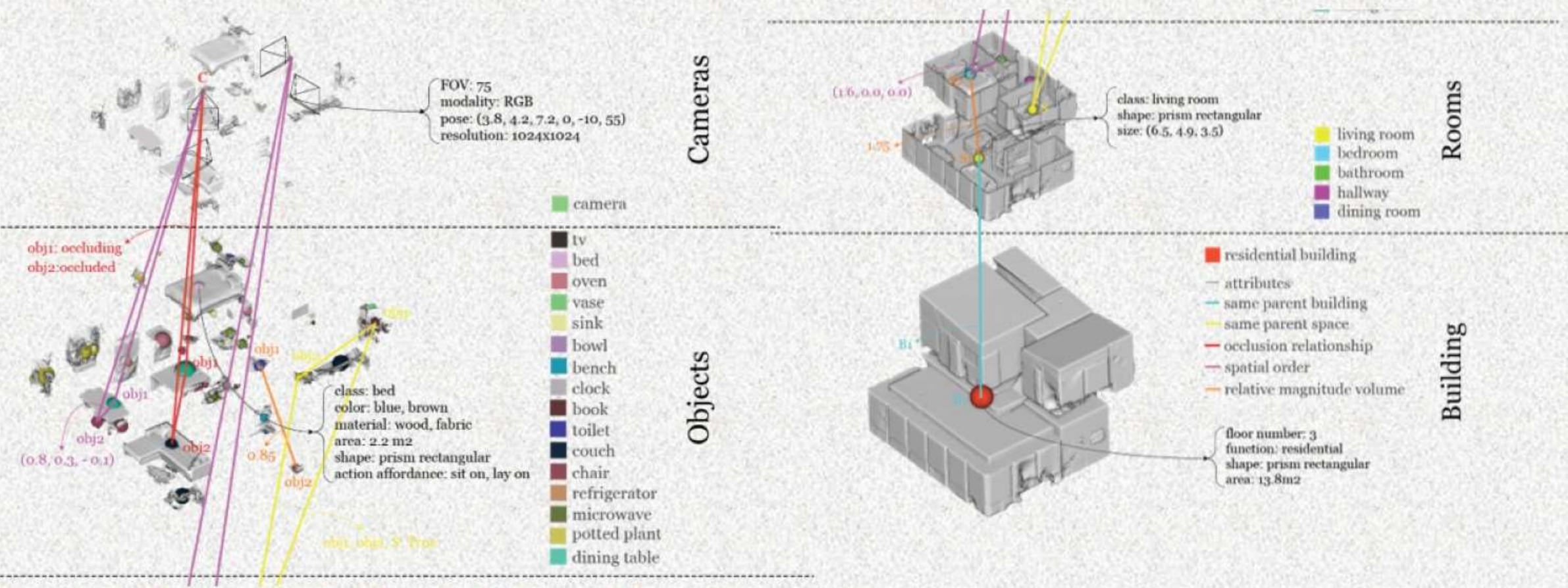
→ **Support**    
 → **Surround**    
 - - - → **Next-to**



→ **Supporting message**    
 - - - → **Supported-by message**  
→ **Surrounding message**    
 - - - → **Surrounded-by message**  
→ **Next-to message**    
 - - - → **Co-occurring message**

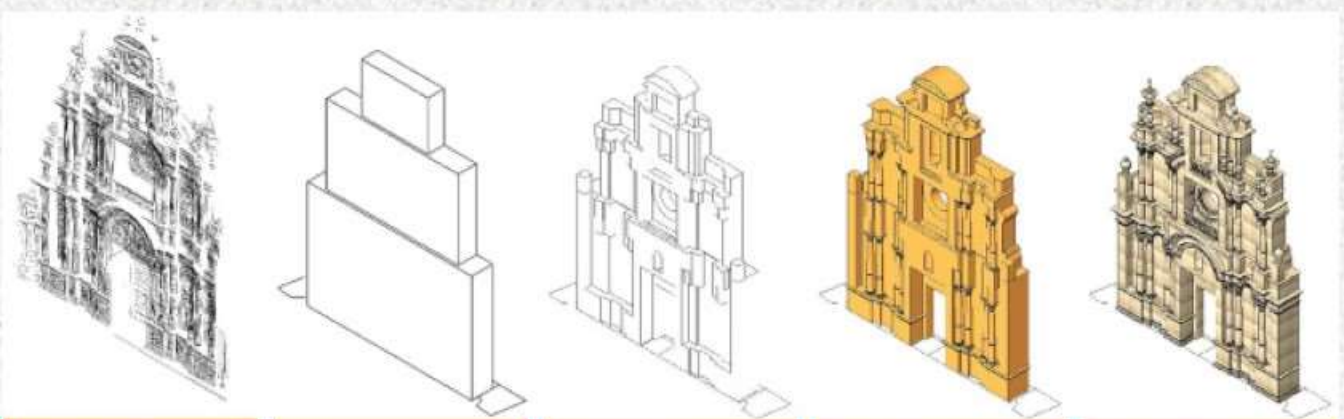
[SceneGraphNet: Neural Message Passing for 3D Indoor Scene Augmentation](#), Zhou et al., 2019

# Scene Semantic Representation

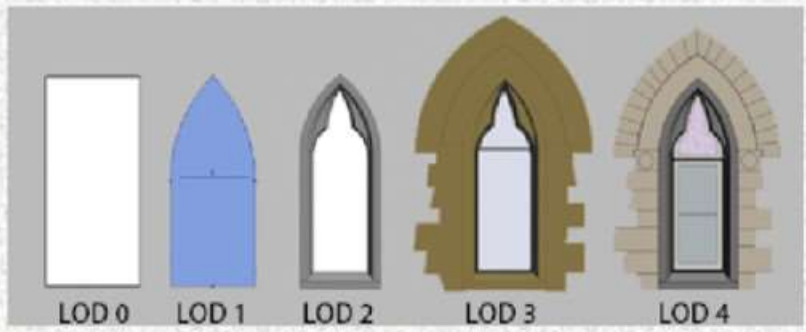


3D Scene Graph: A Structure for Unified Semantics, 3D Space, and Camera, Armeni et al., 2019

# 3D Level of Detail



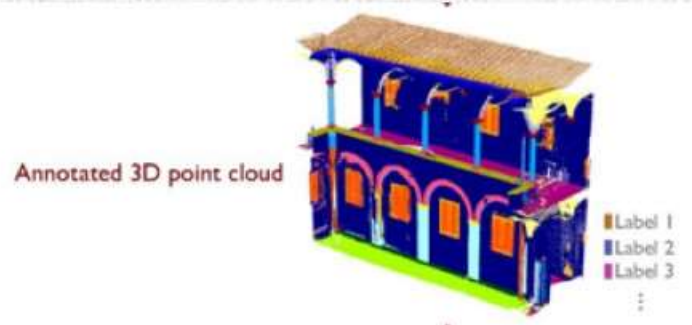
<p><b>LOK100</b> IDENTIFICATION</p> <p>Graphic codification, symbolic or accurate, but not categorized.</p> <p>Basic characterization.</p> <p>Georeferenced location and orientation.</p>	<p><b>LOK200</b> PROTECTION AND DISSEMINATION</p> <p>Basic structures and constructive evolution modelling.</p> <p>Legal protection documentation and strategic planning.</p> <p>Graphical support for dissemination.</p>	<p><b>LOK300</b> ADVANCED RESEARCH</p> <p>Complex structures modelling.</p> <p>Advanced material characterization and disciplinary diagnosis.</p>	<p><b>LOK400</b> CONSERVATION &amp; INTERVENTION</p> <p>Conservation and intervention projects.</p> <p>Criteria and procedures definition.</p>	<p><b>LOK500</b> COMPREHENSIVE MANAGEMENT</p> <p>Periodic programs of research, preventive conservation, use and dissemination.</p> <p>Periodic investment plan.</p>
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	LOD x.0	LOD x.1	LOD x.2	LOD x.3
LOD0				
LOD1				
LOD2				
LOD3				

Dimensions and Levels of Knowledge in Heritage Building Information Modelling, HBIM: The model of the Charterhouse of Jerez (Cádiz, Spain), M. Castellano-Román, F. Puerto

# H-BIM



## Scan-to-Building Information Modeling (BIM)

Extraction of single classes of architectural components

Label 1 Label 2 Label 3  
Label 4 Label 5 Label 6

Libraries of ideal parametric shapes

Reconstruction of parametric components

AUTODESK REVIT



Documentary sources

Materials

State of conservation

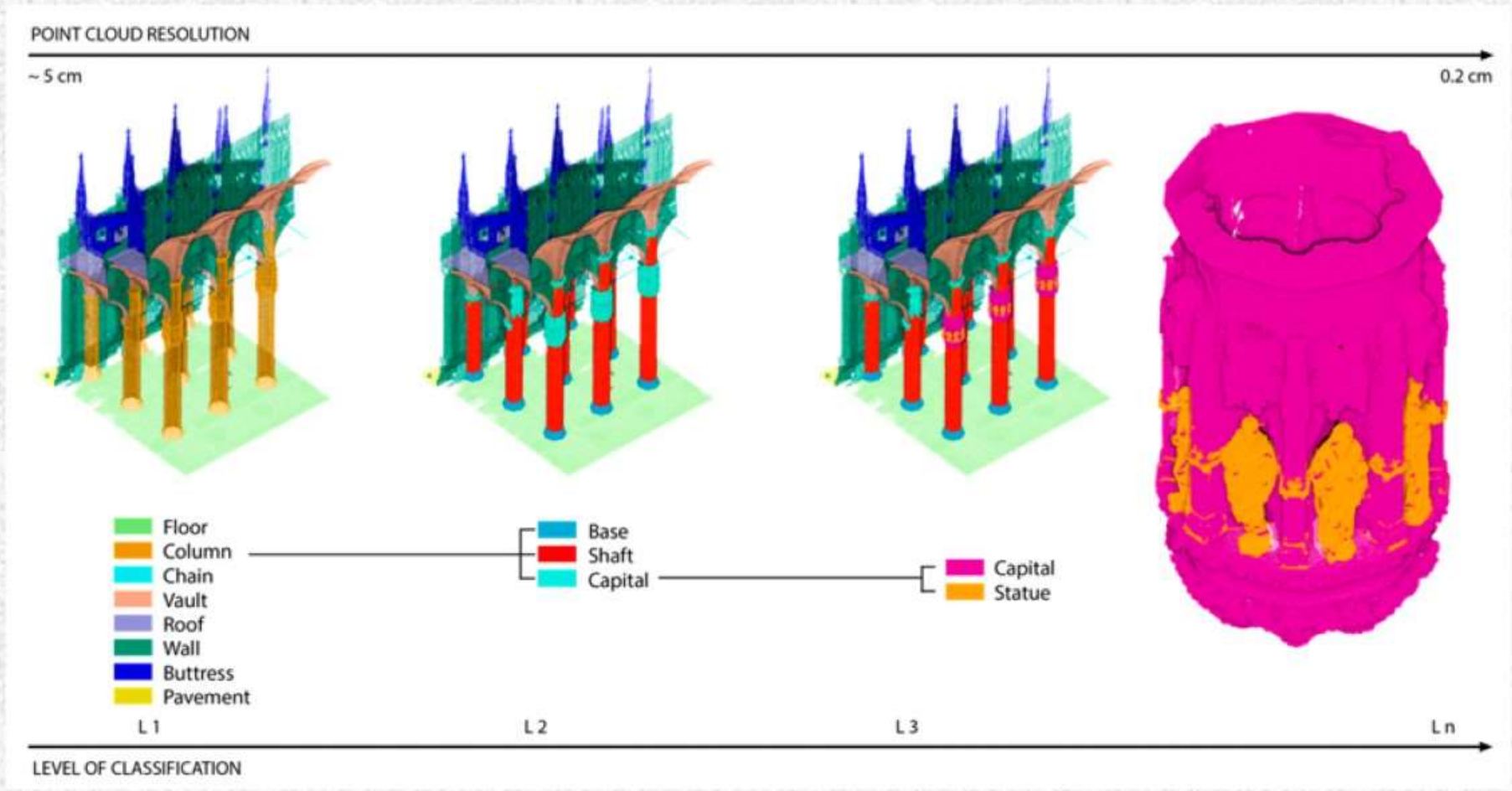
Interventions

Diagnosis

[From the Semantic Point Cloud to Heritage-Building Information Modeling: A Semiautomatic Approach Exploiting Machine Learning](#), Croce et al., 2021



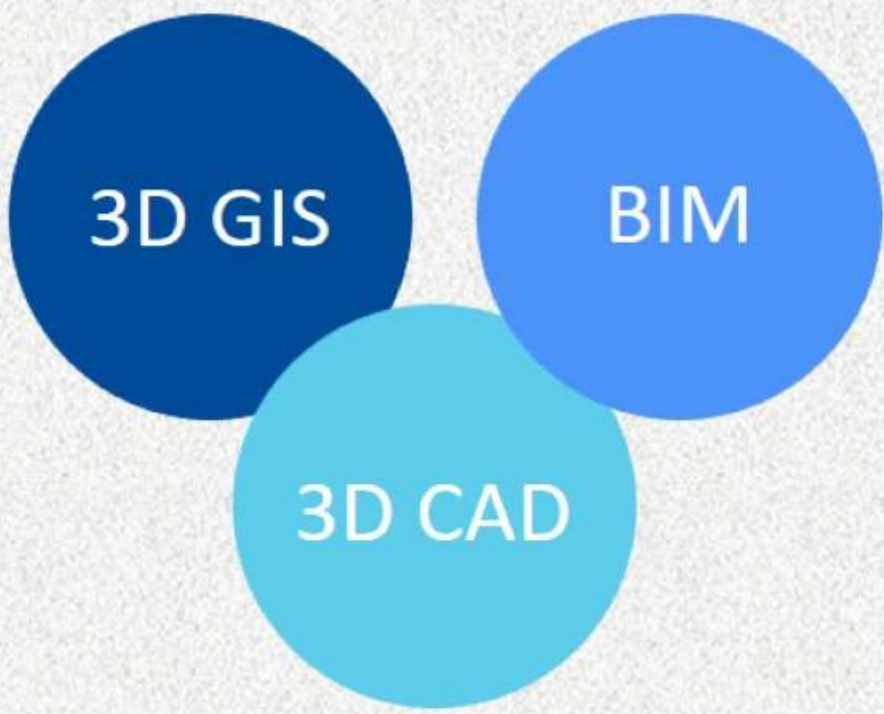
# 3D Hierarchical Semantics



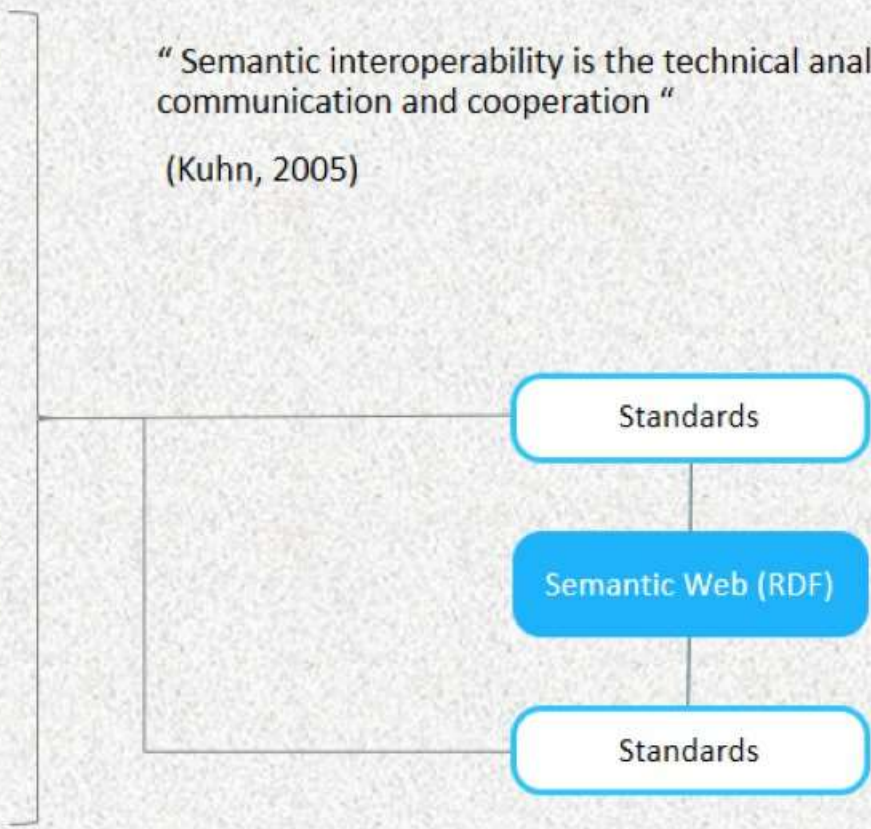
[A Hierarchical Machine Learning Approach for Multi-Level and Multi-Resolution 3D Point Cloud Classification](#), Teruggi et al., 2020

# Semantics Interoperability

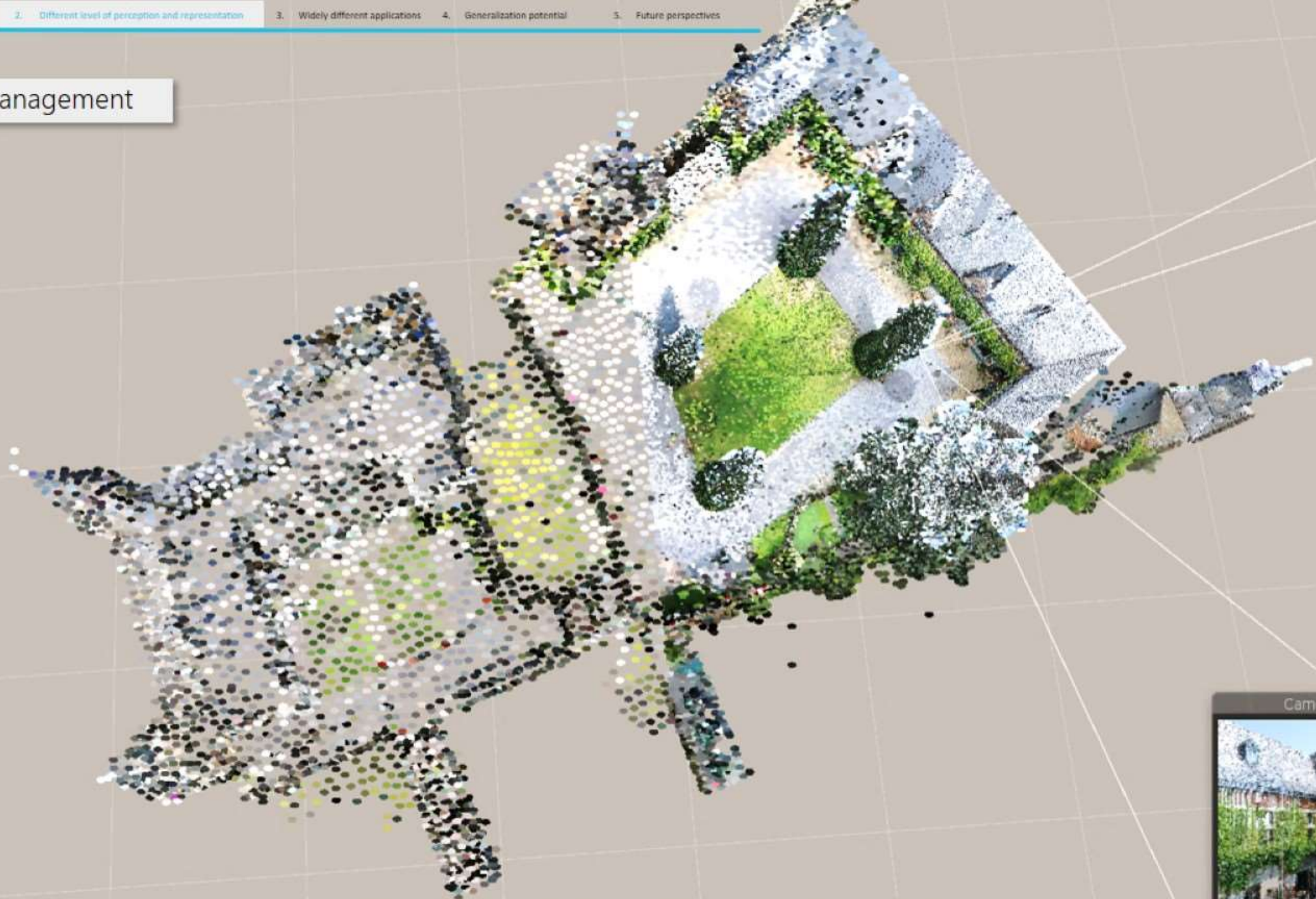
Explicit 3D Spatial IS



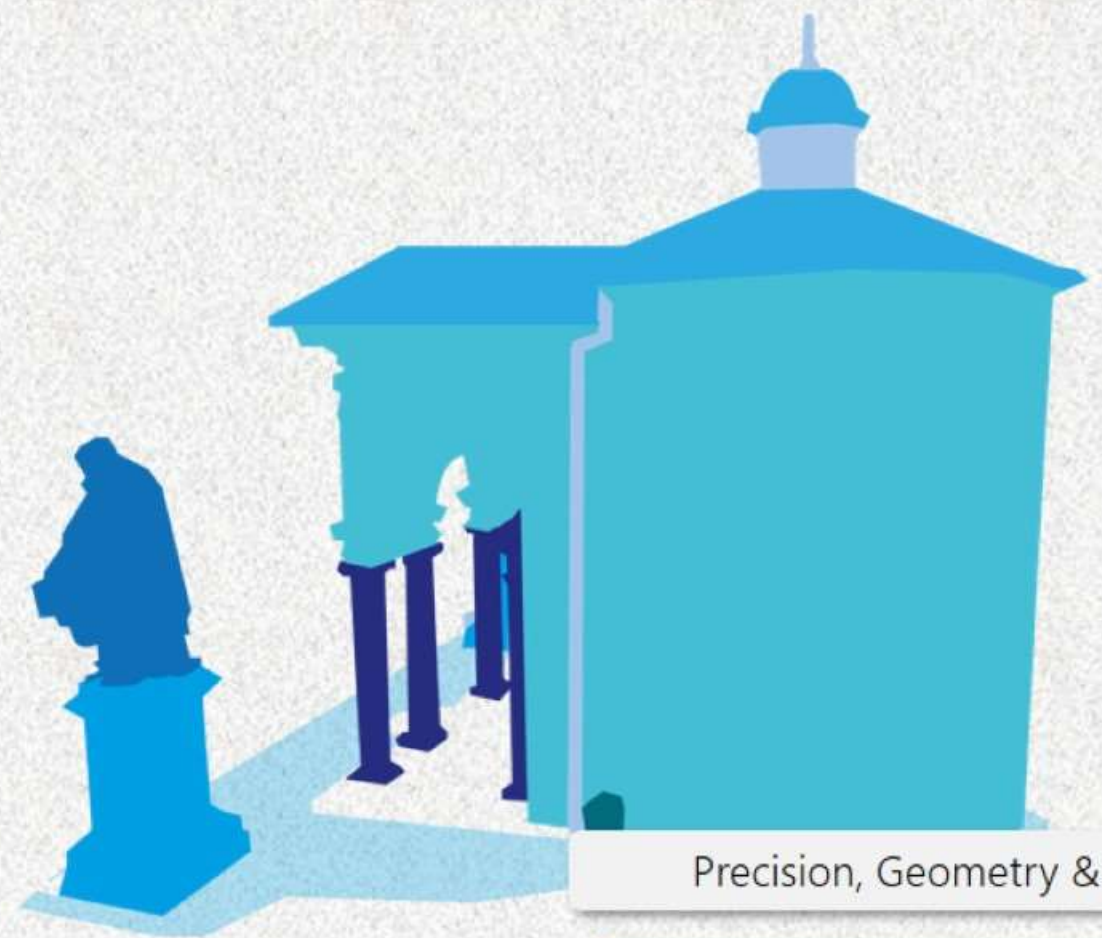
“ Semantic interoperability is the technical analogue to human communication and cooperation “  
(Kuhn, 2005)



# Viewpoint management



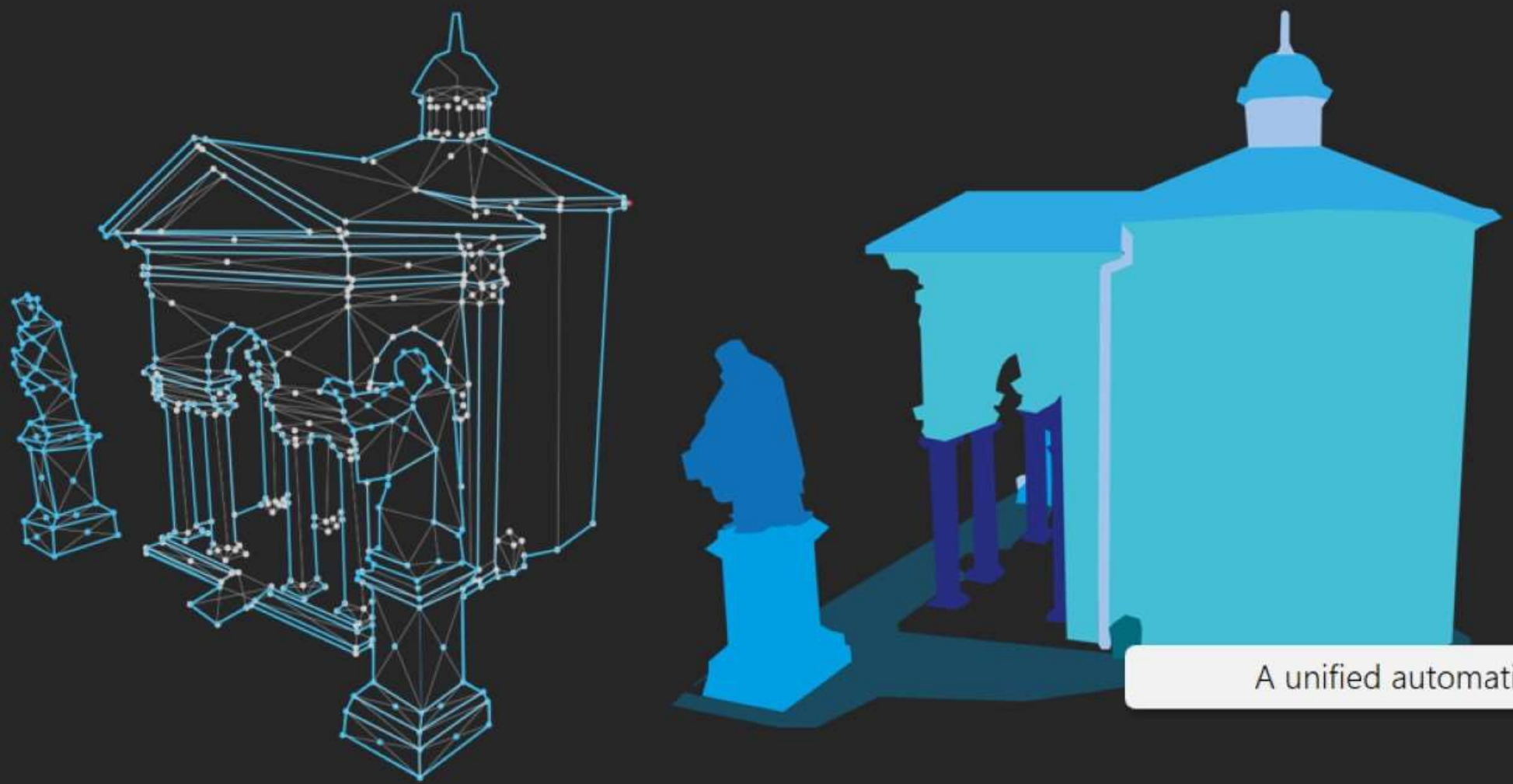
## 2. Multiple levels of perception and representation?



Precision, Geometry & Semantics ✓

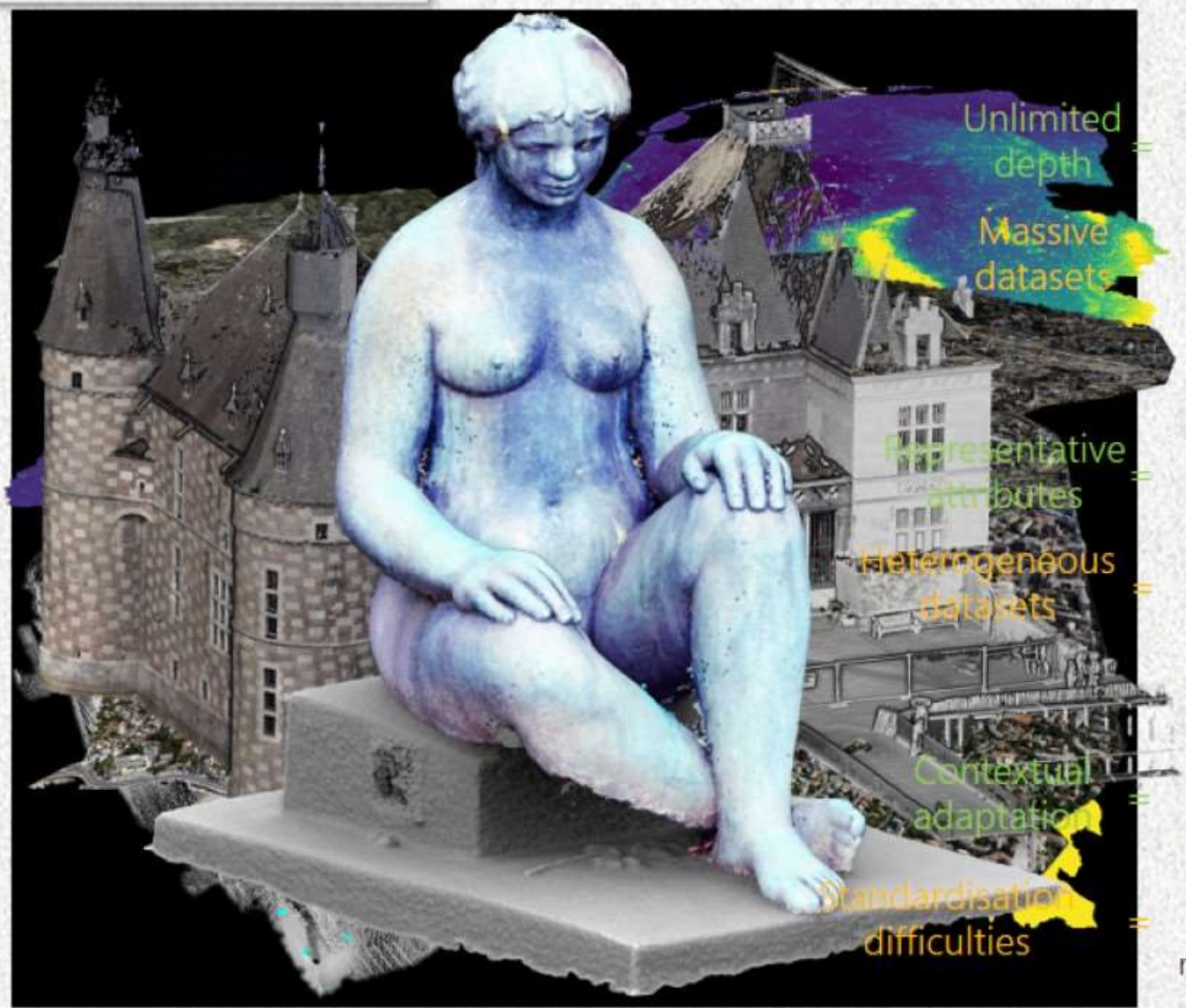
Extended viewpoints & perspectives +

3. Can we address widely different applications and concepts?

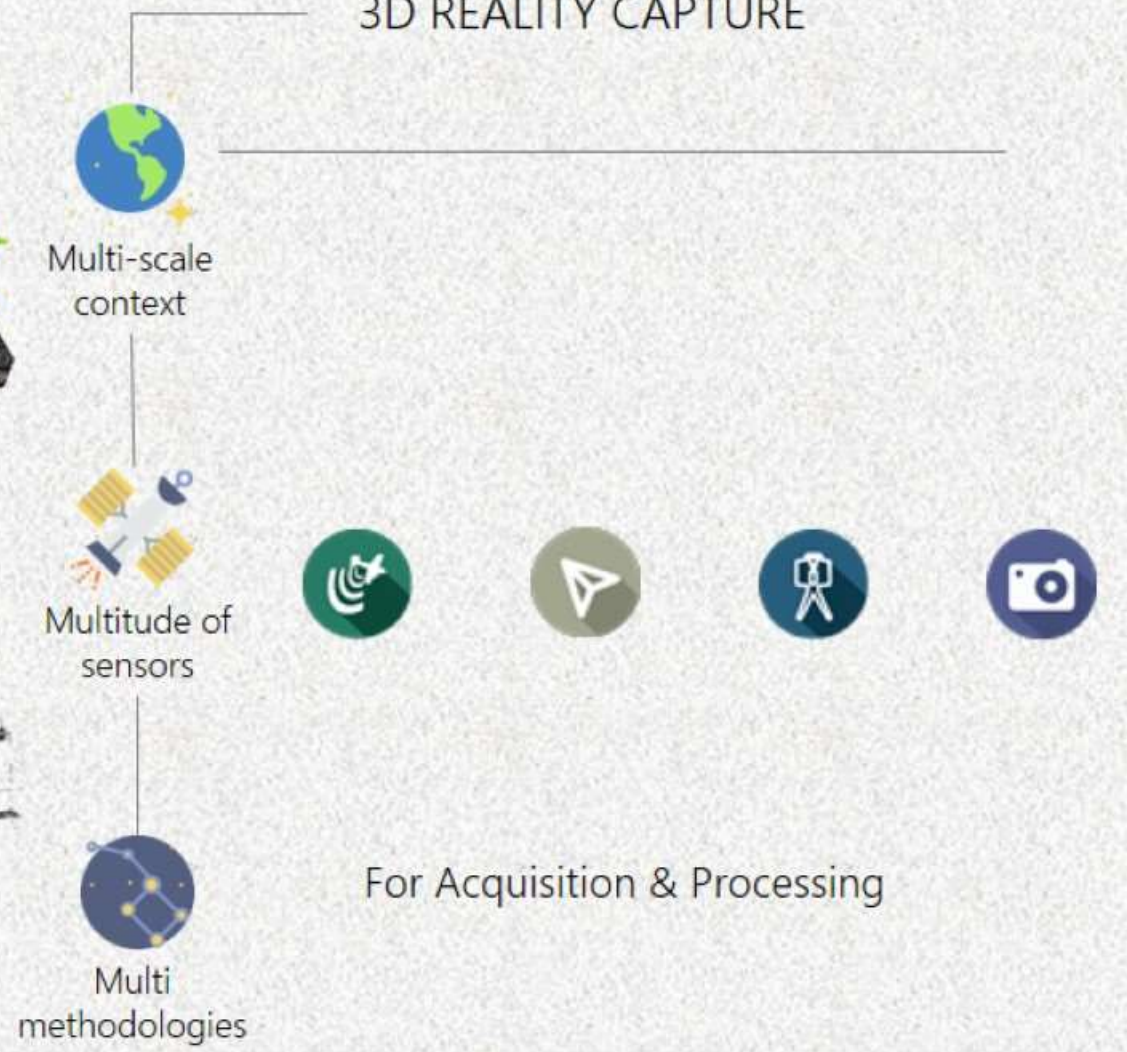


A unified automatic processing?

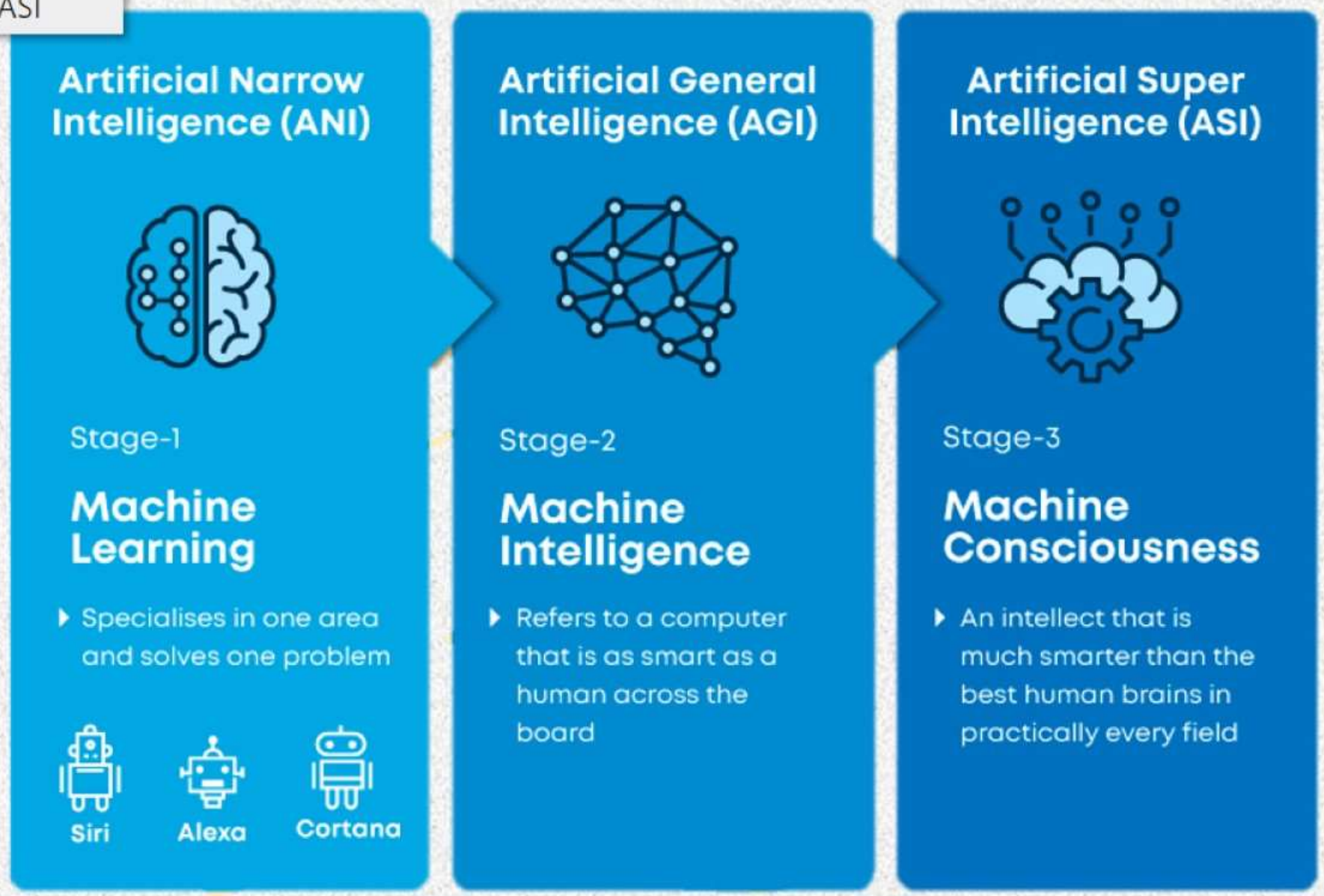
# Acquisition Adaptation



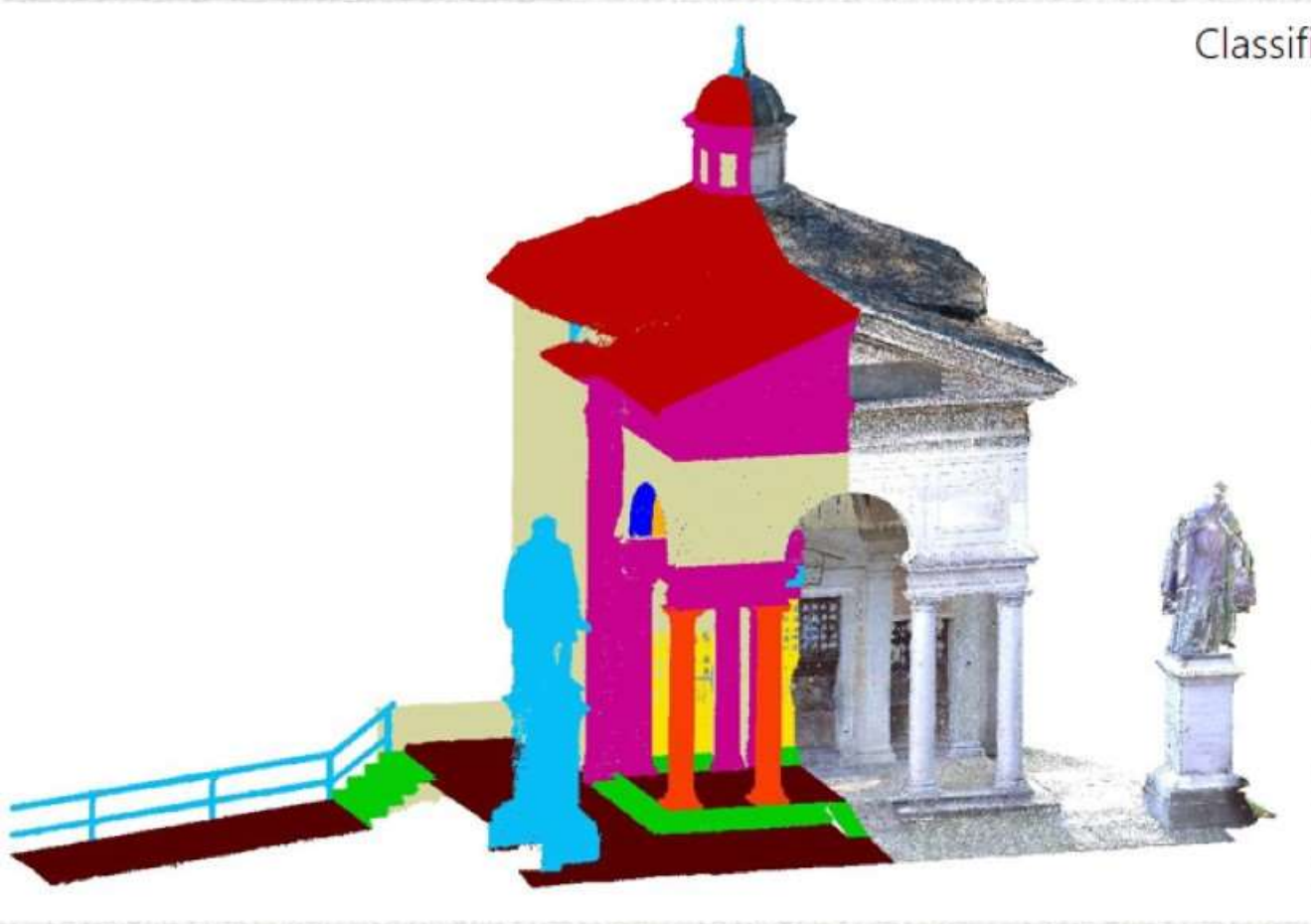
## 3D REALITY CAPTURE



# A(N)I vs AGI vs ASI



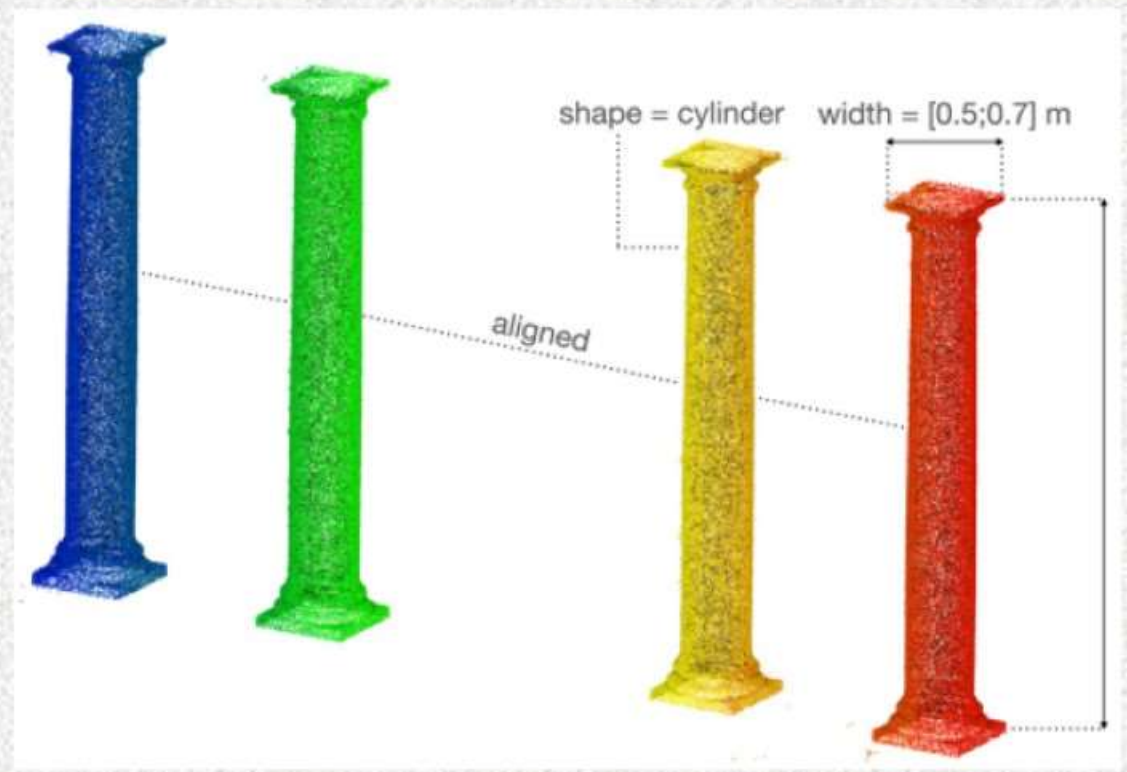
# 3D Segmentation Taxonomy



Semantic Segmentation

[A BENCHMARK FOR LARGE-SCALE HERITAGE POINT CLOUD SEMANTIC SEGMENTATION](#), Matrone et al., 2020

## Classification



Instance segmentation

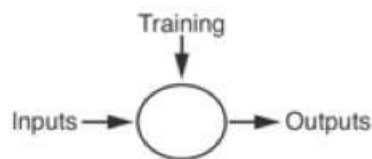
[From Acquisition to Presentation—The Potential of Semantics to Support the Safeguard of Cultural Heritage](#), Ponciano et al., 2021



## Semantic Augmentation

### Supervised learning

Learns known patterns  
Takes labeled input data  
Predicts outcome/future



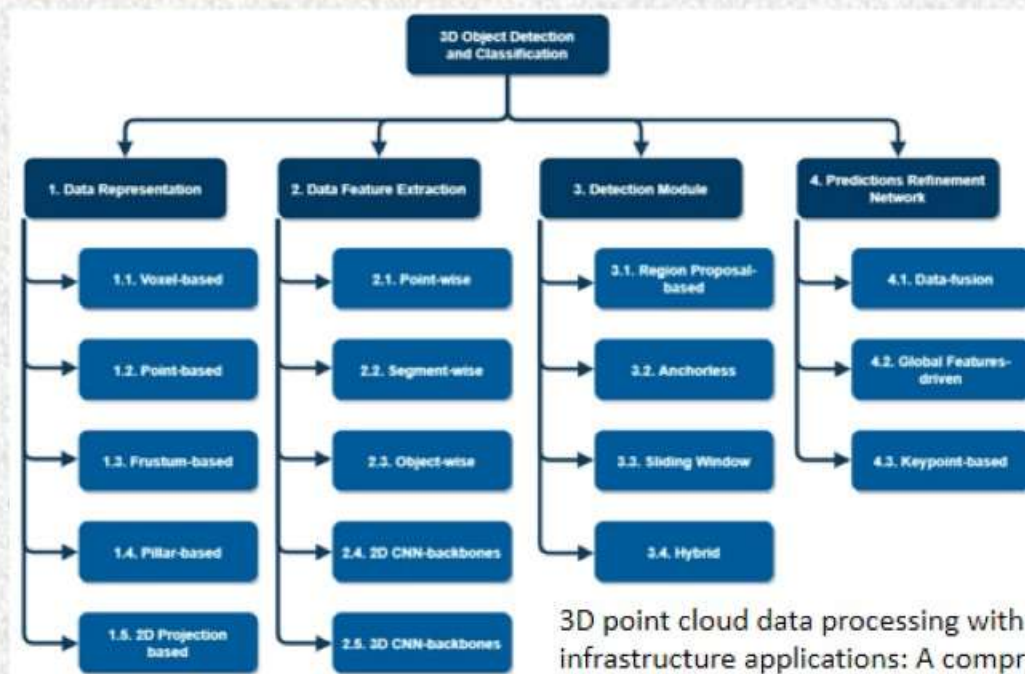
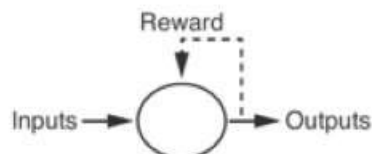
### Unsupervised learning

Learns unknown patterns  
Takes unlabeled input data  
Finds hidden patterns

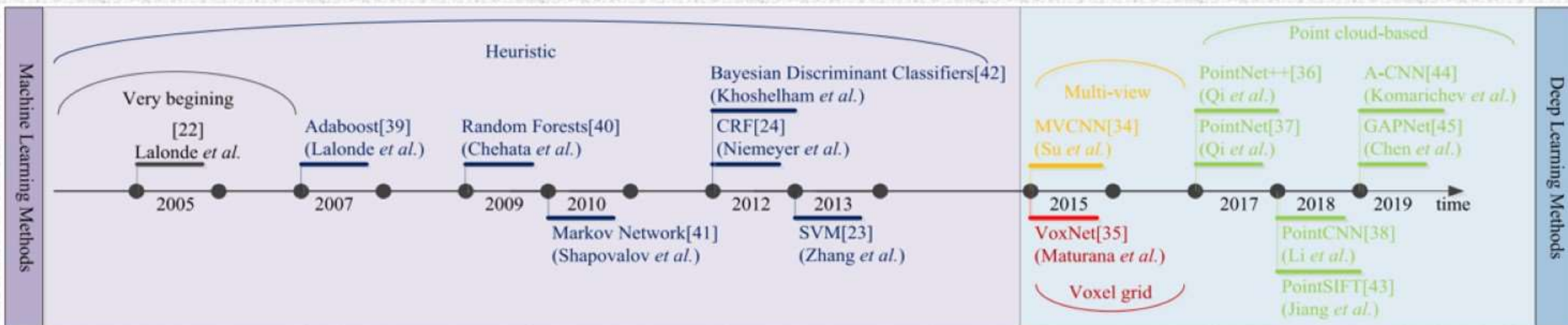
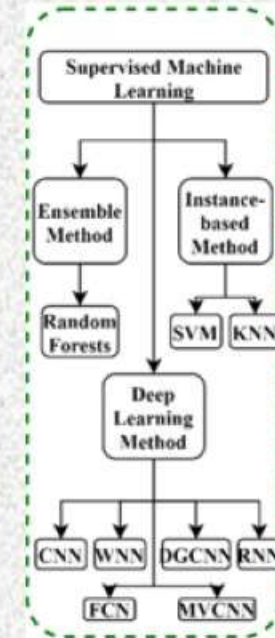


### Reinforcement learning

Generates data  
Takes labeled input data  
Interacts with environment  
Learns series of actions



3D point cloud data processing with machine learning for construction and infrastructure applications: A comprehensive review, Mirzaei et al., 2021

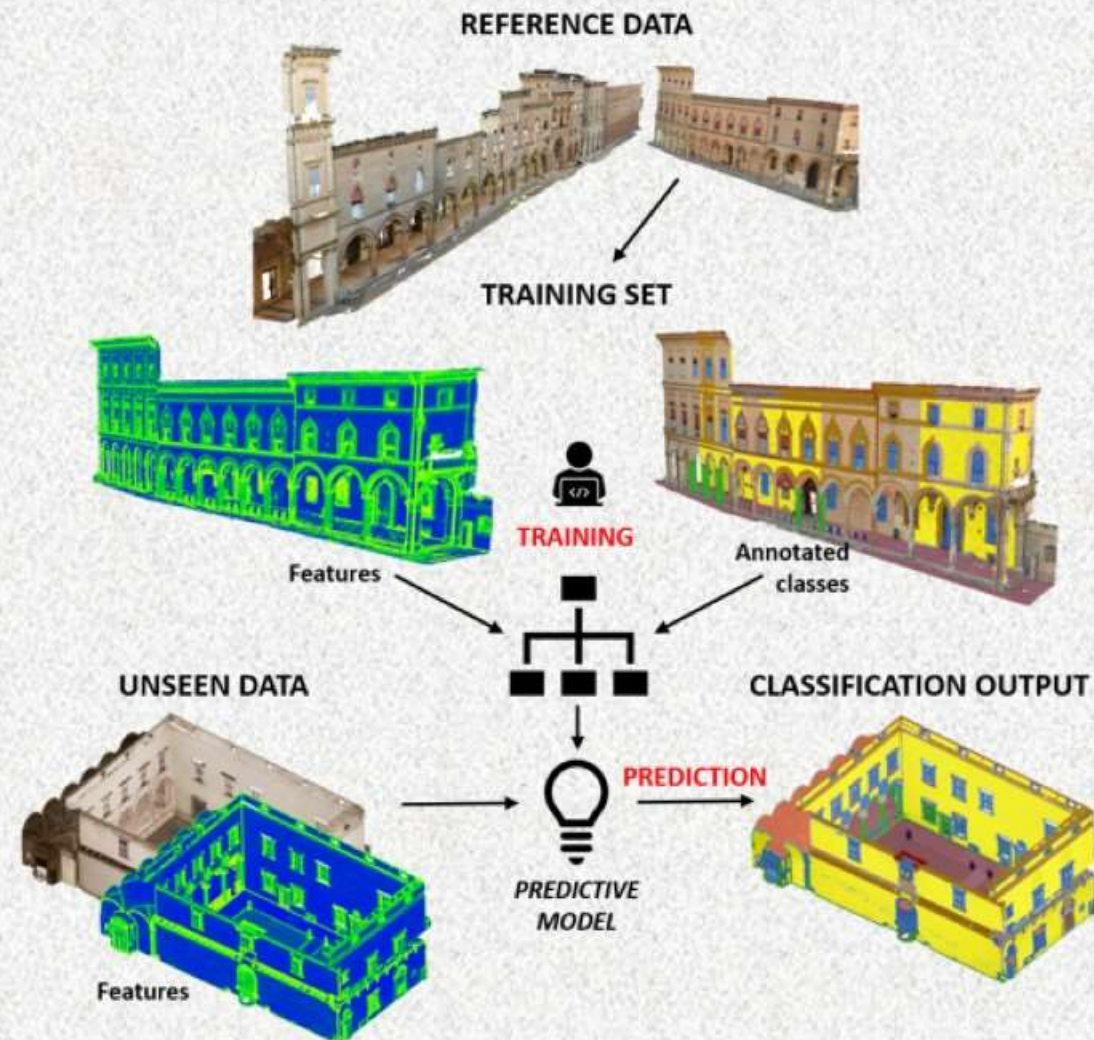


Review of Deep Learning-Based Semantic Segmentation for Point Cloud, Zhang et al., 2020

# SL: Hand-engineer features

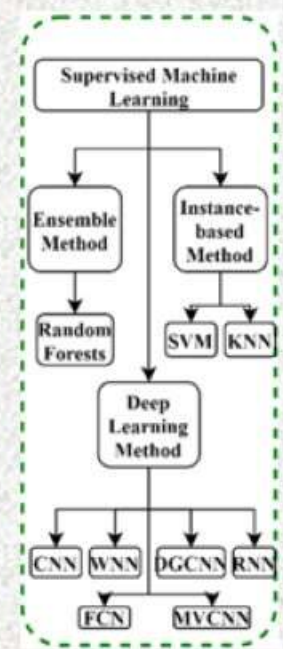
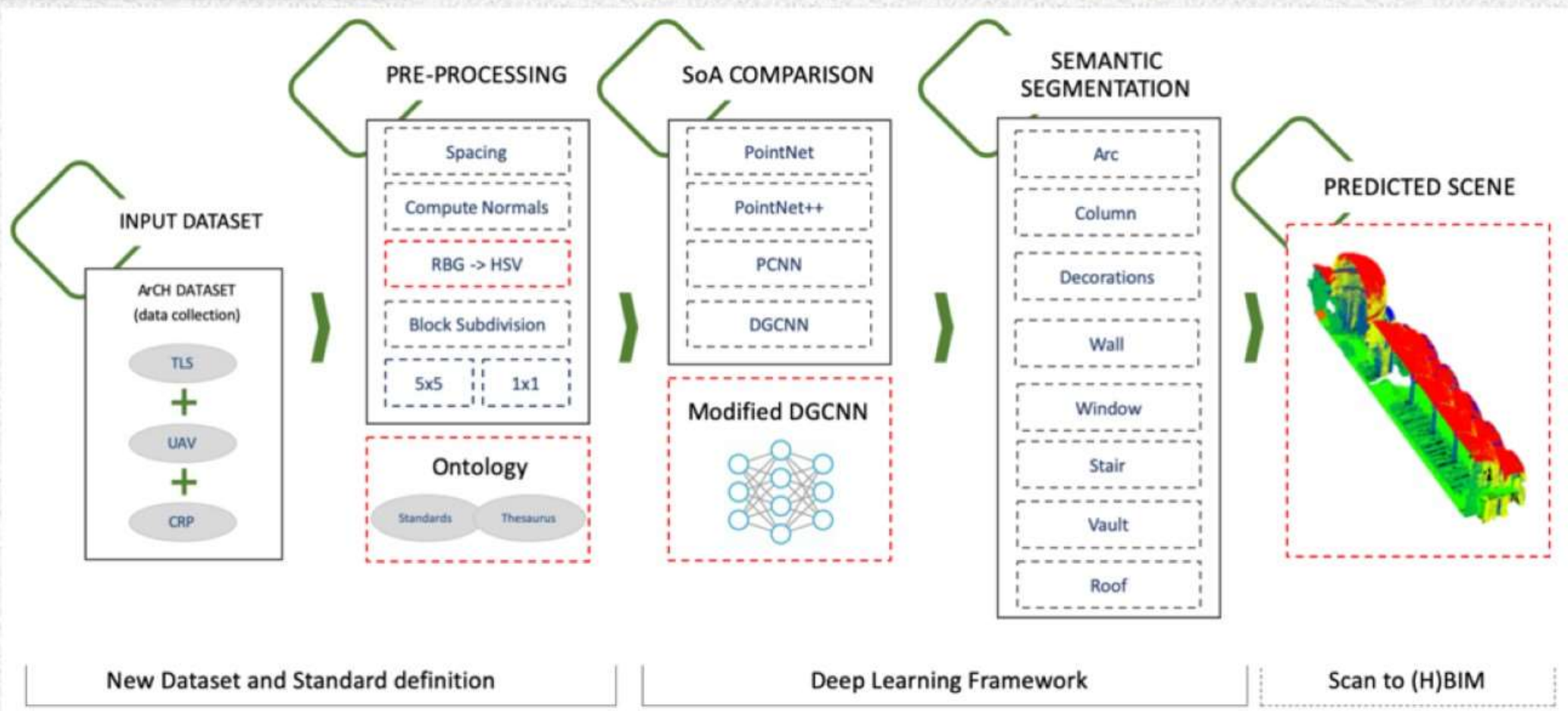


Point Cloud Tutorials: <https://medium.com/@florentpoux>



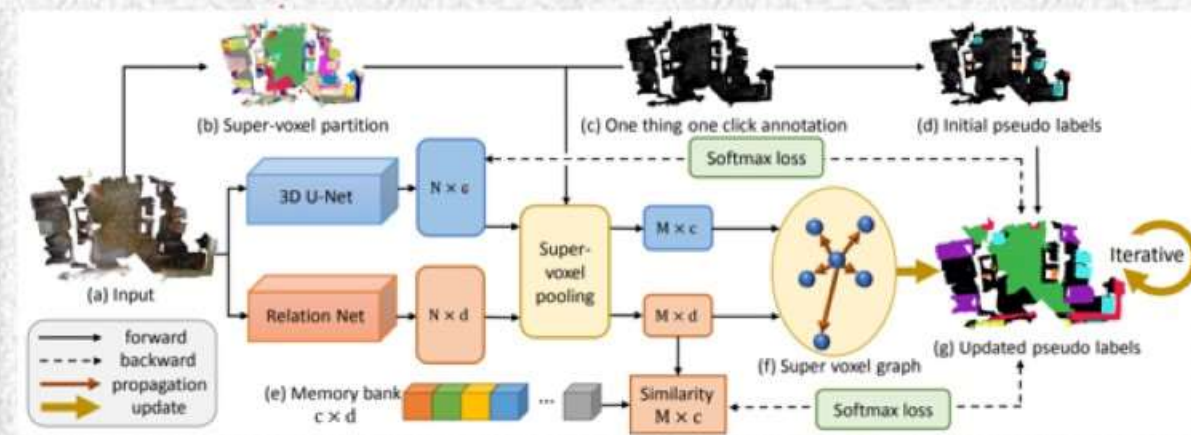
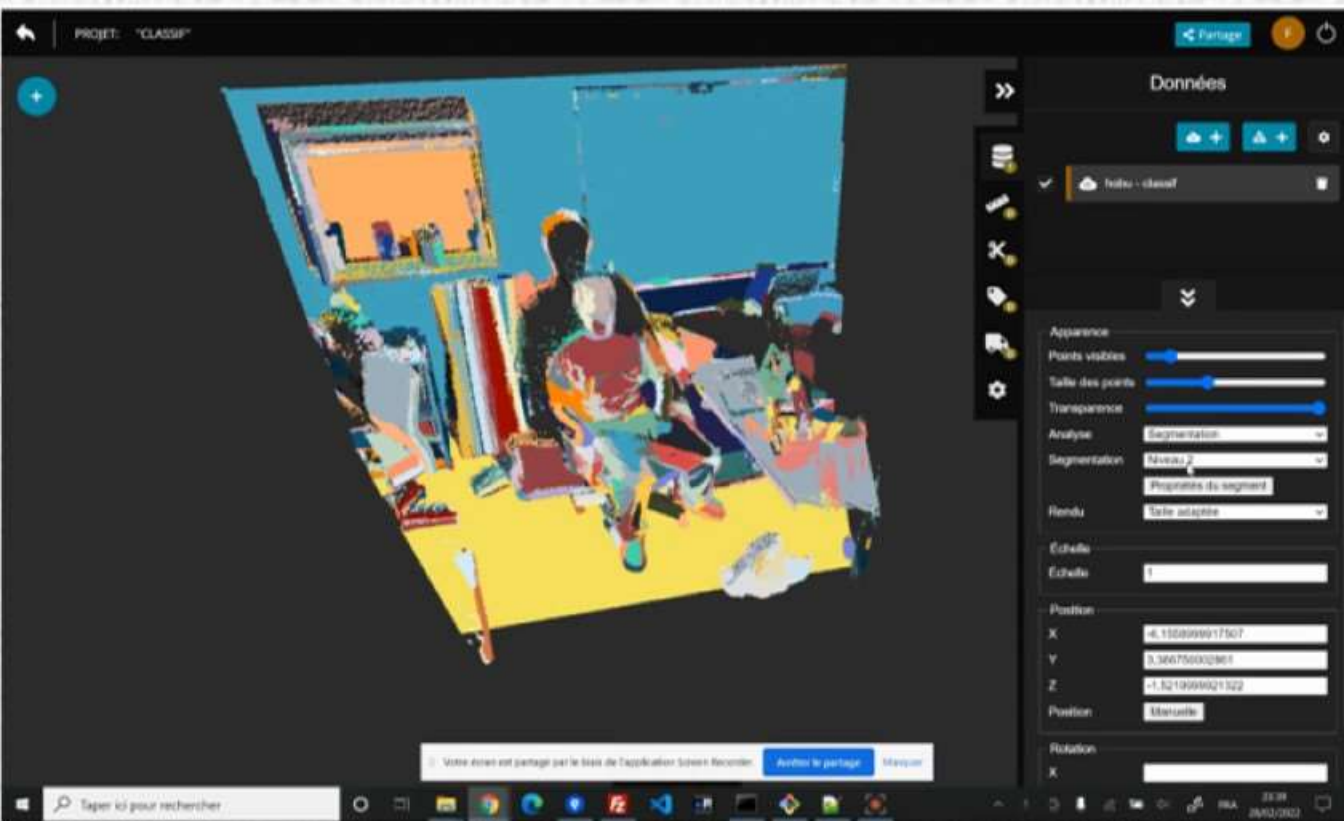
[Machine Learning Generalisation across Different 3D Architectural Heritage](#), Grilli et Remondino, 2020

# SL: Learned features



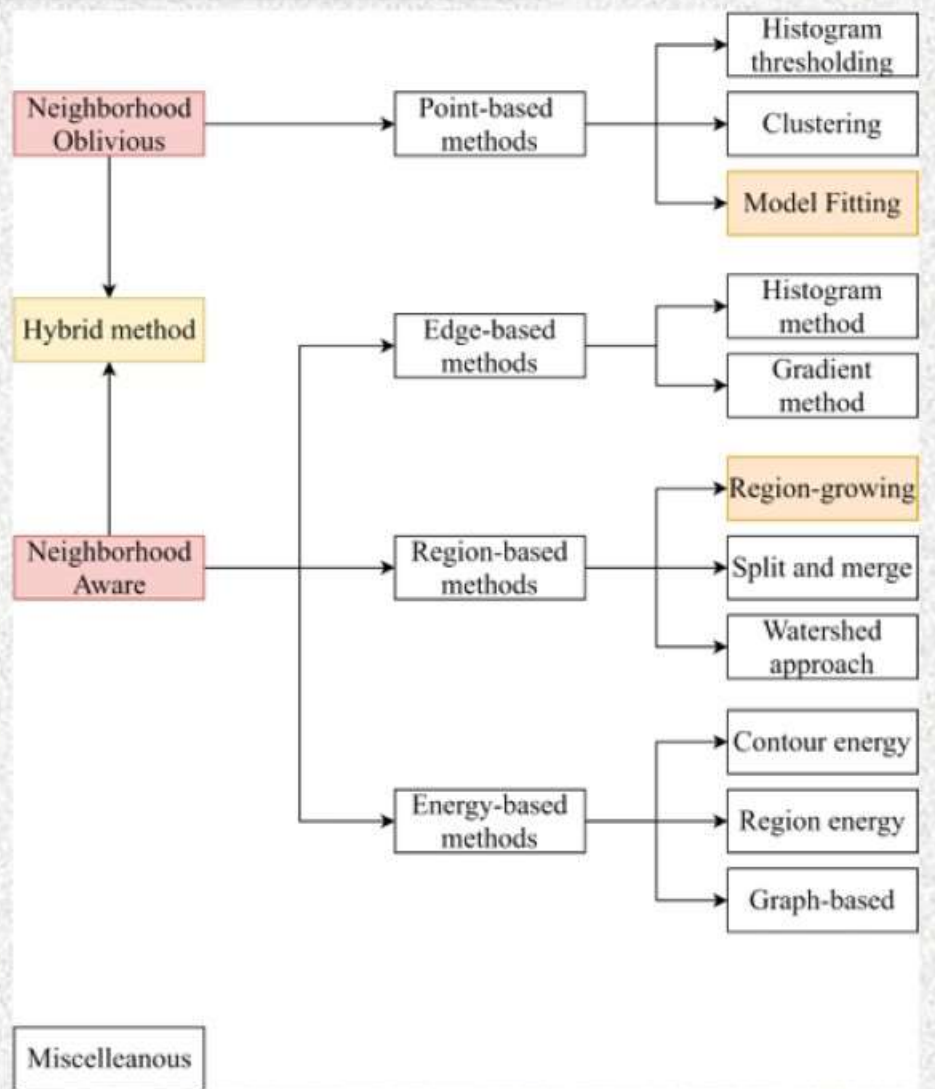
[Point Cloud Semantic Segmentation Using a Deep Learning Framework for Cultural Heritage](#), Pierdicca et al., 2020

# Weakly supervised



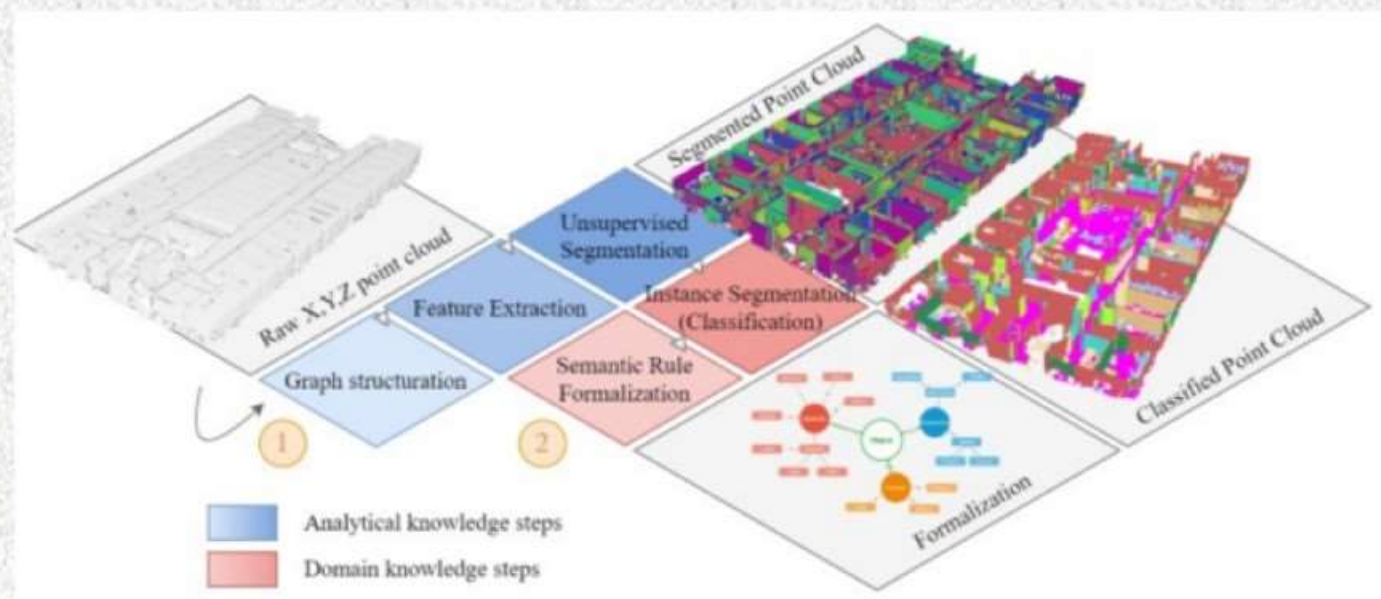
[One Thing One Click: A Self-Training Approach for Weakly Supervised 3D Semantic Segmentation](#), Liu et al., 2021

# Unsupervised segmentation



Unsupervised Point Cloud Segmentation for large point clouds, Poux et al., in press

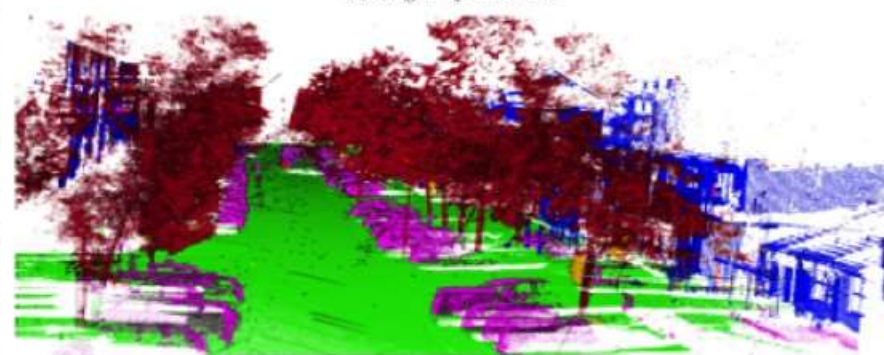
# Self-supervised learning



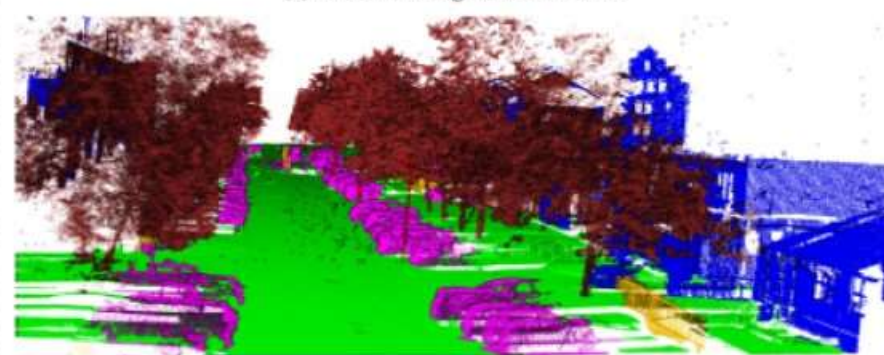
[SELF-LEARNING ONTOLOGY FOR INSTANCE SEGMENTATION OF 3D INDOOR POINT CLOUD](#), Poux et Ponciano, 2020



(a) Original point cloud



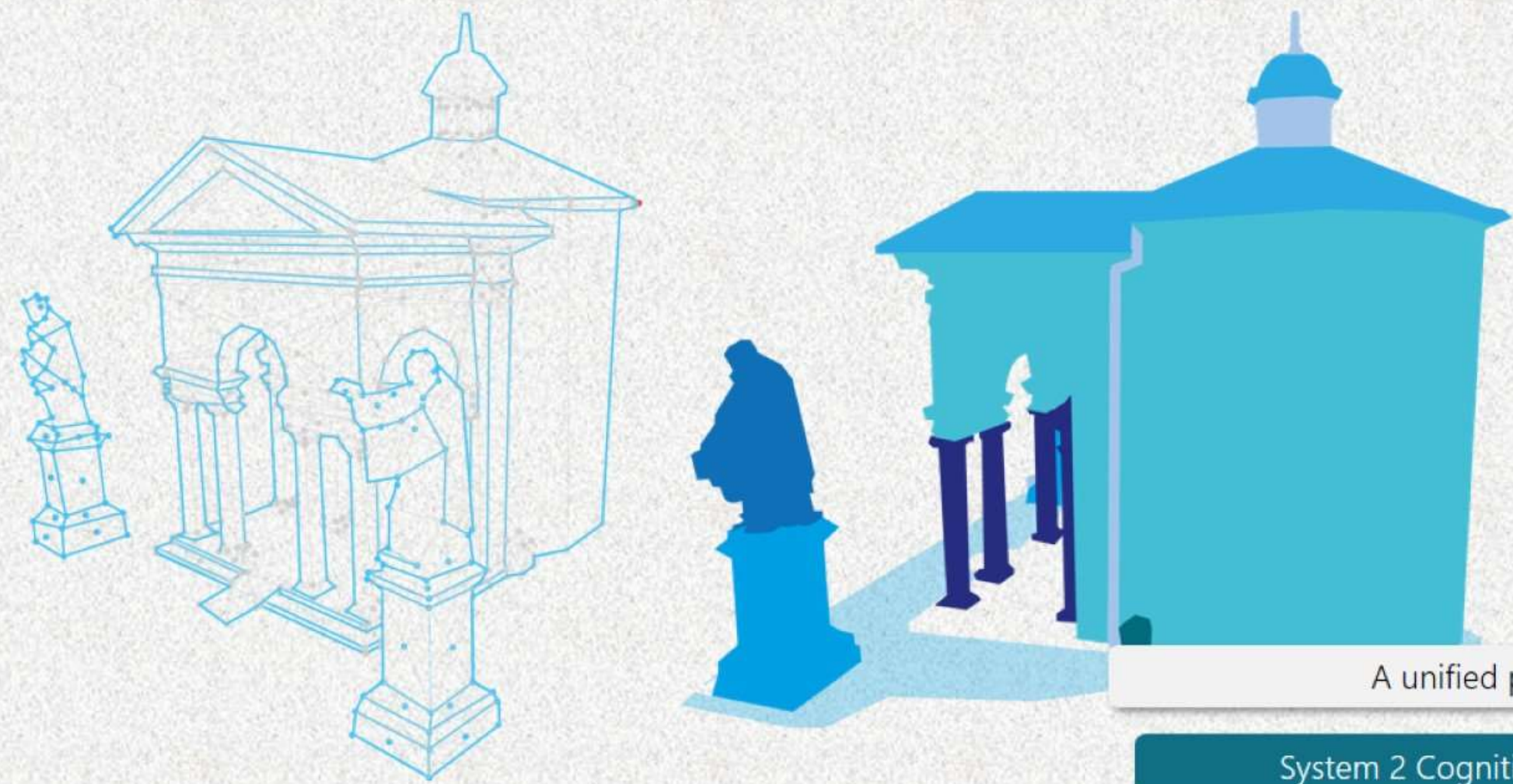
(b) DL semantic segmentation results



(c) KB semantic segmentation results

[Object Semantic Segmentation in Point Clouds— Comparison of a Deep Learning and a Knowledge-Based Method](#), Ponciano et al., 2021

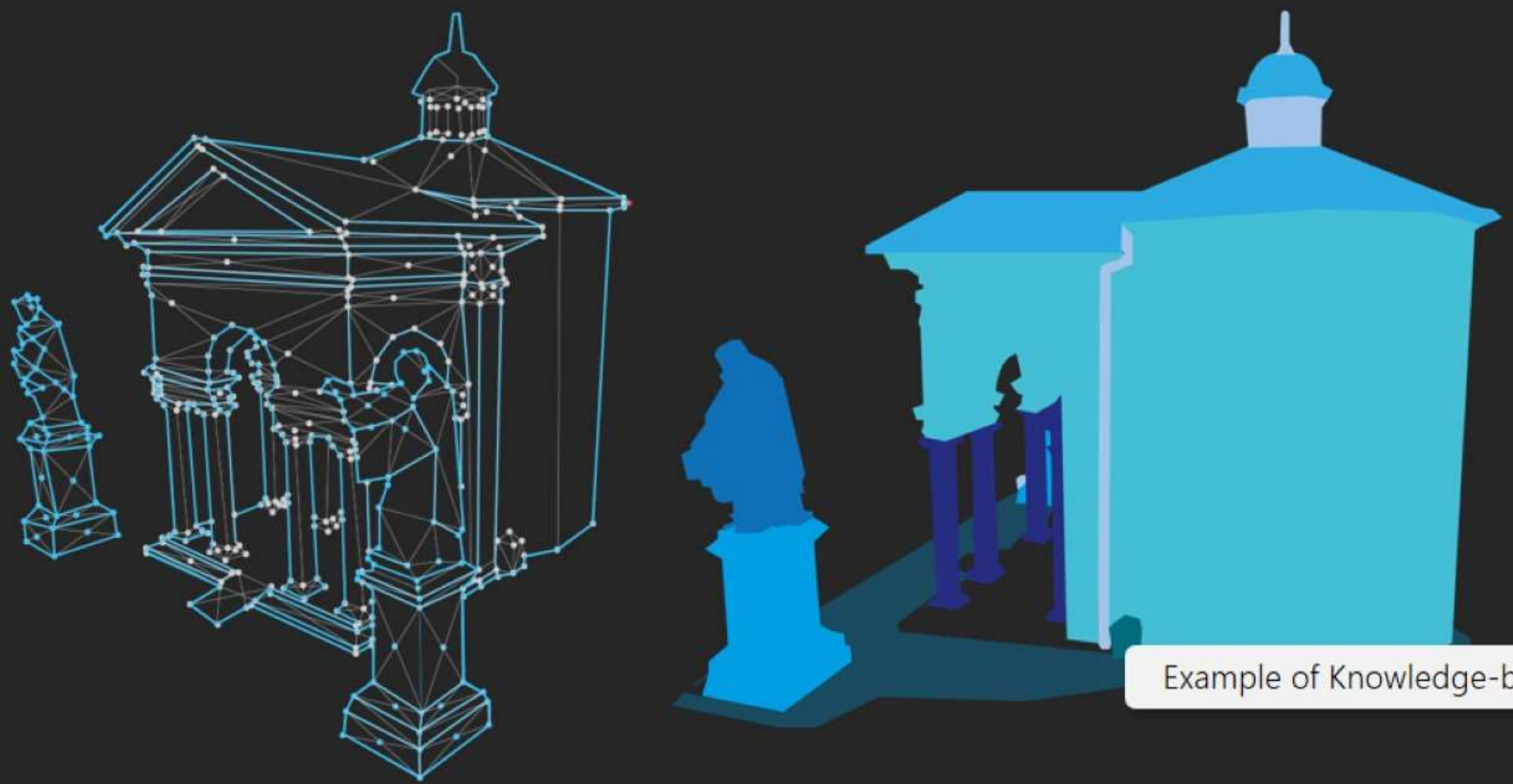
### 3. Can we address widely different applications and concepts?



A unified processing? ❌

System 2 Cognition Research 💡

# 4. Can we generalize our ARCH-approaches?



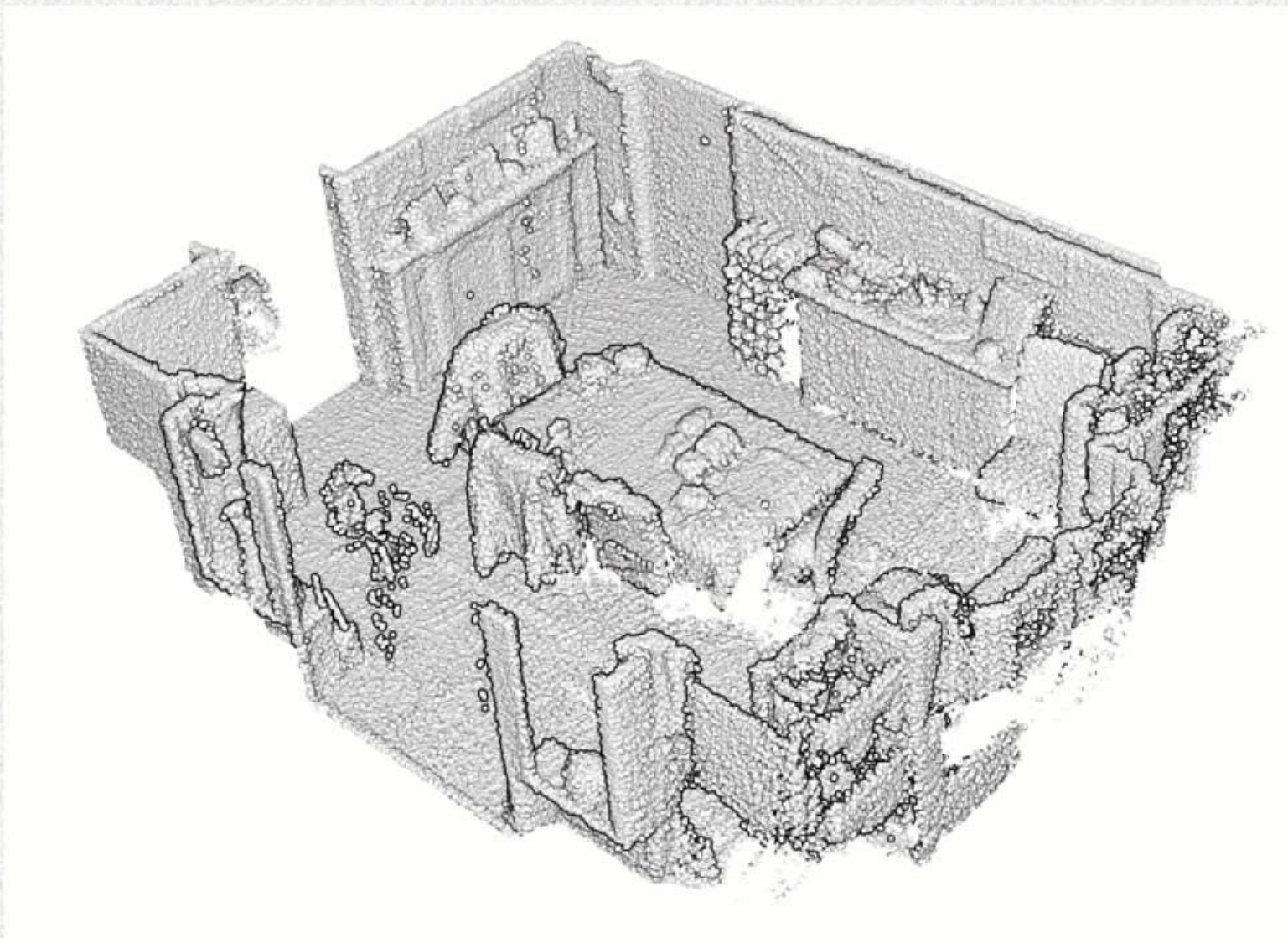
Example of Knowledge-based learning

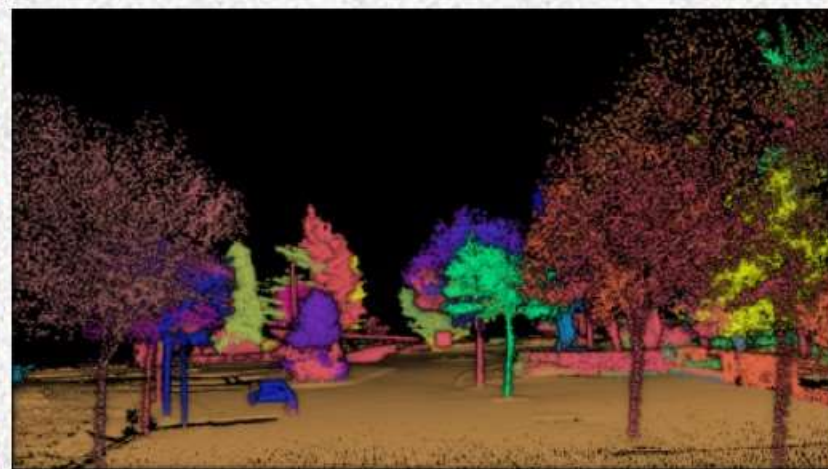
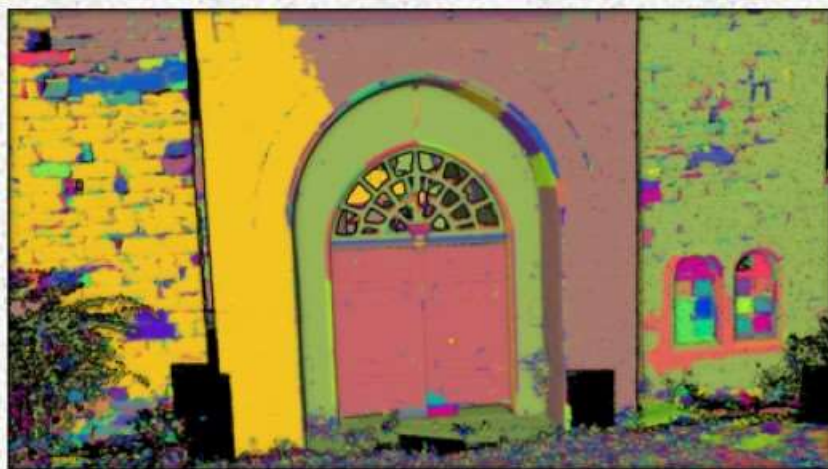
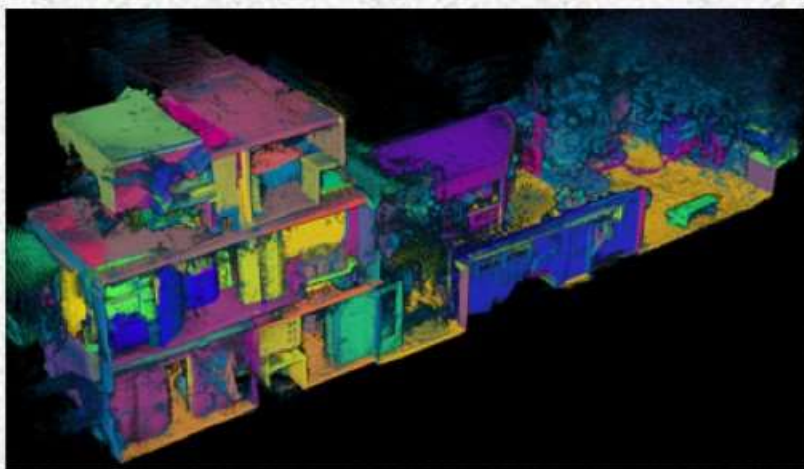


## Labelling datasets

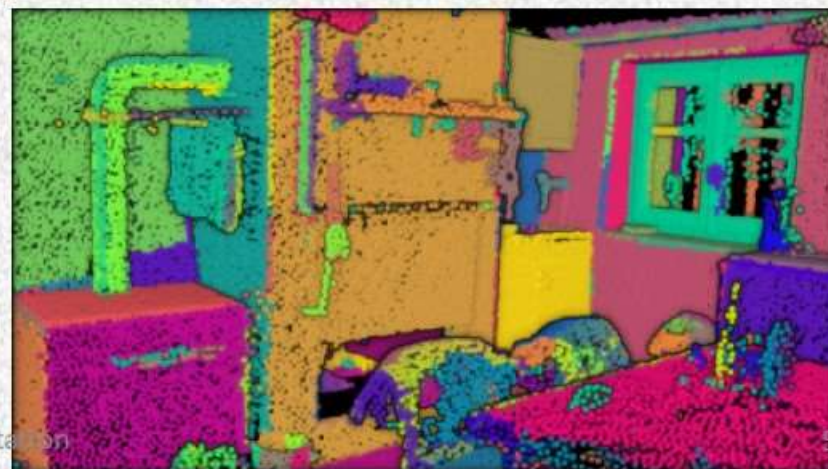
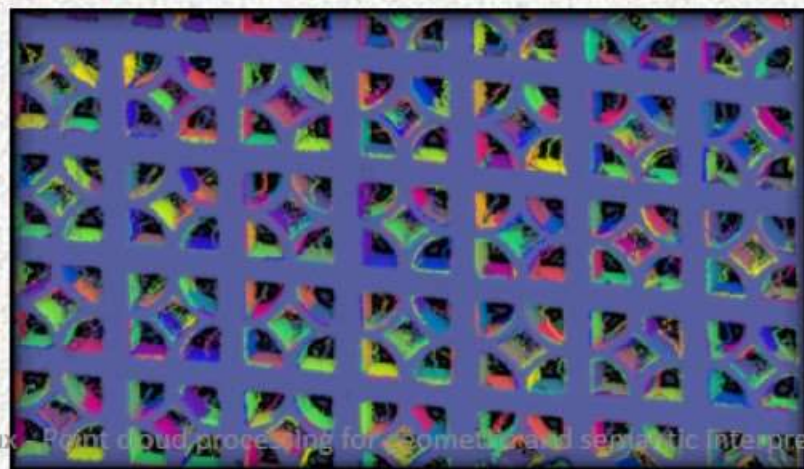


## Unsupervised direction



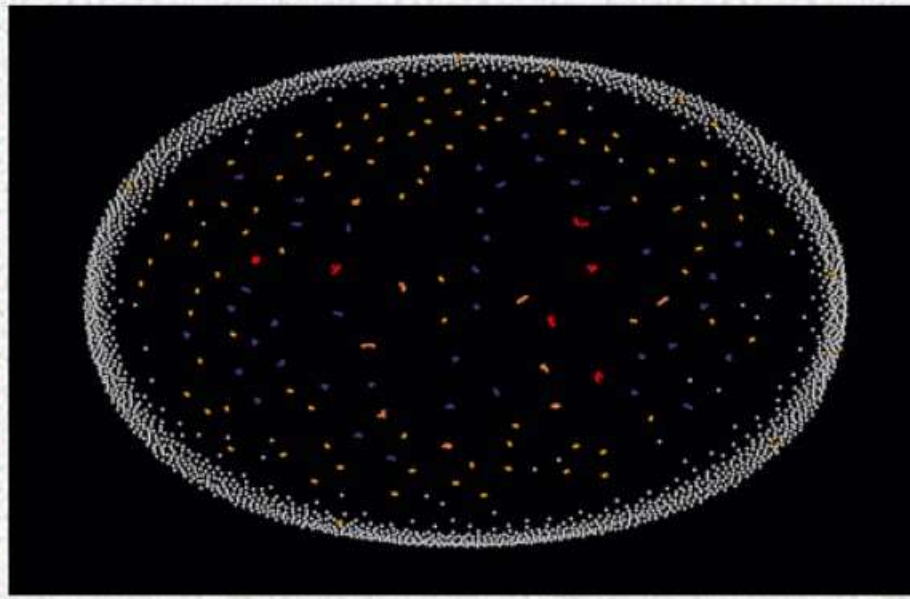
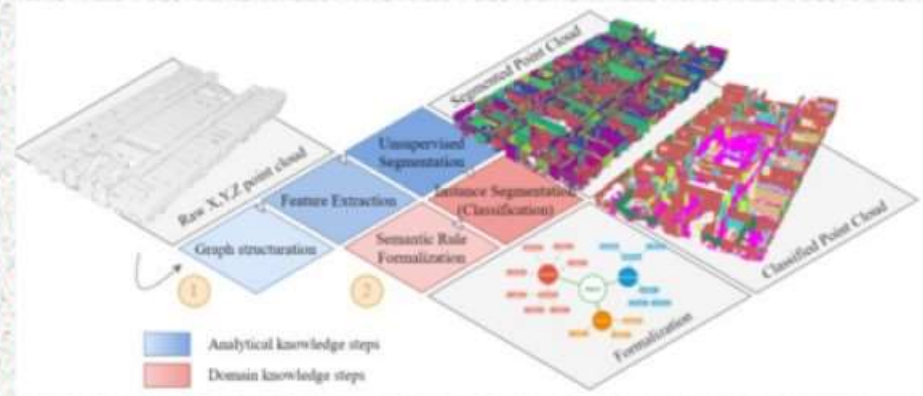
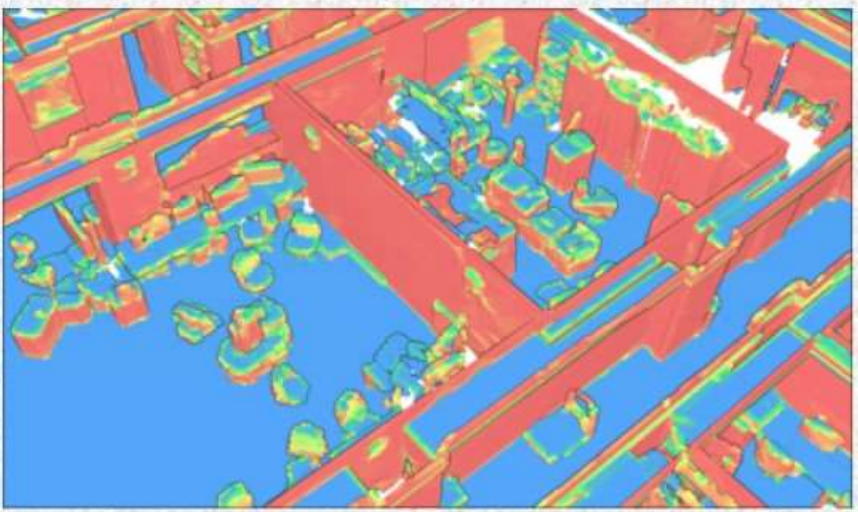
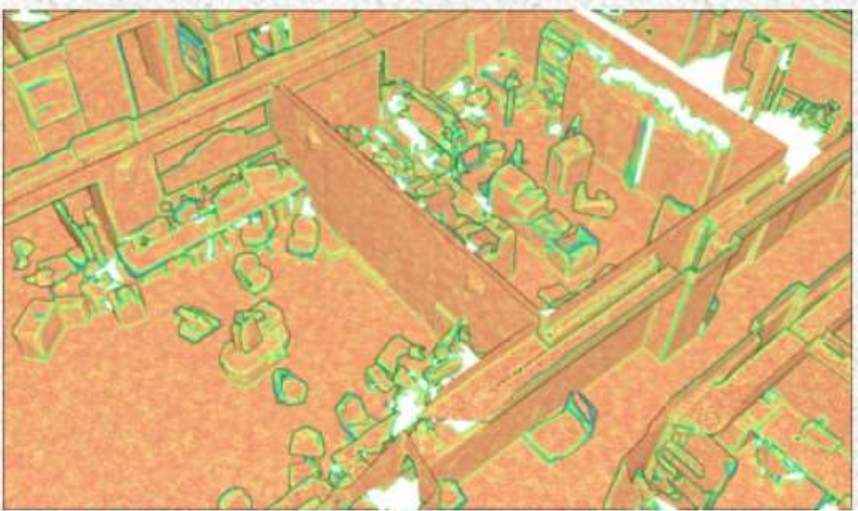
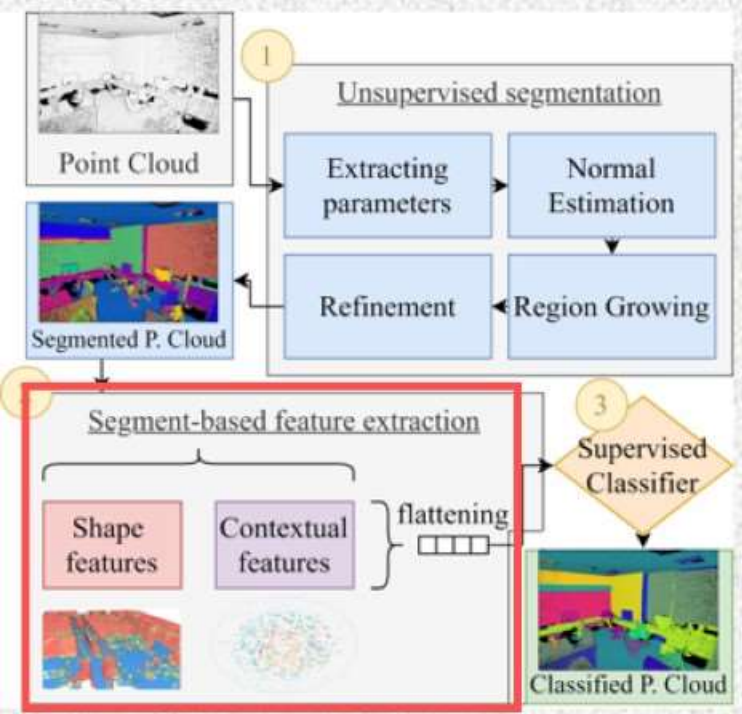


# Segmentation (unsupervised)



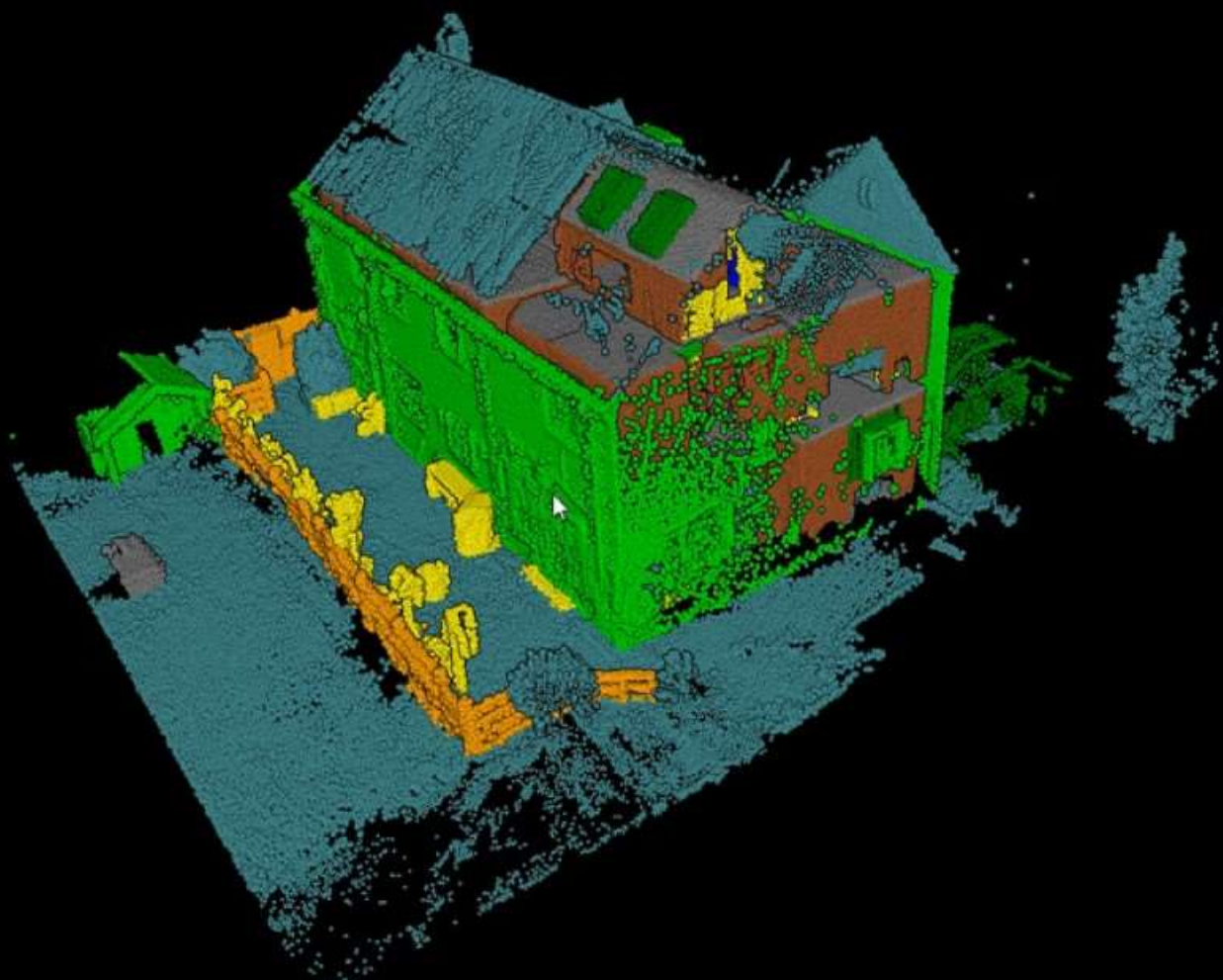
# S-based feature extraction

## SELF-LEARNING ONTOLOGY FOR INSTANCE SEGMENTATION OF 3D INDOOR POINT CLOUD, Poux et Ponciano, 2020



## UNSUPERVISED OBJECT-BASED CLUSTERING IN SUPPORT OF SUPERVISED POINT-BASED 3D POINT CLOUD CLASSIFICATION, Grilli et al., 2021

Geometry, Semantics



Double right-click to select a point.

Activate selection mode :

OFF

MULTIPLE SELECTION

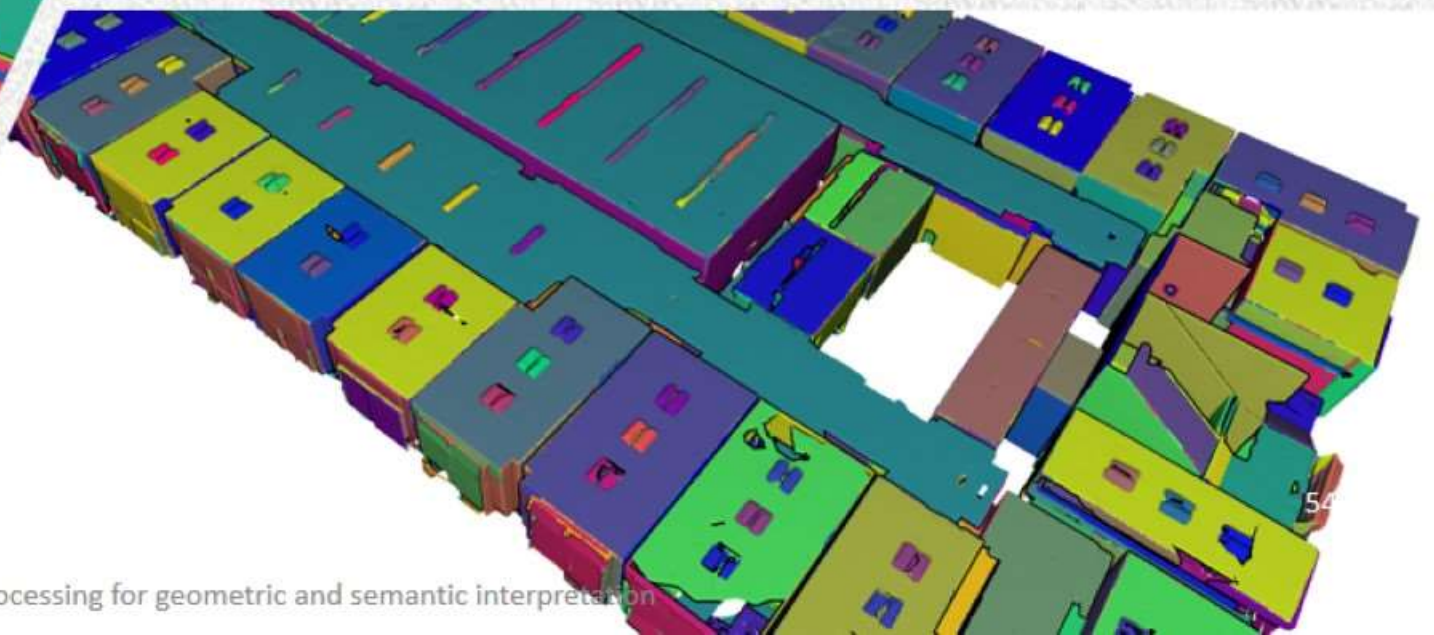
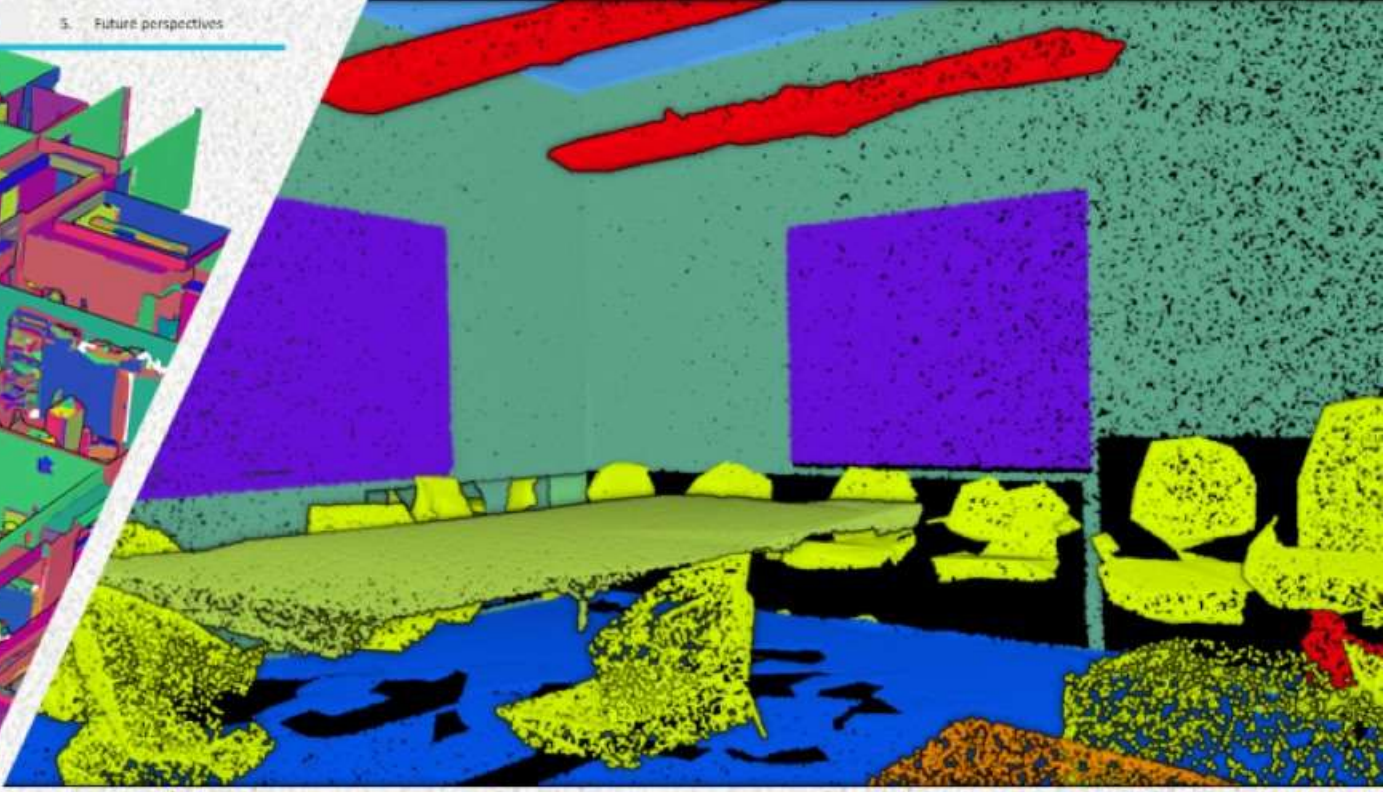
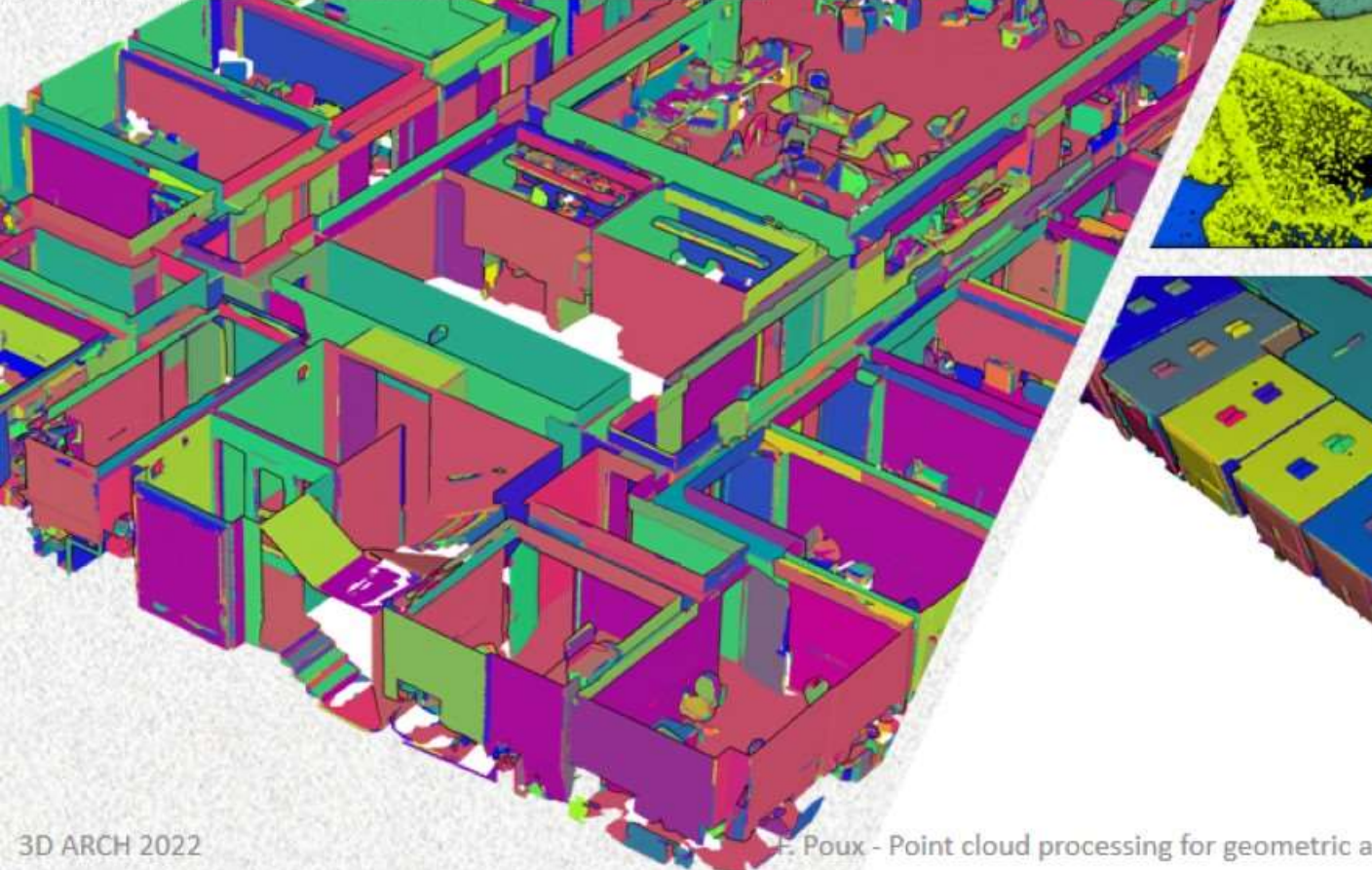
VALIDATE

Query Form

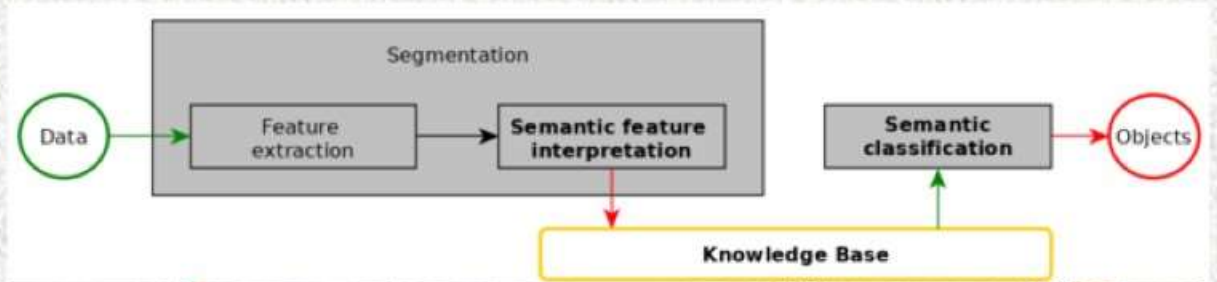
(c) Florent POUX - Smart Point Cloud - BUILD PRE-ALPHA

F. Poux - Point cloud processing for geometric and semantic interpretation

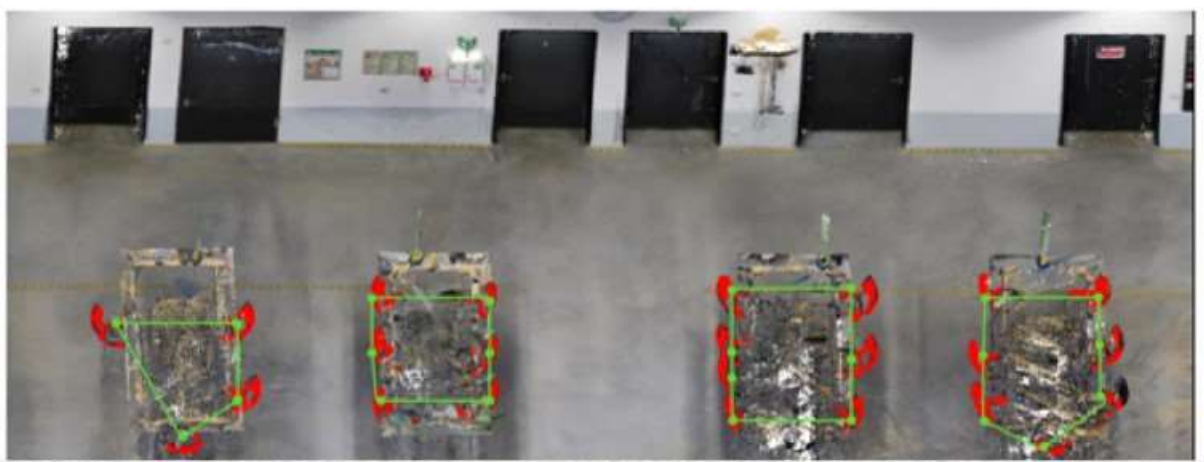
S+Instance segmentation



# Introducing the context

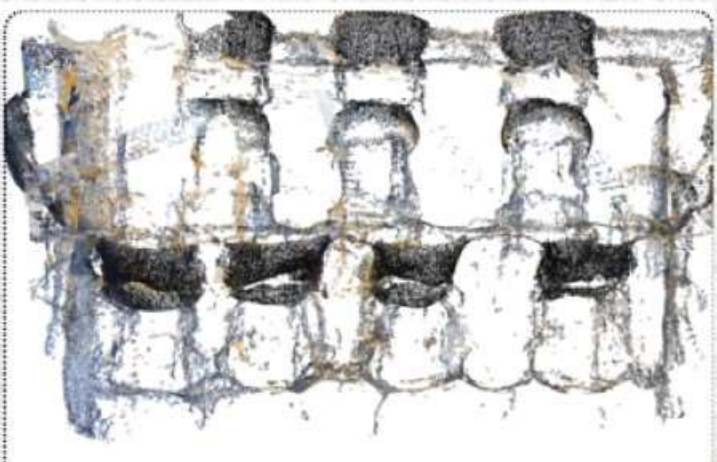


(a) Results of chairs detection in red.



Circular shape

Large room context

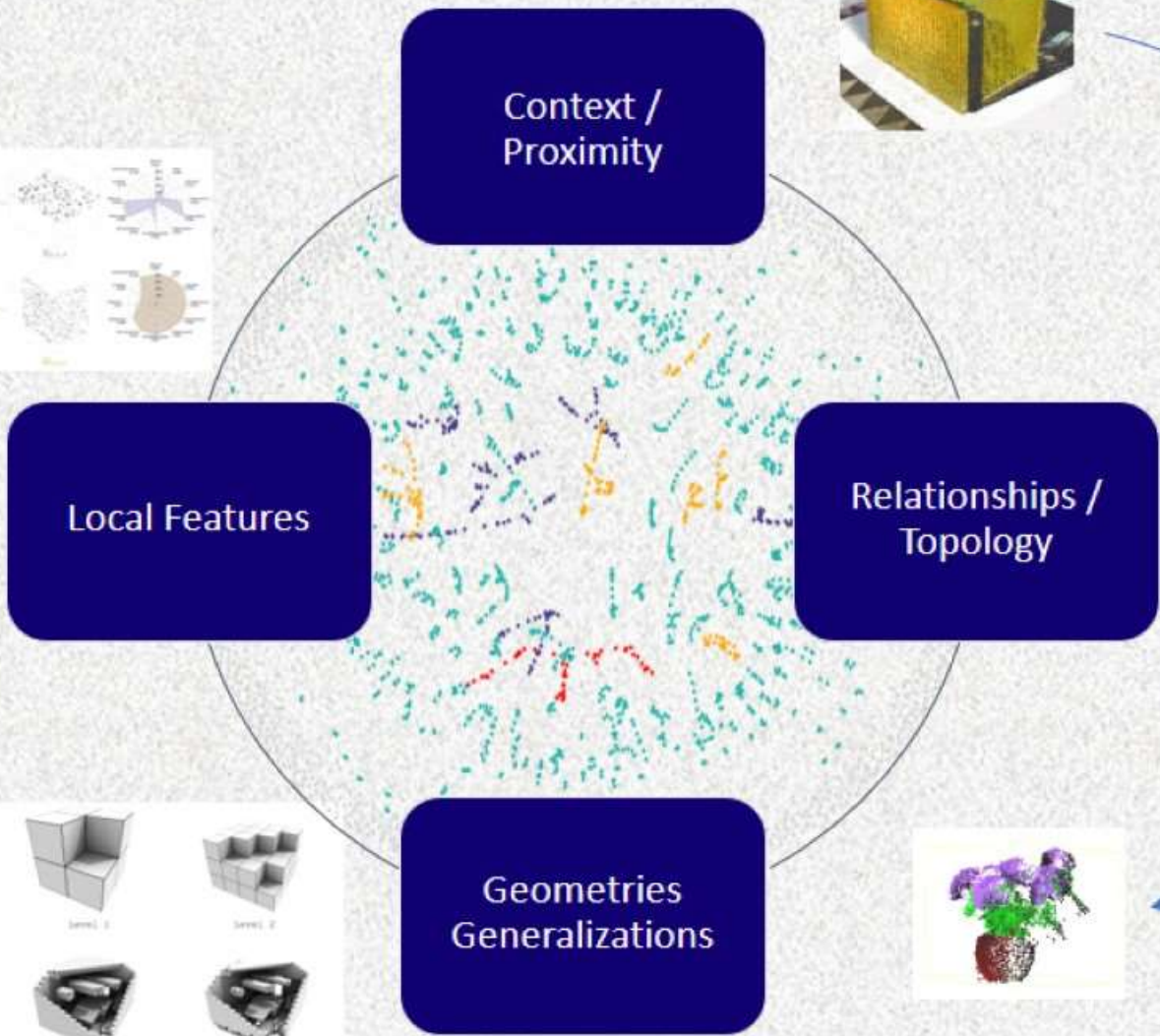
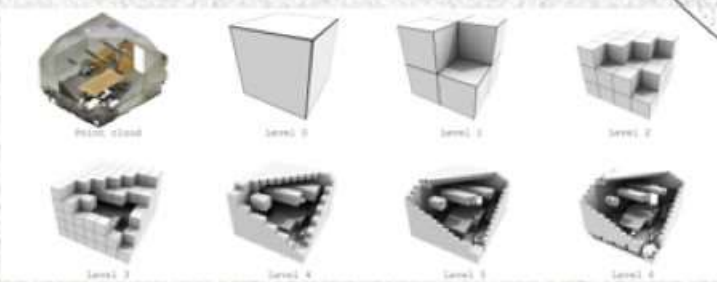
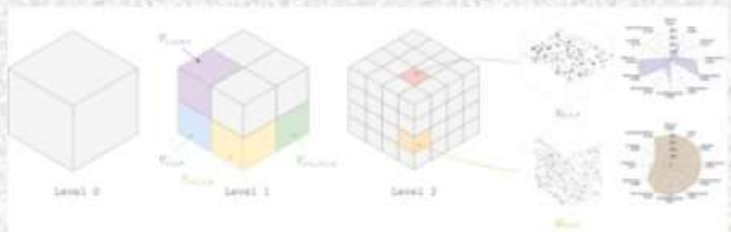


Rectangular shape

Work room context

Source: Ranciano et al., 2020

Knowledge-Driven



Isolation



Relation « host/guest »

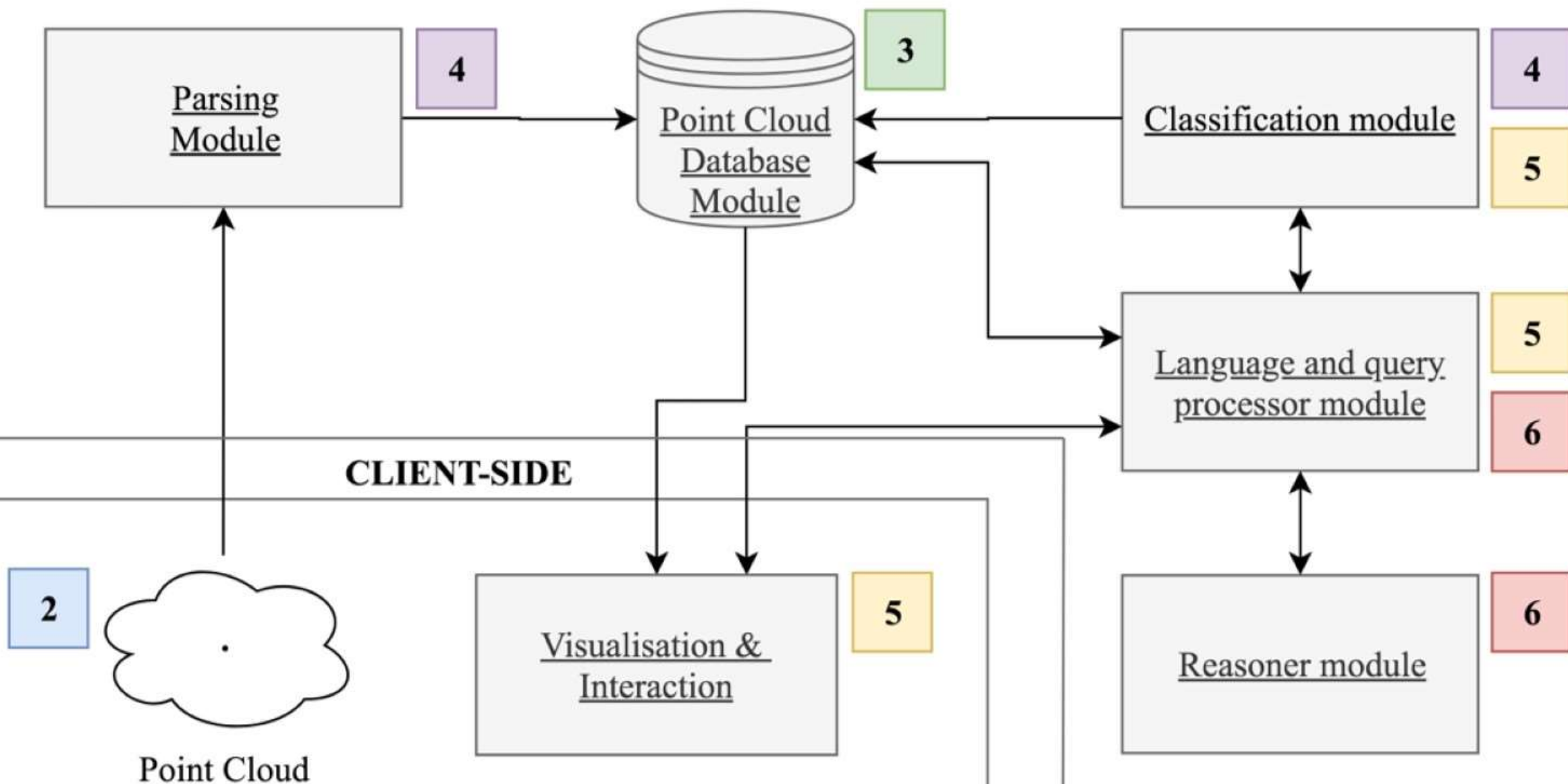


Extract





Poux et Billen, A Smart Point Cloud Infrastructure for intelligent environments, 2019



Acquisition

Pre-processing

Registration

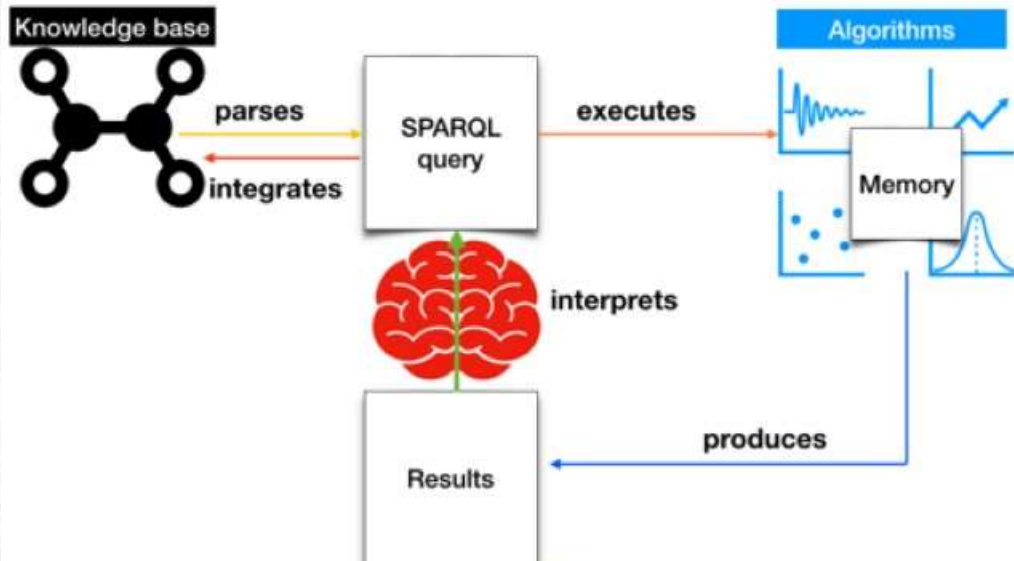
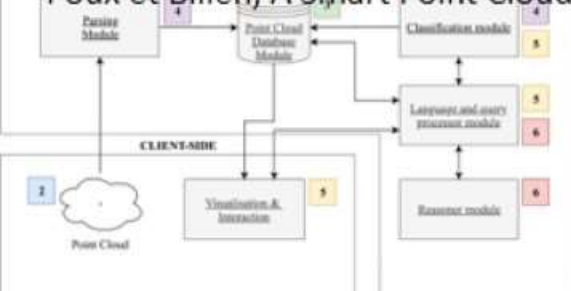
Segmentation

Classification

Structuration

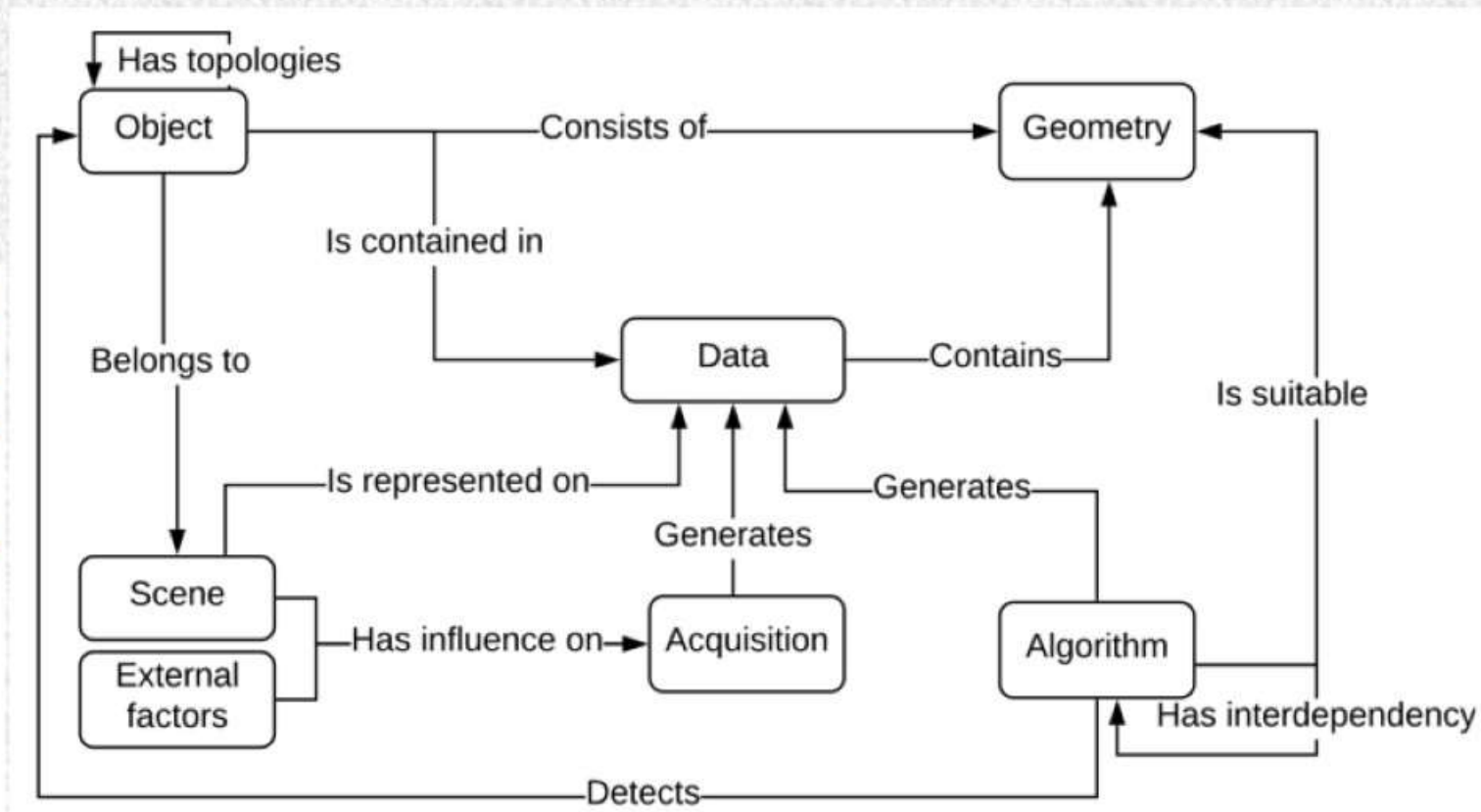
Application

Poux et Billen, A Smart Point Cloud Infrastructure for intelligent environments, 2019

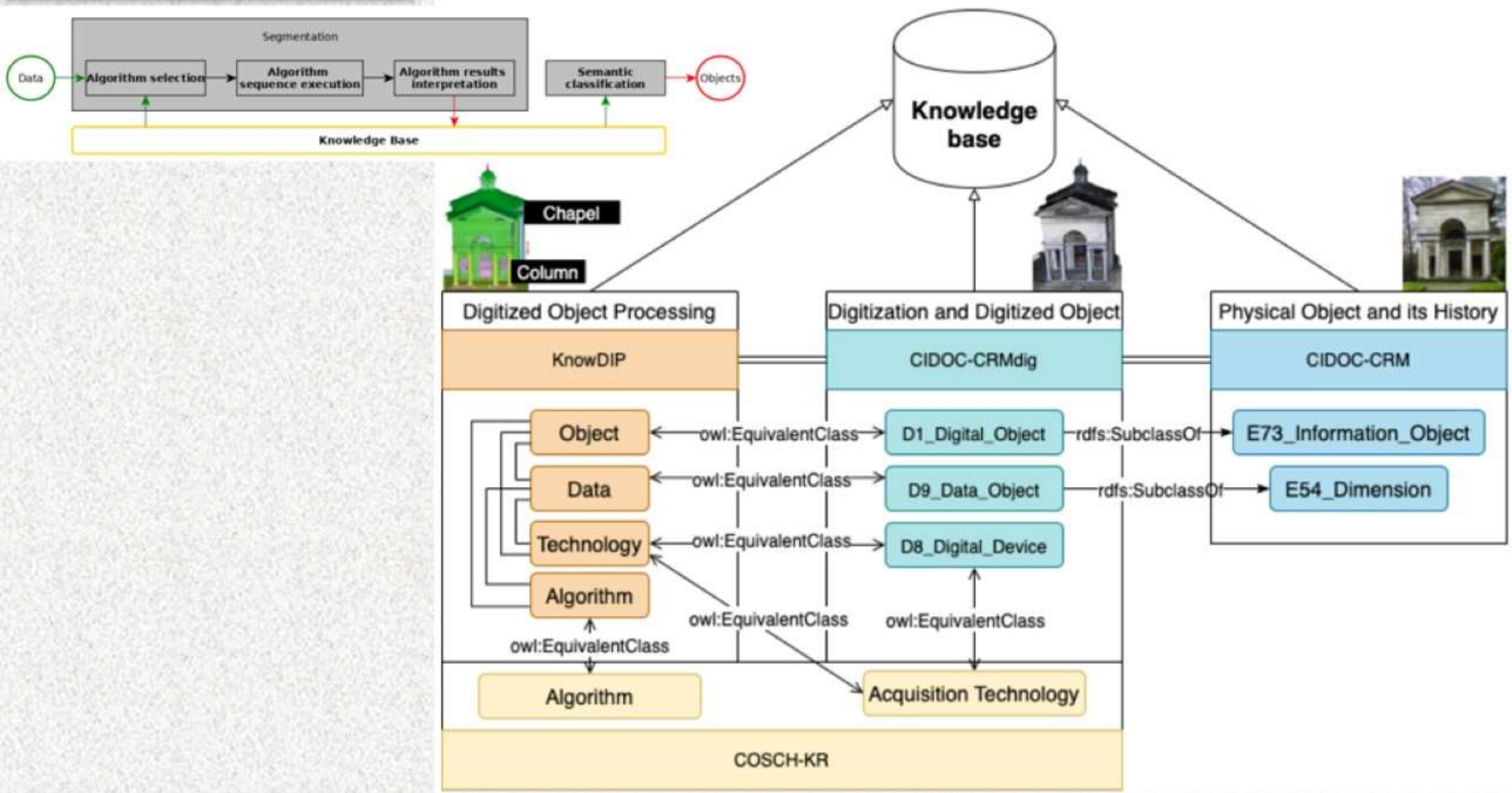


Object Detection in unstructured 3D data sets using explicit semantics, Ponciano, 2019

Poux & Ponciano, 2020

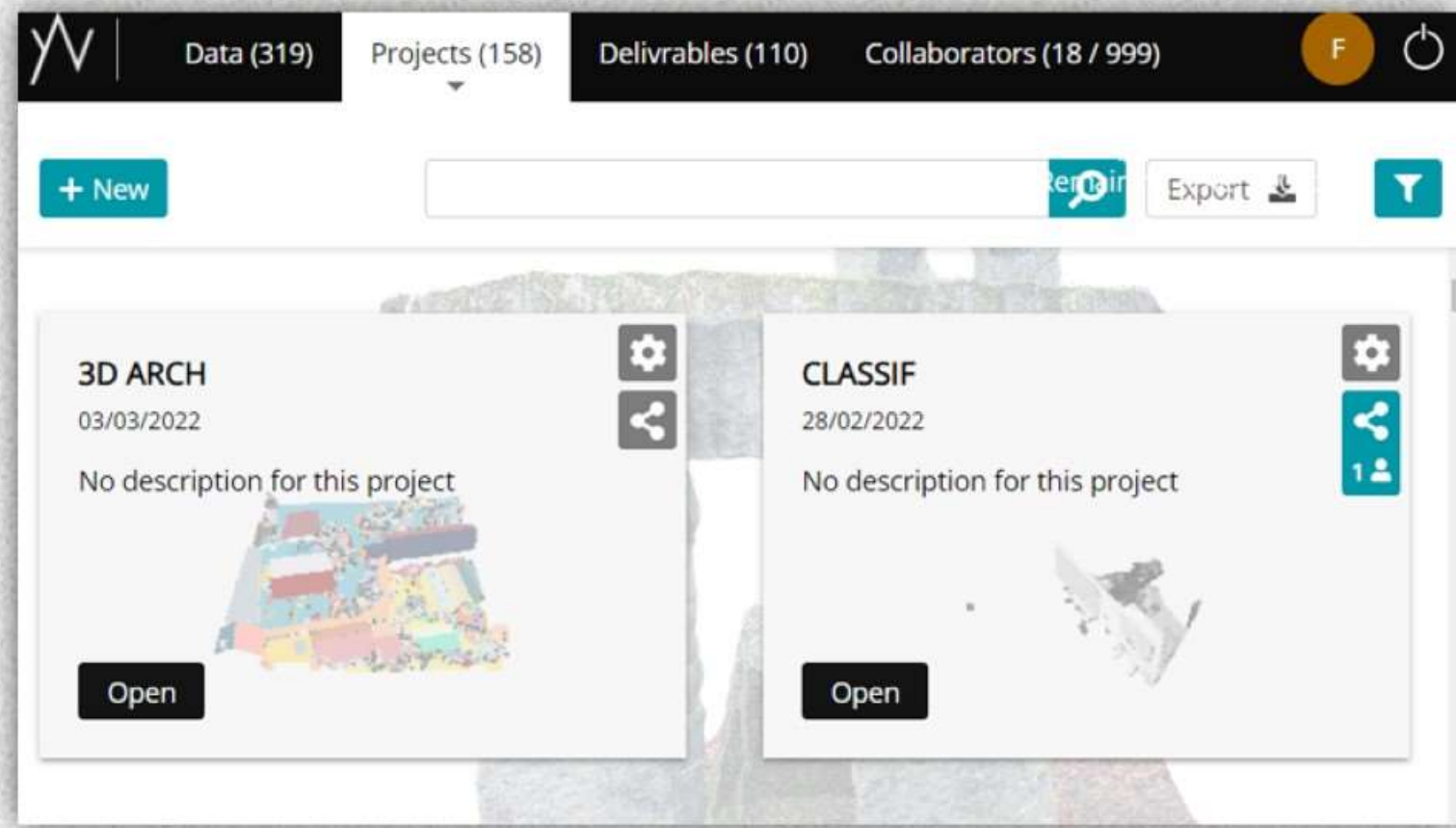


# KB in Cultural Heritage

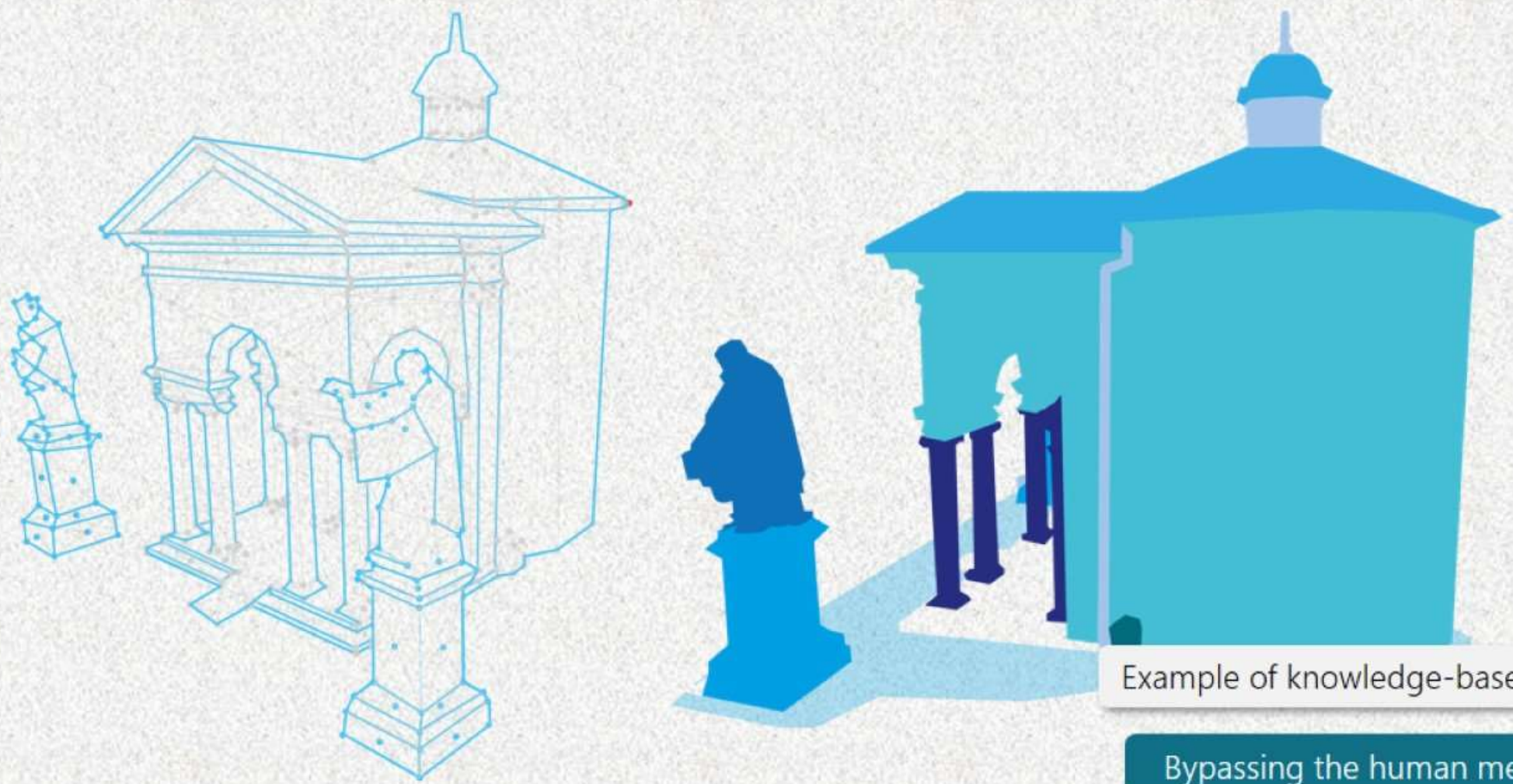


From Acquisition to Presentation—The Potential of Semantics to Support the Safeguard of Cultural Heritage, Ponciano et al., 2021

# Towards innovation



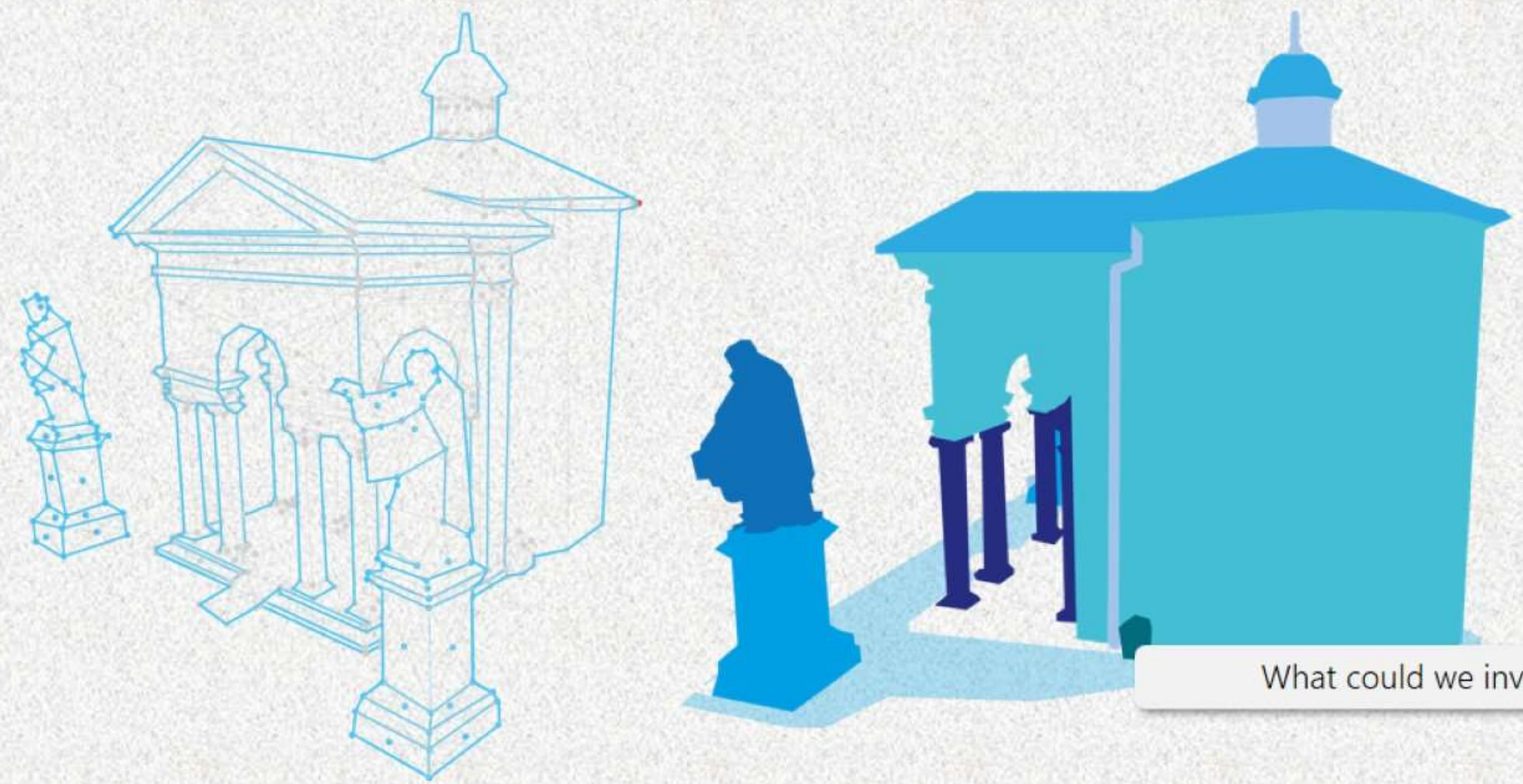
# 4. Can we generalize our ARCH-approaches?



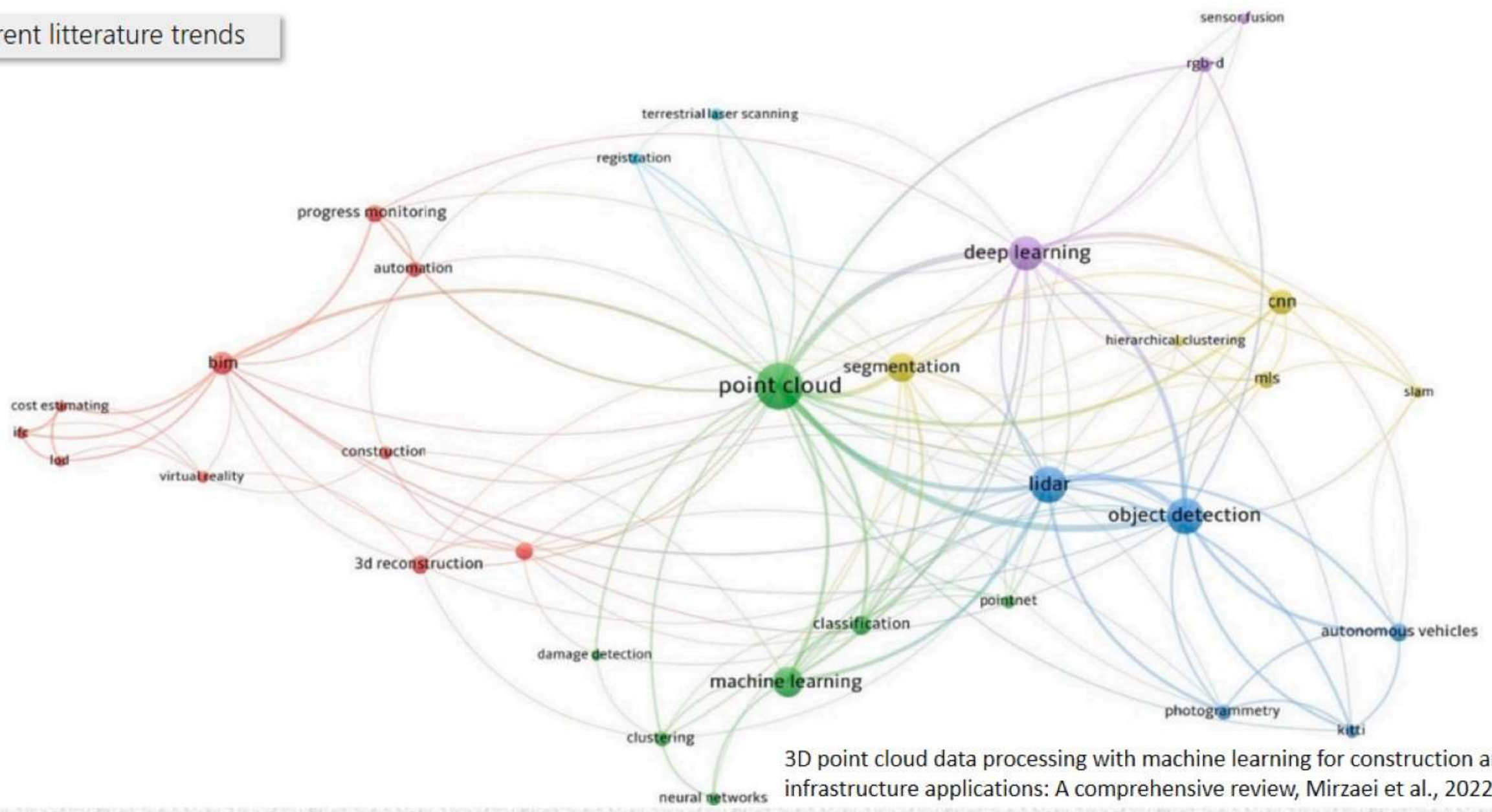
Example of knowledge-based learning ✓

Bypassing the human memory limits +

## 5. Perspectives



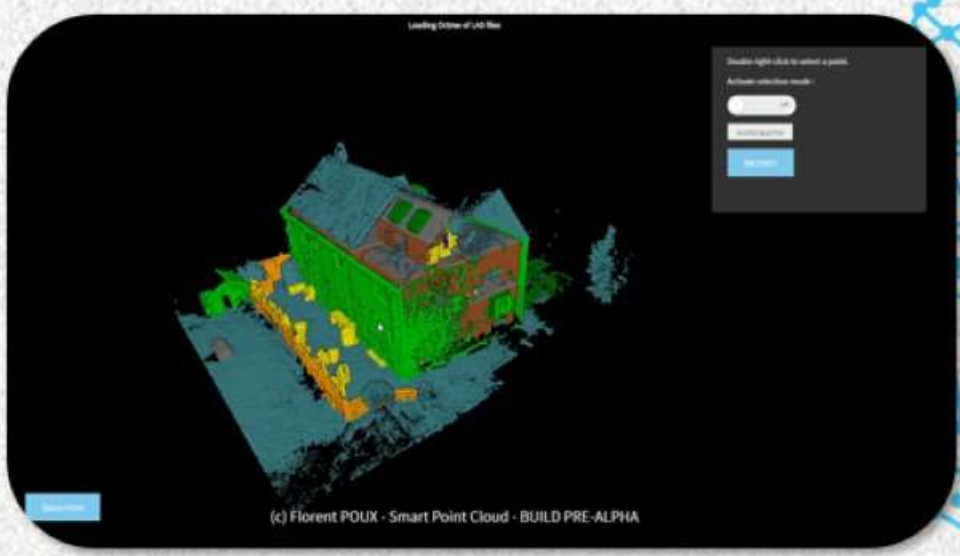
# Current literature trends



3D point cloud data processing with machine learning for construction and infrastructure applications: A comprehensive review, Mirzaei et al., 2022

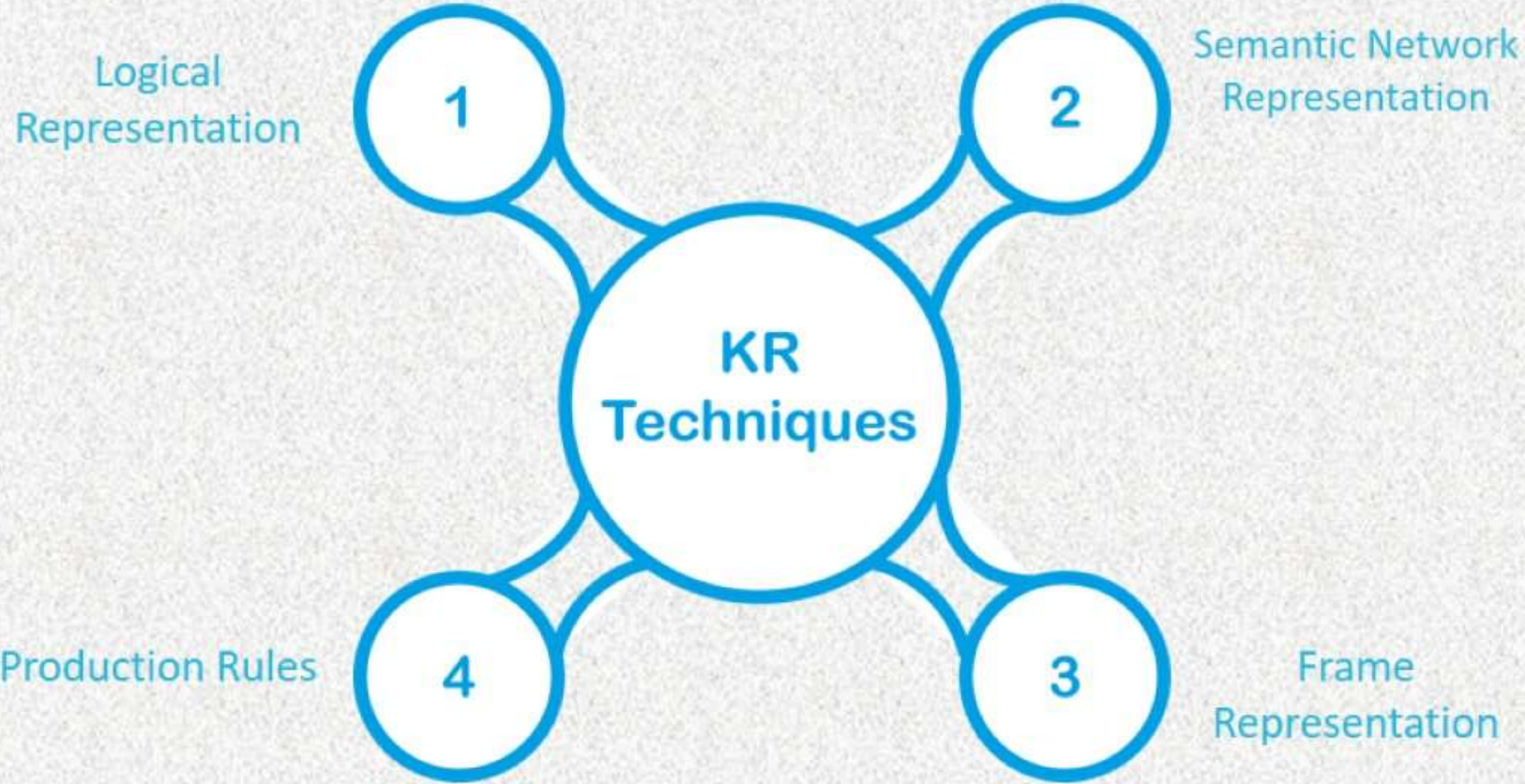
## First pass perspectives

- Define powerful SPC-based AI Agents
- Increase generalization / specialization
- Dynamic data and LoD management
- Enhance unsupervised segmentation
- Enhance classification

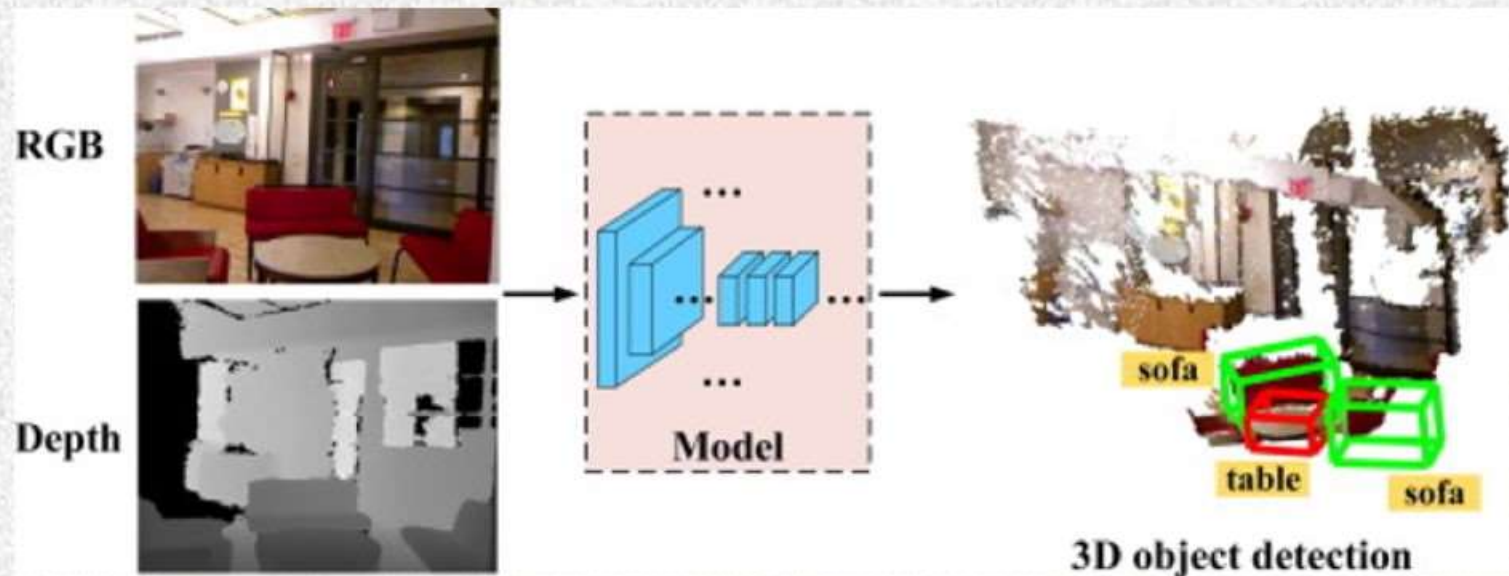




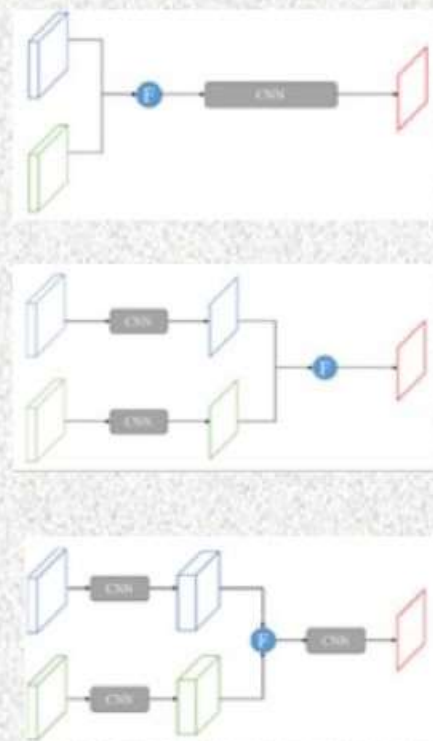
# Knowledge Representation



# Information fusion

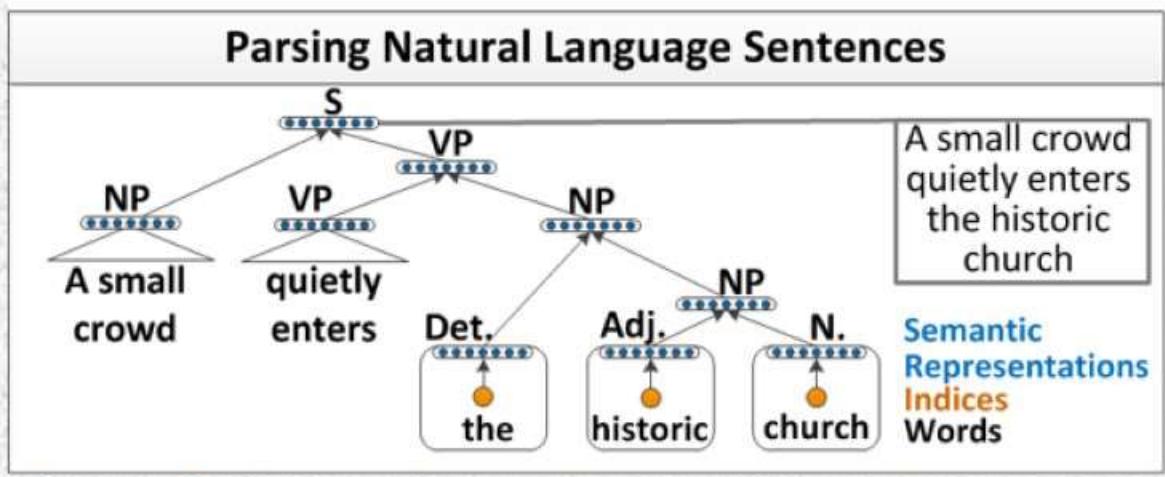
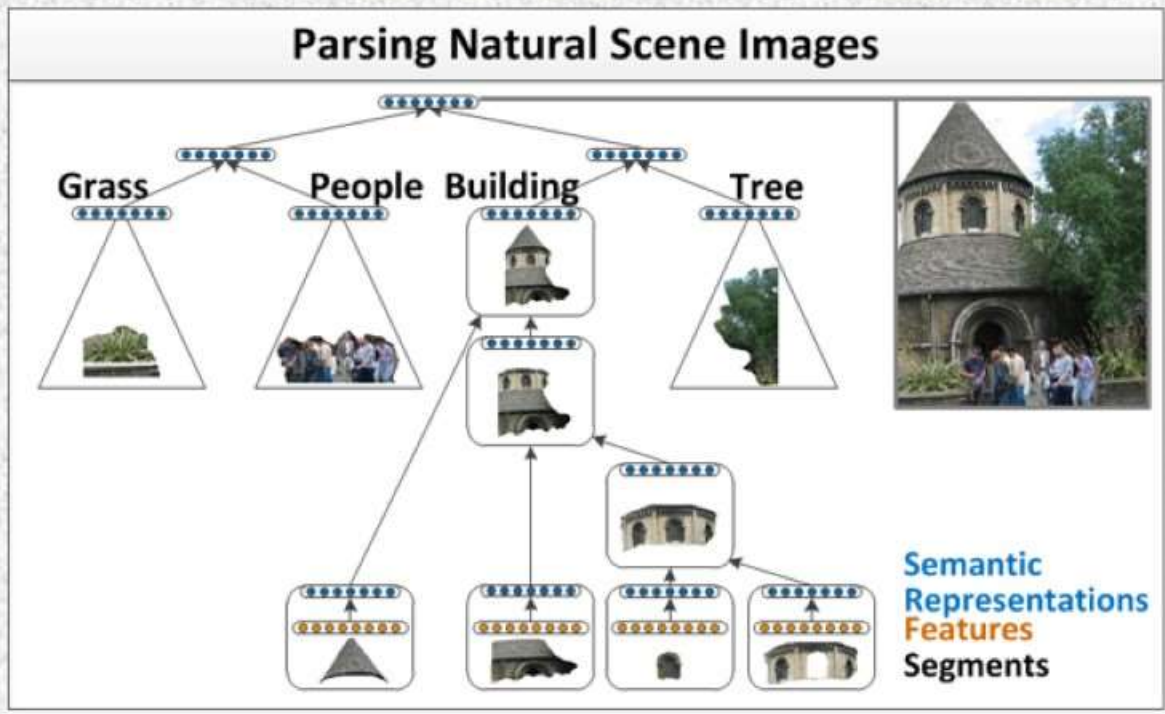


[A multilevel fusion network for 3D object detection](#), Xia et al., 2021



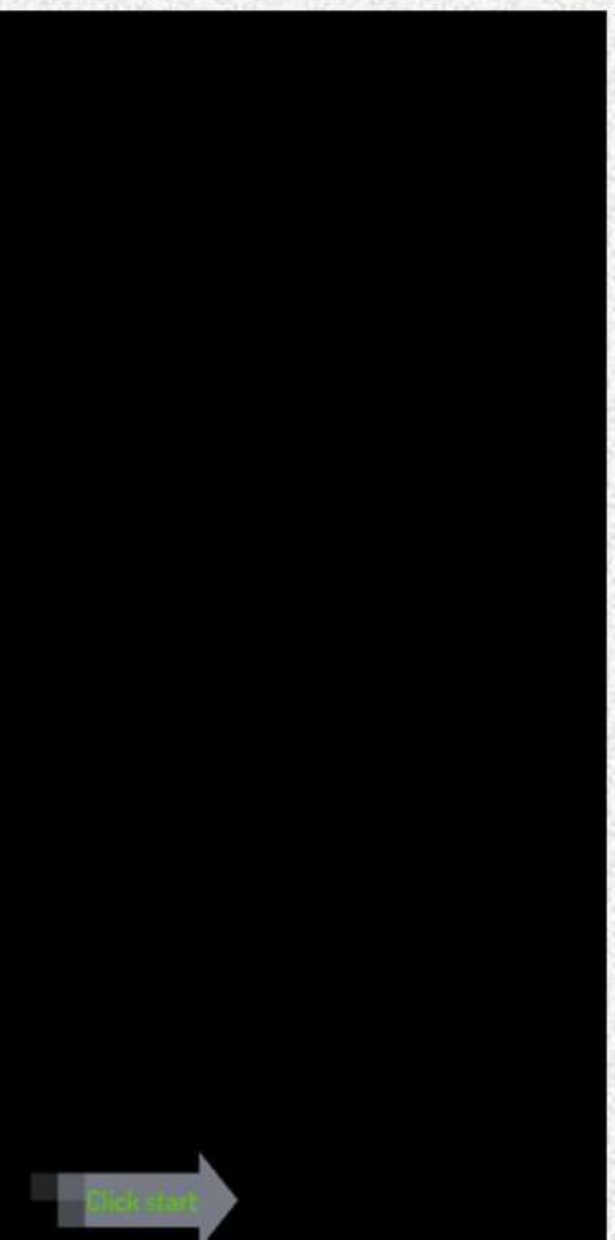
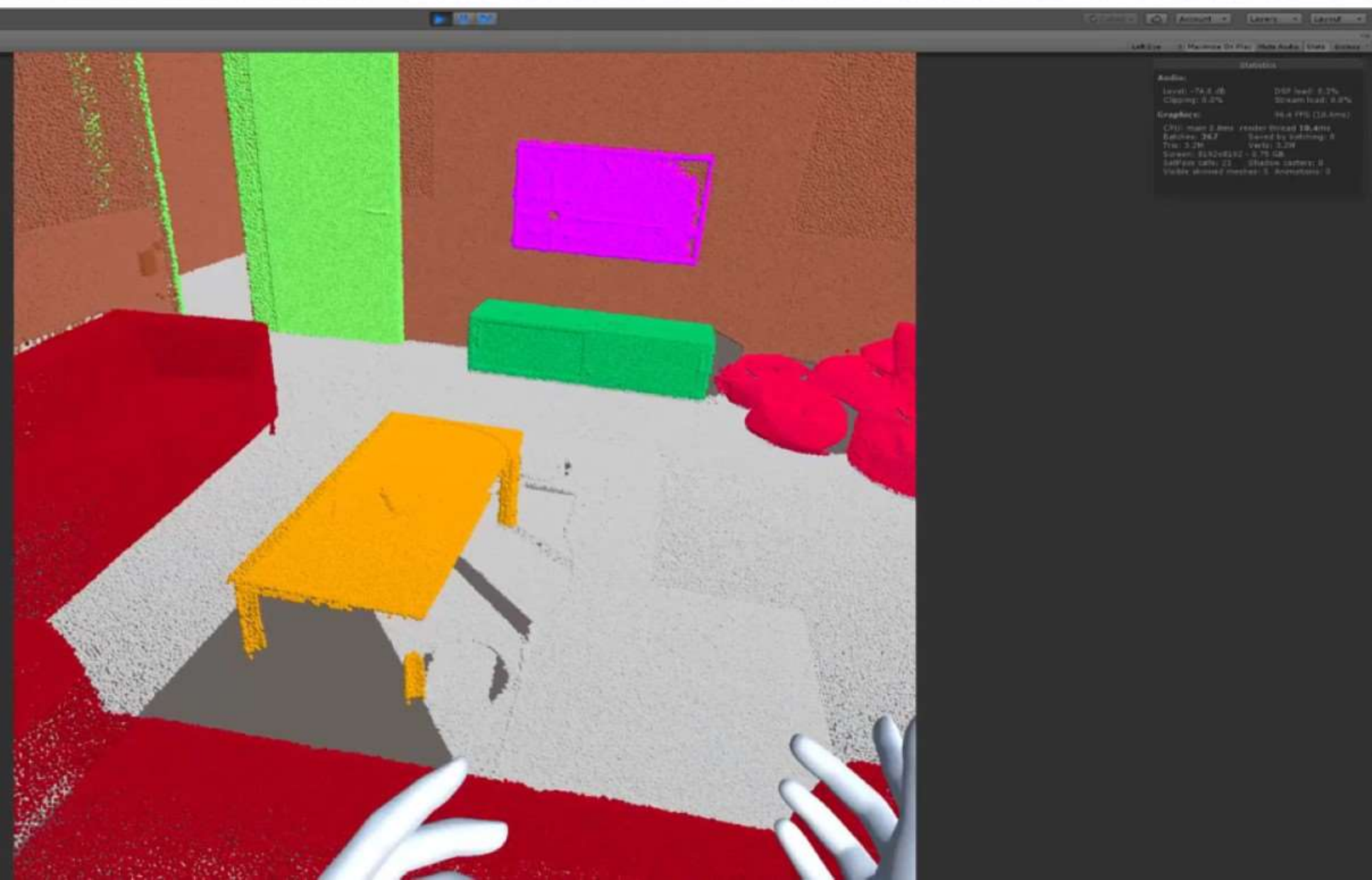
C. Maurice, Satellite photogrammetry for 3D tasks, 2022

Natural language processing

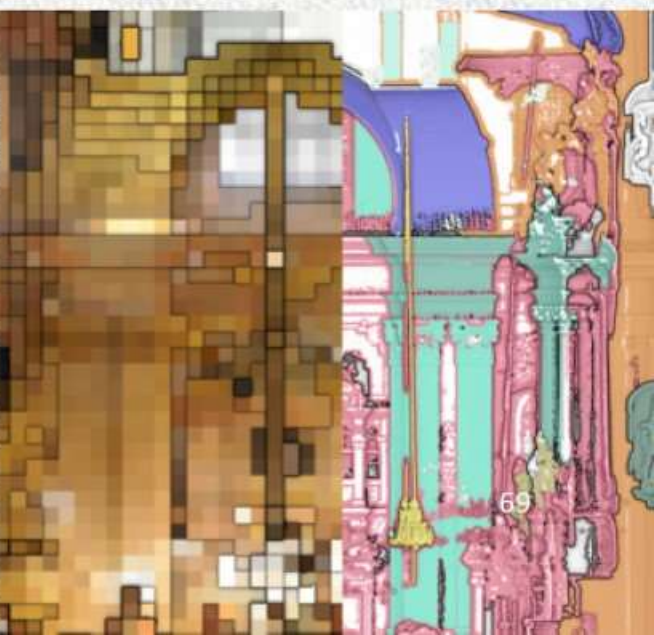
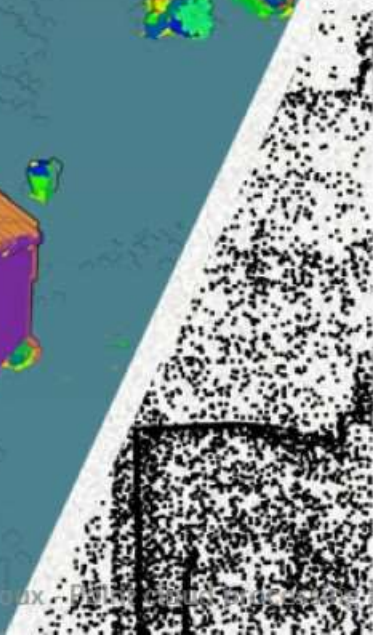
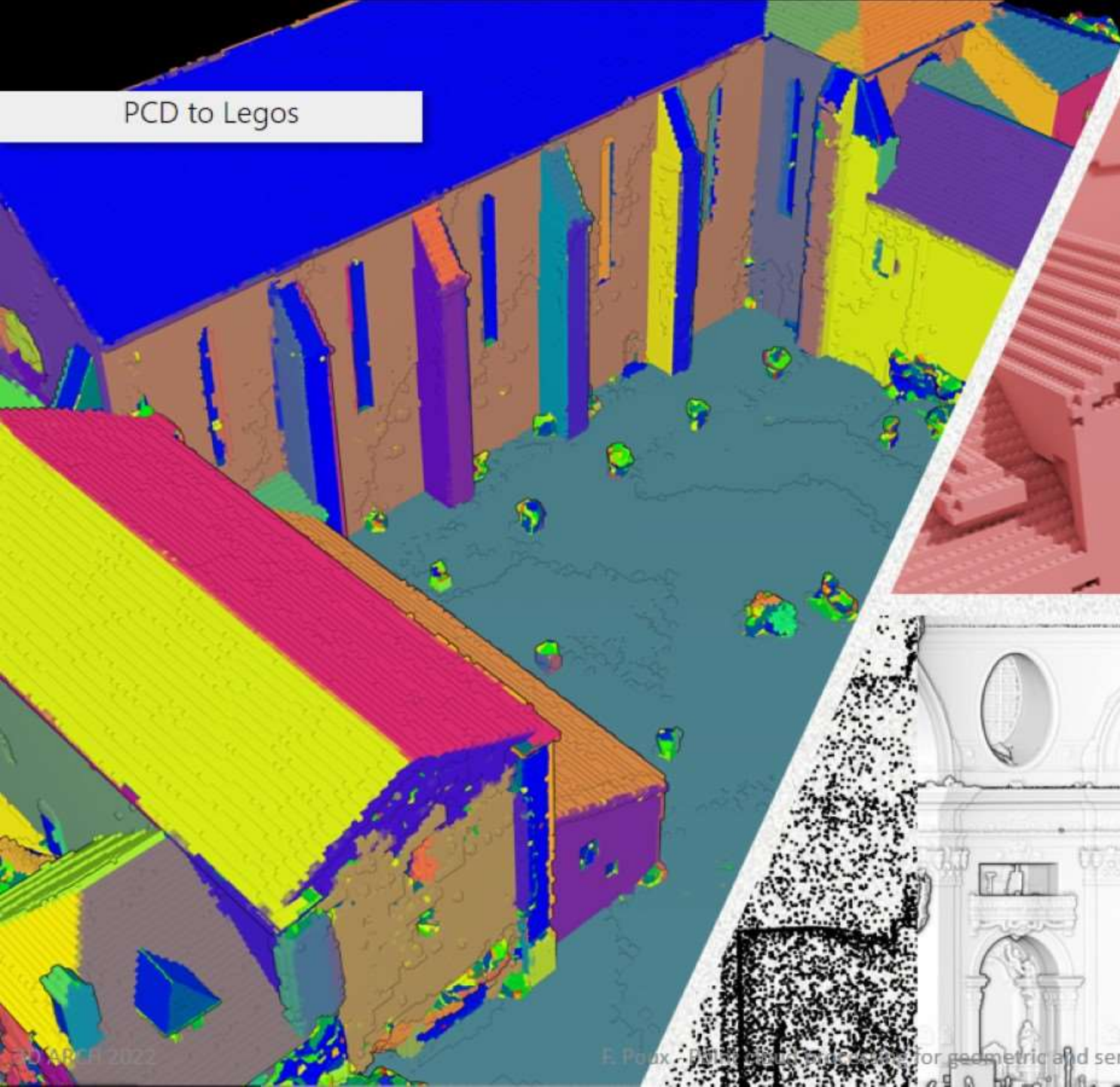


[The Stanford Natural Language Processing Group](#)

# Interaction & Meta



PCD to Legos





E-Learning Center

## Teaching & Sharing Ideas

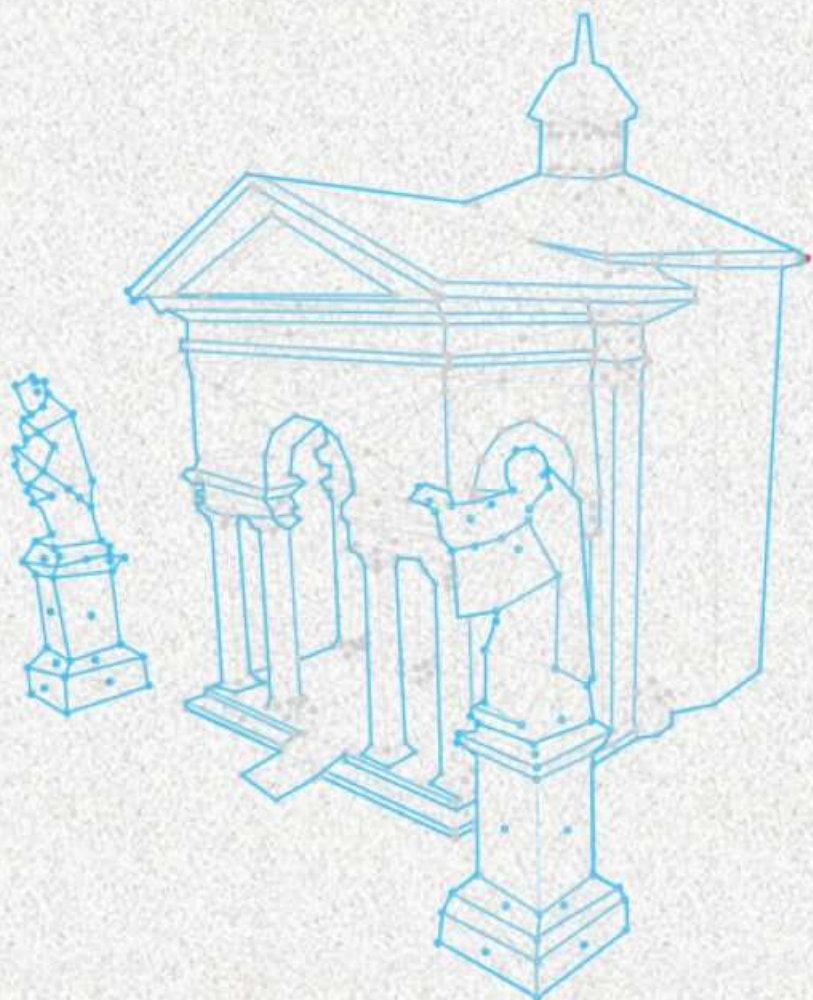


Research Articles

## Innovations, R&T and 3D Projects



Thank you !



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1. Poux, F.; Ponciano, J. J. Self-Learning Ontology For Instance Segmentation Of 3d Indoor Point Cloud. In International Archives of Photogrammetry, Remote Sensing and Spatial Information Sciences; ISPRS, Ed.; Copernicus Publications: Nice, 2020; Vol. XLIII, pp. 309–316.
2. Bassier, M.; Vergauwen, M.; Poux, F. Point Cloud vs. Mesh Features for Building Interior Classification. *Remote Sens.* 2020, 12, 2224, doi:10.3390/rs12142224.
3. Poux, F.; Billen, R.; Kasprzyk, J.-P.; Lefebvre, P.-H.; Hallot, P. A Built Heritage Information System Based on Point Cloud Data: HIS-PC. *ISPRS Int. J. Geo-Information* 2020, 9, 588, doi:10.3390/ijgi9100588.
4. Poux, F.; Valembois, Q.; Mattes, C.; Kobbelt, L.; Billen, R. Initial User-Centered Design of a Virtual Reality Heritage System: Applications for Digital Tourism. *Remote Sens.* 2020, 12, 2583, doi:10.3390/rs12162583.
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7. Poux, F.; Neuville, R.; Van Wersch, L.; Nys, G.-A.; Billen, R. 3D Point Clouds in Archaeology: Advances in Acquisition, Processing and Knowledge Integration Applied to Quasi-Planar Objects. *Geosciences* **2017**, 7, 96.
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12. Poux, F. Vers de nouvelles perspectives lasergrammétriques : optimisation et automatisation de la chaîne de production de modèles 3D Florent Poux To cite this version : HAL Id : dumas-00941990. **2014**.
13. Novel, C.; Keriven, R.; Poux, F.; Graindorge, P. Comparing Aerial Photogrammetry and 3D Laser Scanning Methods for Creating 3D Models of Complex Objects. In Proceedings of the Capturing Reality Forum; Bentley Systems: Salzburg, 2015; p. 15.
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15. Poux, F.; Neuville, R.; Billen, R. POINT CLOUD CLASSIFICATION OF TESSERAЕ FROM TERRESTRIAL LASER DATA COMBINED WITH DENSE IMAGE MATCHING FOR ARCHAEOLOGICAL INFORMATION EXTRACTION. *ISPRS Ann. Photogramm. Remote Sens. Spat. Inf. Sci.* **2017**, *IV-2/W2*, 203–211.